



ESM-4950 96 x 48 1/8 DIN Universal Input PID Process Controller with Smart I/O Module System

- 4 digits process (PV) and 4 digits process set (SV) display
- Universal process input (TC, RTD, mV $\frac{mV}{V}$, V $\frac{V}{V}$, mA $\frac{mA}{mA}$)
- Optional secondary sensor input
- Dual or multi point calibration for $\frac{mV}{V}$ Voltage / Current input
- Configurable ON/OFF, P, PI, PD and PID control forms
- Adaptation of PID coefficients to the system with Auto-tune and Self-tune
- Manual/Automatic mode selection for control outputs
- Bumpless transfer
- Smart I/O module system
- Programmable heating, cooling and alarm functions for control outputs
- Motorized valve control function
- 8 steps profile control (Ramp & Soak) function and start-hold-stop by using logic input module
- Remote set point function by using analogue input modules
- Retransmission of process value or process control by using 0/4...20 mA $\frac{mA}{mA}$ Current Output Module
- Detection of heater failure by using 0...5 A \sim CT input module
- Hardware configuration by using input/output modules
- RS-232 (standard) or RS-485 (optional) serial communication with Modbus RTU protocol

ABOUT INSTRUCTION MANUAL

Instruction manual of ESM-4950 process controller consists of two main sections. Explanation of these sections are below. Also, there are other sections which include order information and technical specifications of the device. All titles and page numbers in instruction manual are in “**CONTENTS**” section. User can reach to any title with section number.

Installation:

In this section, physical dimensions of the device, panel mounting, electrical wiring, module mounting to the device, physical and electrical installation of the device to the system are explained.

Operation and Parameters:

In this section, user interface of the device, how to access to the parameters, description of the parameters are explained.

Also in these sections, there are warnings to prevent serious injury while doing the physical and electrical mounting or using the device.

Explanation of the symbols which are used in these sections are given below.



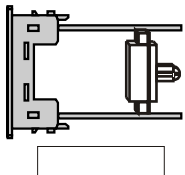
This symbol is used for safety warnings. User must pay attention to these warnings.



This symbol is used to determine the dangerous situations as a result of an electric shock. User must pay attention to these warnings definitely.



This symbol is used to determine the important notes about functions and usage of the device.



In parameters section, for making relevant parameters to be active, determined module must be installed to Module-1 or Module-2 socket.

CONTENTS

1.PREFACE.....	Page	6
1.1 GENERAL SPECIFICATIONS		
1.2 ORDERING INFORMATION		
1.3 WARRANTY		
1.4 MAINTENANCE		
2.INSTALLATION.....	Page	9
2.1 GENERAL DESCRIPTION		
2.2 DIMENSIONS		
2.3 PANEL CUT-OUT		
2.4 ENVIRONMENTAL RATINGS		
2.5 PANEL MOUNTING		
2.6 INSTALLATION FIXING CLAMP		
2.7 REMOVING FROM THE PANEL		
3.ELECTRICAL WIRINGS.....	Page	14
3.1 TERMINAL LAYOUT AND CONNECTION INSTRUCTIONS		
3.2 ELECTRICAL WIRING DIAGRAM		
3.3 SUPPLY VOLTAGE INPUT CONNECTION OF THE DEVICE		
3.4 PROCESS INPUT CONNECTION		
3.4.1 TC (THERMOCOUPLE) CONNECTION		
3.4.2 RTD CONNECTION		
3.4.3 PROCESS INPUT CONNECTION OF SERIAL TRANSMITTERS WITH CURRENT OUTPUT (LOOP POWERED)		
3.4.4 PROCESS INPUT CONNECTION OF 3-WIRE TRANSMITTERS WITH CURRENT OUTPUT		
3.4.5 CONNECTION OF TRANSMITTERS WITH VOLTAGE OUTPUT TO PROCESS INPUT		
3.5 RELAY OUTPUT CONNECTION		
3.6 GALVANIC ISOLATION TEST VALUES OF ESM-4950 PROCESS CONTROLLER AND INPUT/OUTPUT MODULES		
4.DEFINITIONS AND SPECIFICATIONS OF MODULES.....	Page	21
4.1 INPUT MODULES		
4.1.1 EMI-400 DIGITAL INPUT MODULE		
4.1.2 EMI-410 0/4...20mA==CURRENT INPUT MODULE		
4.1.3 EMI-420 0...5A ~CT INPUT MODULE		
4.1.4 EMI-430 TC OR 0...50mV==INPUT MODULE		
4.1.5 EMI-440 PT-100 INPUT MODULE		
4.1.6 EMI-450 0...10V== INPUT MODULE		
4.2 OUTPUT MODULES		
4.2.1 EMO-400 RELAY OUTPUT MODULE		
4.2.2 EMO-410 SSR DRIVER OUTPUT MODULE		
R OUTPUT MODULE		
4.2.3 EMO-420 DIGITAL (TRANSISTOR) OUTPUT MODULE		
4.2.4 EMO-430 0/4 ...20mA== CURRENT OUTPUT MODULE		
4.3 INSTALLING AND PULLING OUT INPUT/OUTPUT MODULES		
4.4 TO STICK INPUT/OUTPUT MODULES' LABELS TO THE DEVICE		
5.CONNECTION TERMINALS OF INPUT/OUTPUT MODULES AND CONNECTION WIRINGS.....	Page	30
5.1 CONNECTION WIRINGS FOR INPUT MODULES		
5.1.1 CONNECTION OF EMI-400 DIGITAL INPUT MODULE		
5.1.2 CONNECTION OF 3-WIRE TRANSMITTER TO EMI-410 0/4...20mA== CURRENT INPUT MODULE		
5.1.3 CONNECTION OF SERIAL TRANSMITTER (LOOP POWERED) TO EMI-410 0/4...20mA== CURRENT INPUT MODULE		
5.1.4 CURRENT TRANSFORMER CONNECTION TO EMI-420 0...5A~ CT INPUT MODULE		
5.1.5 CONNECTION OF EMI-430 TC OR 0...50mV== INPUT MODULE		
5.1.6 USING EMI-430 TC or 0...50mV==INPUT MODULE AS 0...50mV== INPUT		

5.1.7 CONNECTION OF EMI-440 PT-100 INPUT MODULE	
5.1.8 CONNECTION OF EMI-450 0...10V $\frac{1}{4}$ INPUT MODULE	
5.2 CONNECTION WIRINGS FOR OUTPUT MODULES	
5.2.1 EMO-400 RELAY OUTPUT MODULE CONNECTION	
5.2.2 EMO-410 SSR DRIVER OUTPUT MODULE CONNECTION	
5.2.3 EMO-420 DIGITAL (TRANSISTOR) OUTPUT MODULE CONNECTION	
5.2.4 EMO-430 0/4 ...20mA $\frac{1}{4}$ CURRENT OUTPUT MODULE CONNECTION	
5.2.5 TO GET 0...10V $\frac{1}{4}$ WITH EMO-430 0/4 ...20mA $\frac{1}{4}$ CURRENT OUTPUT MODULE	
6.CONNECTIONS FOR RS-232 / RS-485 SERIAL COMMUNICATION.....	Page 37
6.1 CABLE CONNECTION BETWEEN RS-232 TERMINAL OF THE DEVICE AND PC	
6.2 CONNECTION FOR RS-485 SERIAL COMMUNICATION	
6.3 INSTALLING RS-232 / RS-485 SERIAL COMMUNICATION MODULES TO THE DEVICE	
7.DEFINITION OF FRONT PANEL AND ACCESSING TO THE PARAMETERS.....	Page 40
7.1 DEFINITION OF FRONT PANEL	
7.2 OBSERVATION OF OPTIONAL MODULES AND SOFTWARE REVISION ON THE DISPLAYS	
7.3 ADJUSTMENT OF PROCESS SET VALUE	
7.4 ACCESSING TO THE OPERATOR MENU	
7.5 ACCESSING TO THE TECHNICIAN MENU	
7.6 ADJUSTMENT OF ALARM SET VALUES	
7.7 CHANGING AND SAVING PARAMETER VALUES	
8.PARAMETERS.....	Page 62
8.1 OPERATOR PARAMETERS	
8.1.1 PROCESS AND ALARM SET PARAMETERS	
8.1.2 SELECTION OF PID TUNE AND OPERATION FORM	
8.1.3 FUNCTION SELECTION FOR TOP AND BOTTOM DISPLAY	
8.1.4 CONFIGURATION OF RAMP/SOAK FUNCTION AND STEP SET VALUES	
8.2 TECHNICIAN PARAMETERS	
8.2.1 PROCESS INPUT TYPE AND RELEVANT PARAMETERS WITH PROCESS INPUT	
8.2.2 PID CONFIGURATION PARAMETERS	
8.2.3 MODULE-1 CONFIGURATION PARAMETERS	
8.2.4 MODULE-2 CONFIGURATION PARAMETERS	
8.2.5 OUTPUT-3 CONFIGURATION PARAMETERS	
8.2.6 GENERAL PARAMETERS	
8.2.7 PARAMETERS FOR CONFIGURATION OF SERIAL COMMUNICATION	
8.2.8 OPERATOR AND TECHNICIAN PASSWORDS	
9.FAILURE MESSAGES IN ESM-4950 PROCESS CONTROLLERS.....	Page 119
10.SPECIFICATIONS.....	Page 122

EU DECLARATION OF CONFORMITY

Manufacturer Company Name : Emko Elektronik A.S.

Manufacturer Company Address: DOSAB, Karanfil Sokak, No:6, 16369 Bursa, Turkiye

The manufacturer hereby declares that the product conforms to the following standards and conditions.

Product Name : Process Controller

Model Number : ESM-4950

Type Number : ESM-4950

Product Category : Electrical equipment for measurement, control and laboratory use

Conforms to the following directives :

73 / 23 / EEC The Low Voltage Directive as amended by 93 / 68 / EEC

89 / 336 / EEC The Electromagnetic Compatibility Directive

Has been designed and manufactured according to the following specifications

EN 61000-6-4:2001 EMC Generic Emission Standard for the Industrial Environment

EN 61000-6-2:2001 EMC Generic Immunity Standard for the Industrial Environment

EN 61010-1:2001 Safety Requirements for electrical equipment for measurement, control and laboratory use

1. Preface

ESM series process controllers are designed for measuring and controlling temperature and any process value. They can be used in many applications with their universal process input, multifunction control outputs, selectable alarm functions, serial communication unit and input/output modules.

Some application fields and applications which they are used are below:

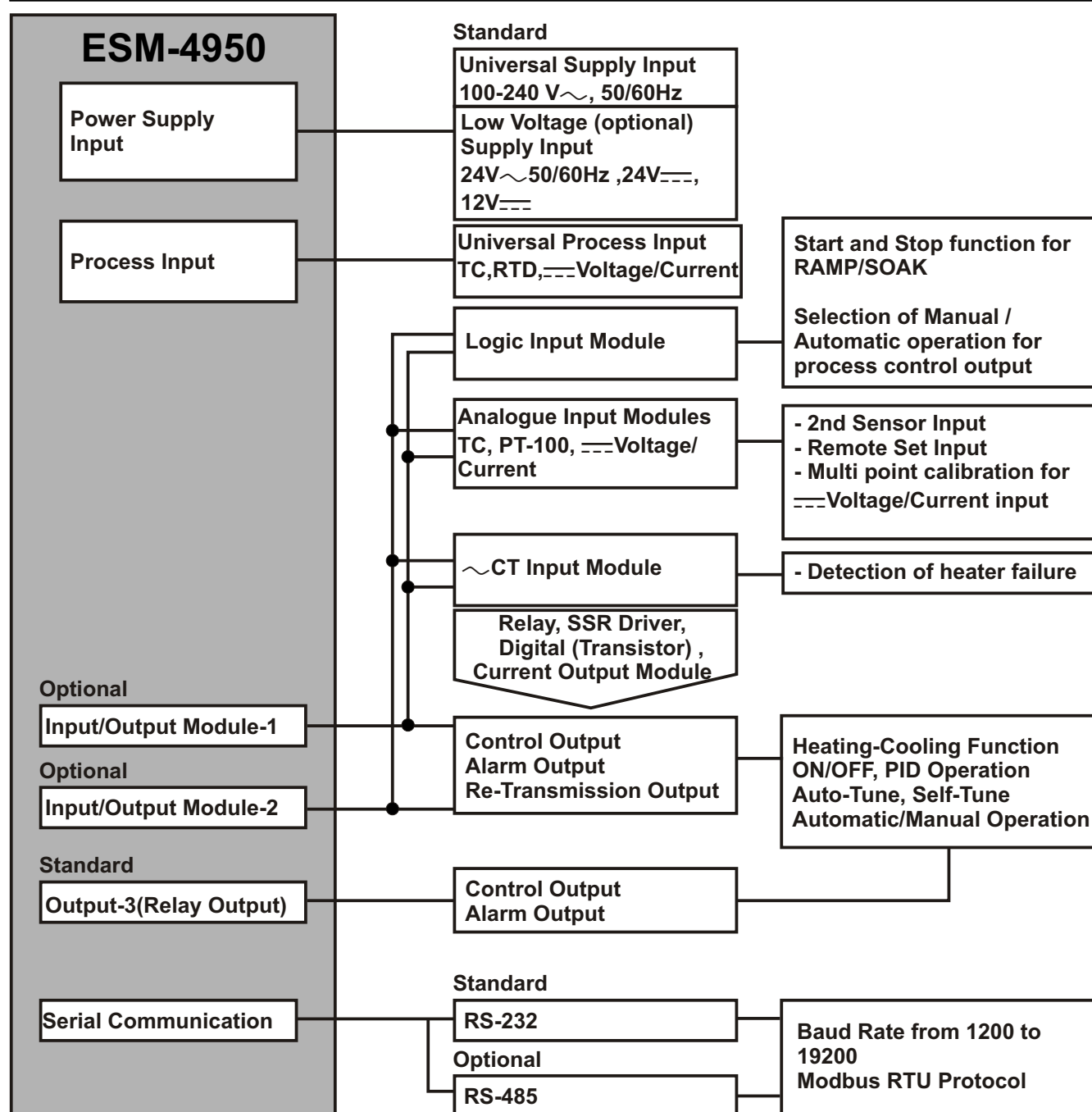
Application Fields

Glass
Plastic
Petro-Chemistry
Textile
Automotive
Machine production industries

Applications

Motorized valve control
Profile Control
PID Process Control
Heater Failure detection

1.1 General Specifications



1.2 Ordering Information

ESM-4950 (96x48 1/8 DIN)	A	BC	D	E	/	FG	HI	/	U	V	W	Z
				1	/			/				

A	Supply Voltage
1	100-240V~ (-15%;+10%) 50/60Hz
2	24 V~ (-15%;+10%) 50/60Hz 24V=== (-15%;+10%)
6	12 V=== (-15%;+10%)
9	Customer (Maximum 240V~ (-15%;+10%))50/60Hz

BC	Input Type	Scale
20	Configurable (Table-1)	Table-1

D	Serial Communication	Product Code
0	None	-
1	RS-232	EMC-400
2	RS-485	EMC-410

E	Output-1
1	Relay Output

FG	Module-1	Product Code
00	None	-
01	Relay Output Module	EMO-400
02	SSR Driver Output Module	EMO-410
03	Digital (Transistor) Output Module	EMO-420
04	Current Output Module (0/4 ...20 mA===)	EMO-430
07	Digital Input Module	EMI-400
08	0/4...20 mA=== Current Input Module	EMI-410
09	0...5A ~CT Input Module	EMI-420
10	TC or 0...50mV=== Input Module	EMI-430
11	PT-100 Input Module	EMI-440
12	0...10 V=== Input Module	EMI-450

HI	Module-2	Product Code
00	None	-
01	Relay Output Module	EMO-400
02	SSR Driver Output Module	EMO-410
03	Digital (Transistor) Output Module	EMO-420
04	Current Output Module (0/4 ...20 mA===)	EMO-430
07	Digital Input Module	EMI-400
08	0/4...20 mA=== Current Input Module	EMI-410
09	0...5A ~CT Input Module	EMI-420
10	TC or 0...50mV=== Input Module	EMI-430
11	PT-100 Input Module	EMI-440
12	0...10 V=== Input Module	EMI-450

Table-1

BC	Input Type(TC)	Scale(°C)	Scale(°F)
21	L ,Fe Const DIN43710	-100°C,850°C	-148°F,1562°F
22	L ,Fe Const DIN43710	-100.0°C,850.0°C	-148.0°F,999.9°F
23	J ,Fe CuNi IEC584.1(ITS90)	-200°C,900°C	-328°F,1652°F
24	J ,Fe CuNi IEC584.1(ITS90)	-199.9°C,900.0°C	-199.9°F,999.9°F
25	K ,NiCr Ni IEC584.1(ITS90)	-200°C,1300°C	-328°F,2372°F
26	K ,NiCr Ni IEC584.1(ITS90)	-199.9°C,999.9°C	-199.9°F,999.9°F
27	R ,Pt13%Rh Pt IEC584.1(ITS90)	0°C,1700°C	32°F,3092°F
28	R ,Pt13%Rh Pt IEC584.1(ITS90)	0.0°C,999.9°C	32.0°F,999.9°F
27	S ,Pt10%Rh Pt IEC584.1(ITS90)	0°C,1700°C	32°F,3092°F
28	S ,Pt10%Rh Pt IEC584.1(ITS90)	0.0°C,999.9°C	32.0°F,999.9°F
29	T ,Cu CuNi IEC584.1(ITS90)	-200°C,400°C	-328°F,752°F
30	T ,Cu CuNi IEC584.1(ITS90)	-199.9°C,400.0°C	-199.9°F,752.0°F
31	B ,Pt30%Rh Pt6%Rh IEC584.1(ITS90)	44°C,1800°C	111°F,3272°F
32	B ,Pt30%Rh Pt6%Rh IEC584.1(ITS90)	44.0°C,999.9°C	111.0°F,999.9°F
33	E ,NiCr CuNi IEC584.1(ITS90)	-150°C,700°C	-238°F,1292°F
34	E ,NiCr CuNi IEC584.1(ITS90)	-150.0°C,700.0°C	-199.9°F,999.9°F
35	N ,Microsil Nisil IEC584.1(ITS90)	-200°C,1300°C	-328°F,2372°F
36	N ,Microsil Nisil IEC584.1(ITS90)	-199.9°C,999.9°C	-199.9°F,999.9°F
37	C , (ITS90)	0°C,2300°C	32°F,3261°F
38	C , (ITS90)	0.0°C,999.9°C	32.0°F,999.9°F

BC	Input Type(RTD)	Scale(°C)	Scale(°F)
39	PT 100 , IEC751(ITS90)	-200°C,650°C	-328°F,1202°F
40	PT 100 , IEC751(ITS90)	-199.9°C,650.0°C	-199.9°F,999.9°F

BC	Input Type (=== Voltage and Current)	Scale
41	0...50 mV===	-1999 9999
42	0...5 V===	-1999 9999
43	0...10 V===	-1999 9999
44	0...20 mA===	-1999 9999
45	4...20 mA===	-1999 9999

All order information of ESM-4950 are given on the table at left. User may form appropriate device configuration from information and codes that at the table and convert it to the ordering codes.

Firstly, supply voltage then input/output modules and other specifications must be determined. Please fill the order code blanks according to your needs.

Please contact us, if your needs are out of the standards.



EMI-400, EMO-410, EMO-420 and EMC-410 modules can not be used in 12V=== type.



~ Symbol means Vac,
 === Symbol means Vdc
 ~ Symbol means Vac and Vdc

1.3 Warranty

EMKO Elektronik warrants that the equipment delivered is free from defects in material and workmanship. This warranty is provided for a period of two years. The warranty period starts from the delivery date. This warranty is in force if duty and responsibilities which are determined in warranty document and instruction manual performs by the customer completely.

1.4 Maintenance

Repairs should only be performed by trained and specialized personnel. Cut power to the device before accessing internal parts.

Do not clean the case with hydrocarbon-based solvents (Petrol, Trichlorethylene etc.). Use of these solvents can reduce the mechanical reliability of the device. Use a cloth dampened in ethyl alcohol or water to clean the external plastic case.

2.Installation



Before beginning installation of this product, please read the instruction manual and warnings below carefully.

In package ,

- One piece unit
- Two pieces mounting clamps
- One piece instruction manual

A visual inspection of this product for possible damage occurred during shipment is recommended before installation. It is your responsibility to ensure that qualified mechanical and electrical technicians install this product.

If there is danger of serious accident resulting from a failure or defect in this unit, power off the system and separate the electrical connection of the device from the system.

The unit is normally supplied without a power switch or a fuse. Use power switch and fuse as required.

Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.

Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

Never attempt to disassemble, modify or repair this unit. Tampering with the unit may results in malfunction, electric shock or fire.

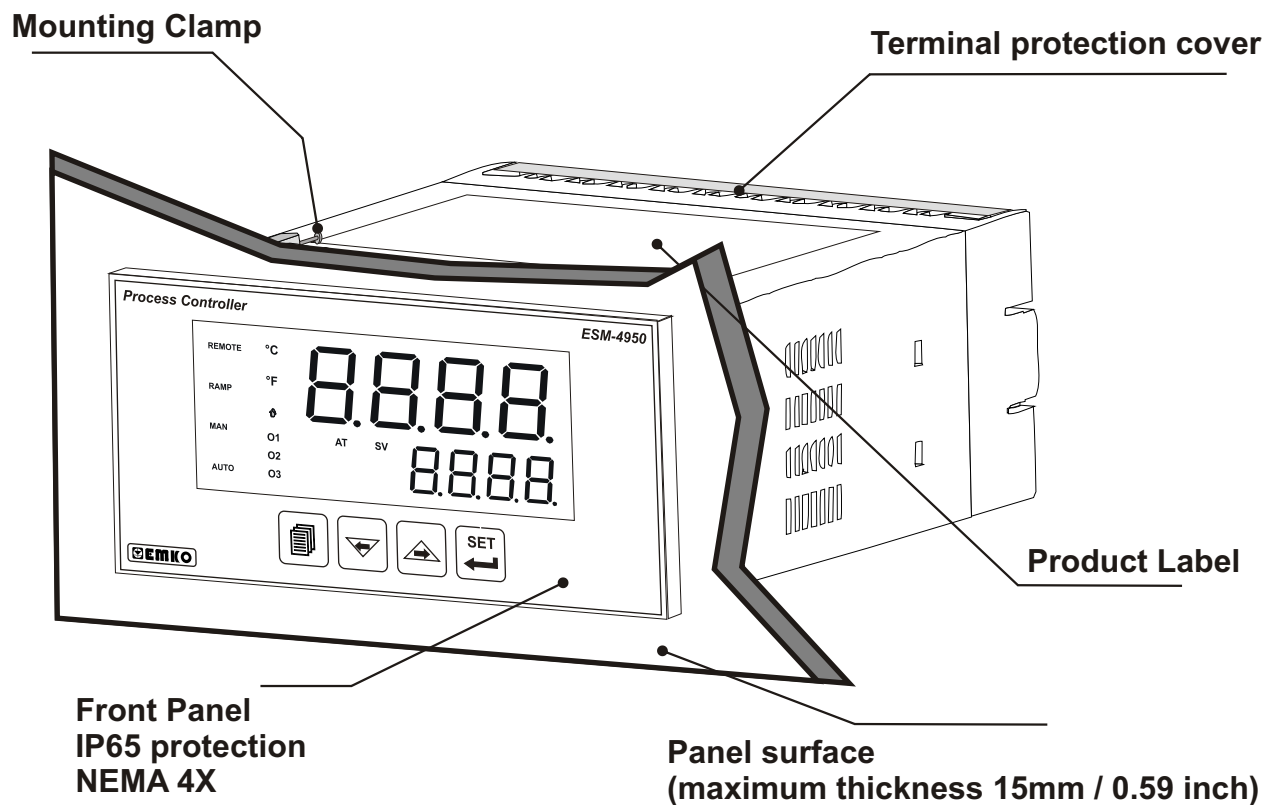
Do not use the unit in combustible or explosive gaseous atmospheres.

During the equipment is putted in hole on the metal panel while mechanical installation some metal burrs can cause injury on hands, you must be careful.

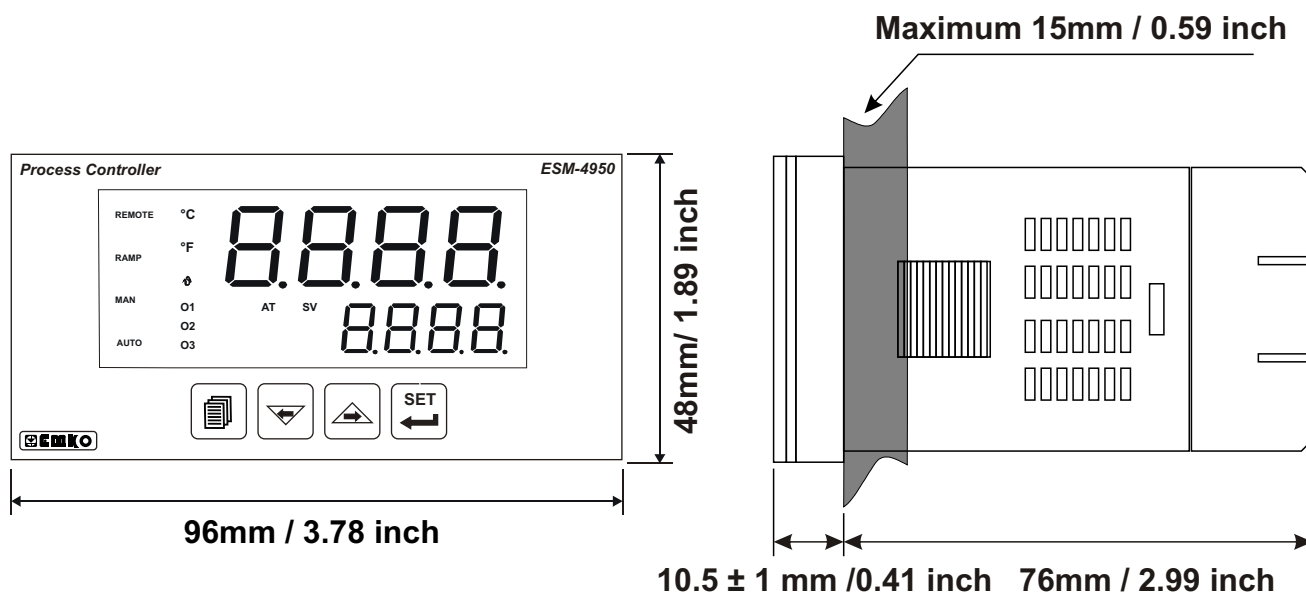
Montage of the product on a system must be done with it's fixing clamps. Do not do the montage of the device with inappropriate fixing clamp. Be sure that device will not fall while doing the montage.

It is your responsibility if this equipment is used in a manner not specified in this instruction manual.

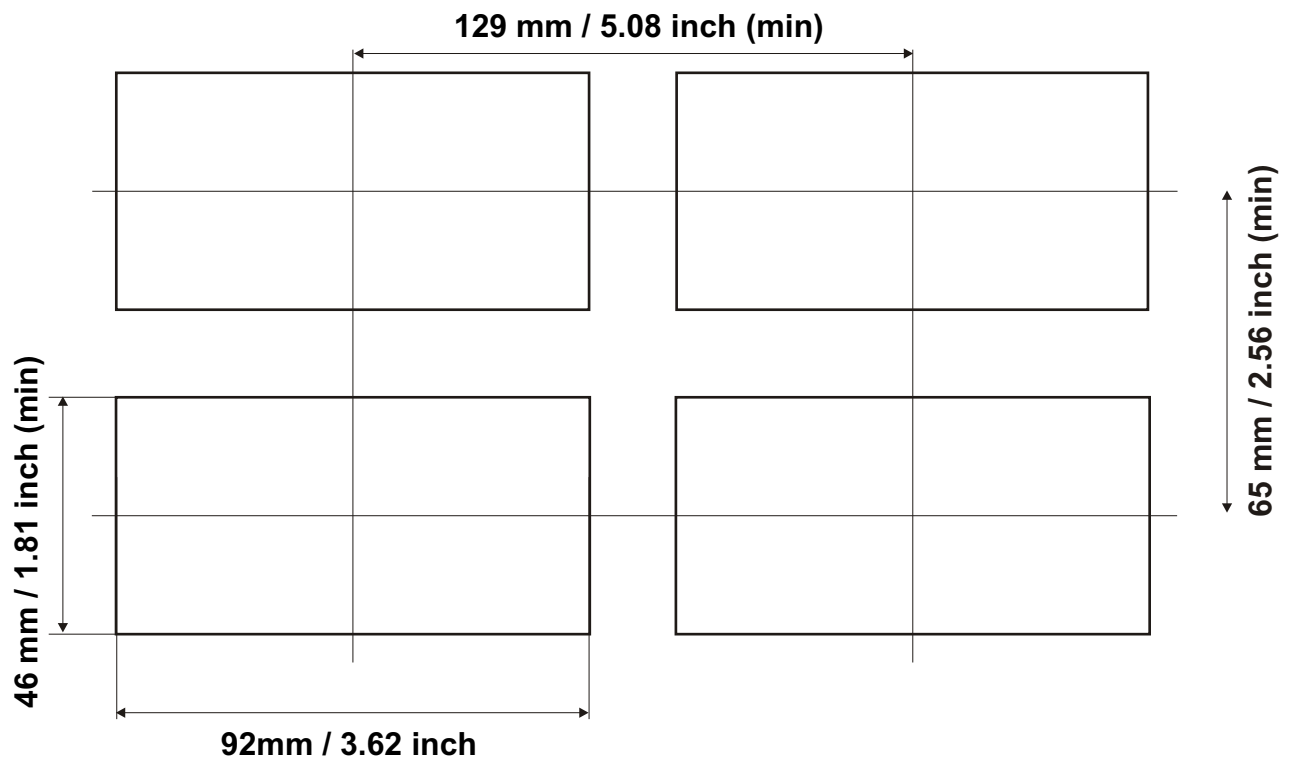
2.1 General Description



2.2 Dimensions



2.3 Panel Cut-Out



2.4 Environmental Ratings

Operating Conditions



Operating Temperature : 0 to 50 °C



Max. Operating Humidity : 90% Rh (non-condensing)



Altitude : Up to 2000m.



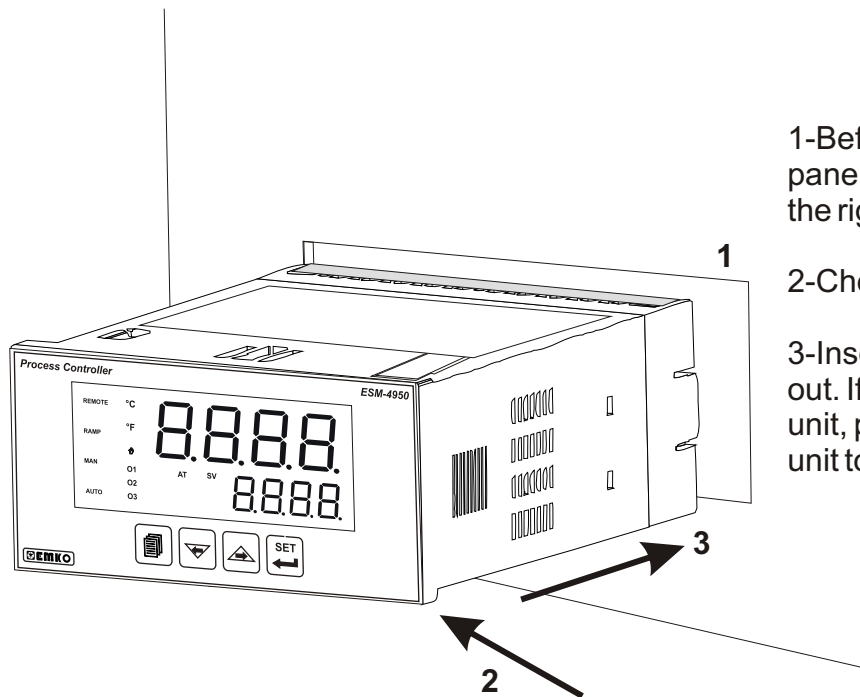
Forbidden Conditions:

Corrosive atmosphere

Explosive atmosphere

Home applications (The unit is only for industrial applications)

2.5 Panel Mounting



1-Before mounting the device in your panel, make sure that the cut-out is of the right size.

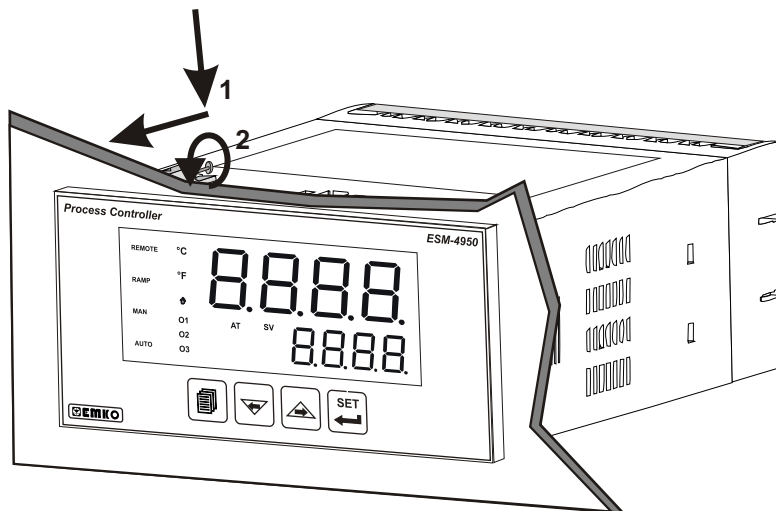
2-Check front panel gasket position

3-Insert the device through the cut-out. If the mounting clamps are on the unit, put out them before inserting the unit to the panel.



During installation into a metal panel, care should be taken to avoid injury from metal burrs which might be present. The equipment can loosen from vibration and become dislodged if installation parts are not properly tightened. These precautions for the safety of the person who does the panel mounting.

2.6 Installation Fixing Clamp



The unit is designed for panel mounting.

1-Insert the unit in the panel cut-out from the front side.

2- Insert the mounting clamps to the holes that located top and bottom sides of device and screw up the fixing screws until the unit completely immobile within the panel

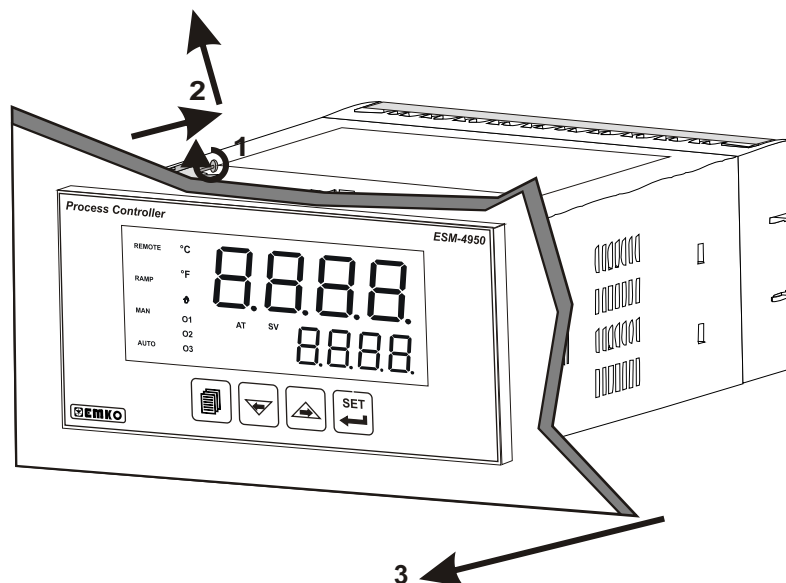


Montage of the unit to a system must be done with it's own fixing clamps. Do not do the montage of the device with inappropriate fixing clamps. Be sure that device will not fall while doing the montage.

2.7 Removing from the Panel



Before starting to remove the unit from panel, power off the unit and the related system.



1-Loosen the screws.

2-Pull mounting clamps from top and bottom fixing sockets.

3-Pull the unit through the front side of the panel

3. Electrical Wirings



You must ensure that the device is correctly configured for your application. Incorrect configuration could result in damage to the process being controlled, and/or personal injury. It is your responsibility, as the installer, to ensure that the configuration is correct.

Device parameters has factory default values. These parameters must be set according to the system's needs.



Only qualified personnel and technicians should work on this equipment. This equipment contains internal circuits with voltage dangerous to human life. There is severe danger for human life in the case of unauthorized intervention.

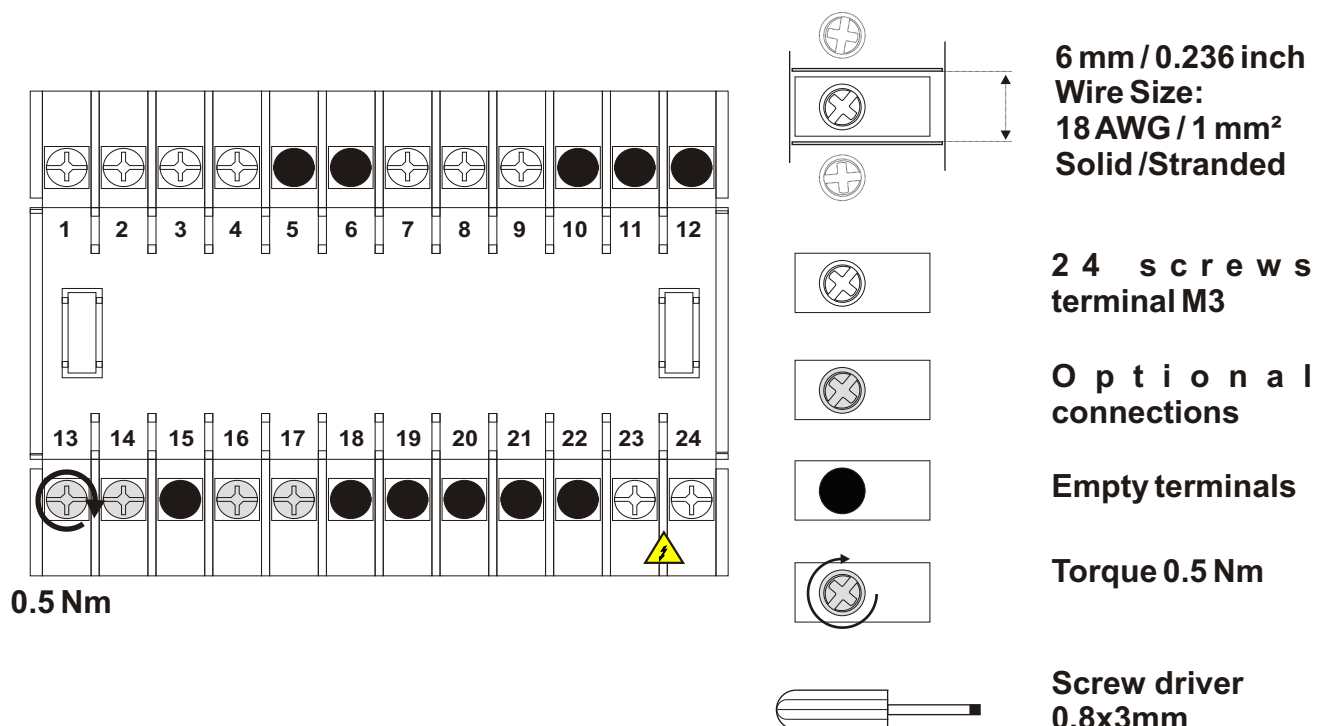


Be sure to use the rated power supply voltage to protect the unit against damage and to prevent failure.



Keep the power off until all of the wiring is completed so that electric shock and trouble with the unit can be prevented.

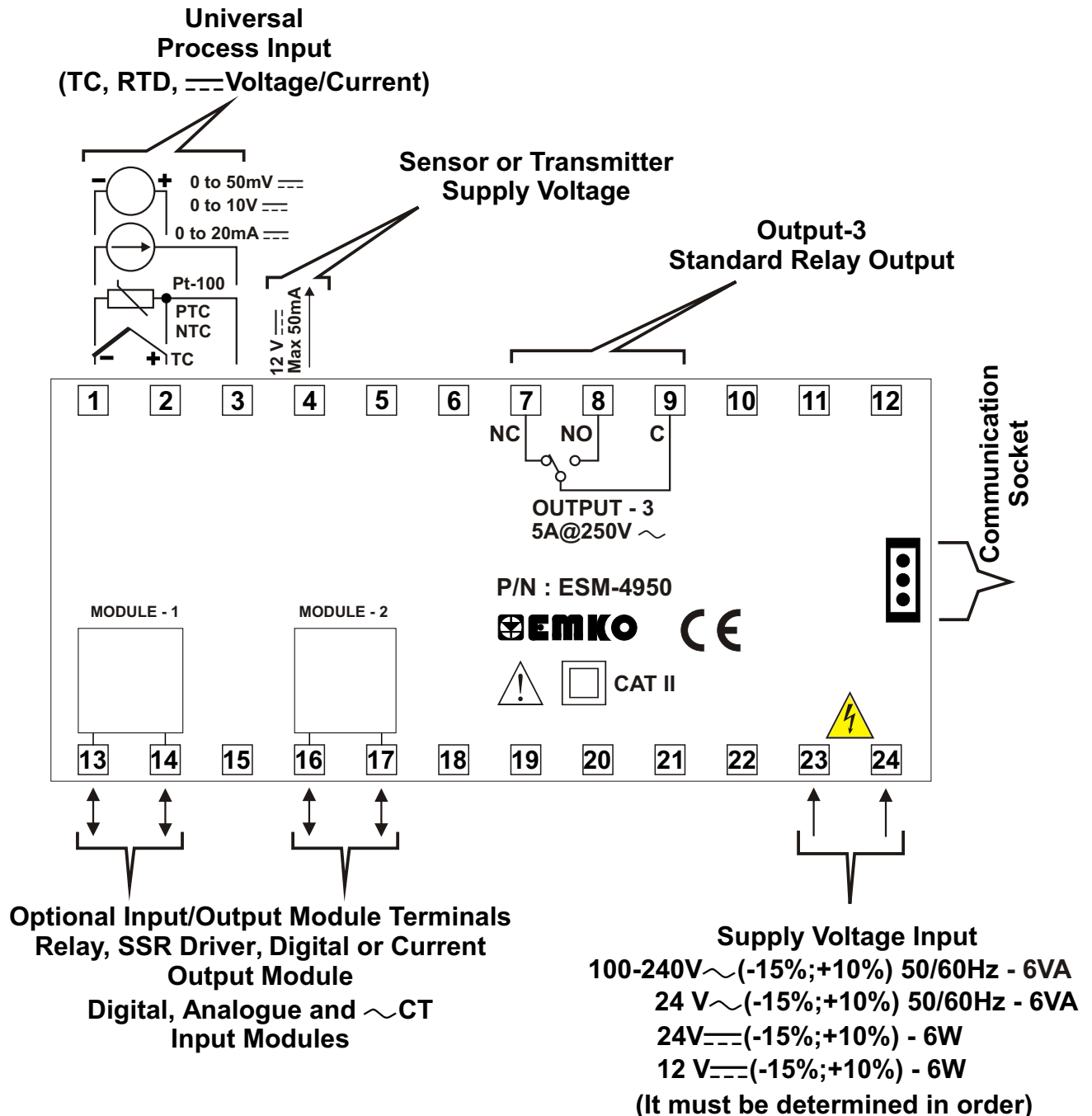
3.1 Terminal Layout and Connection Instructions



3.2 Electrical Wiring Diagram



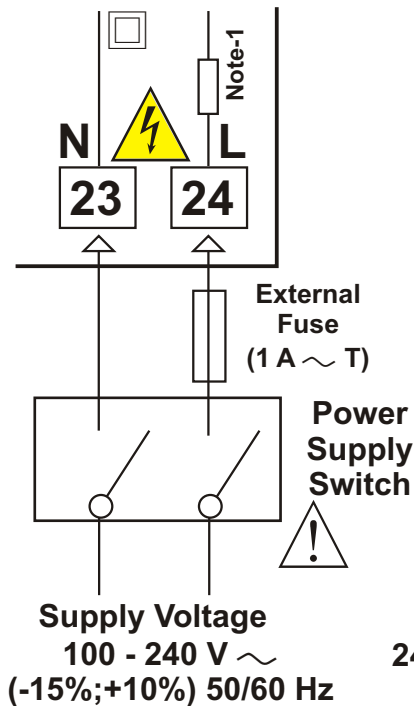
Electrical wiring of the device must be the same as 'Electrical Wiring Diagram' below to prevent damage to the process being controlled and personnel injury.



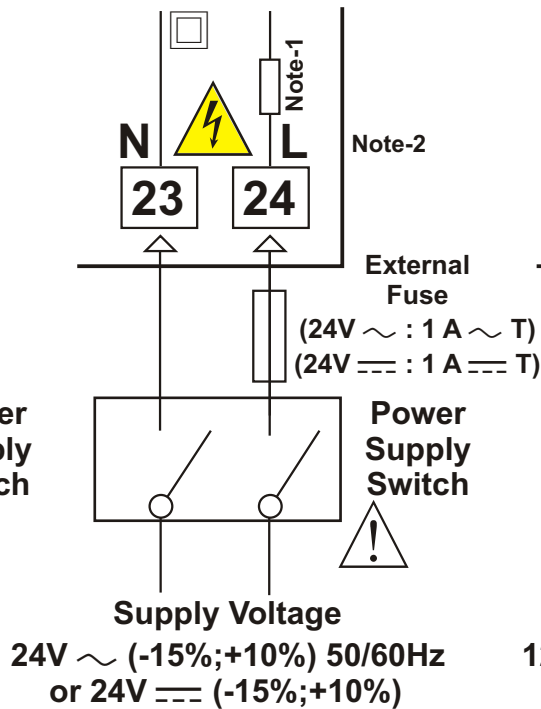
Process input, Analogue Module Inputs (EMI-410, EMI-430, EMI-440, EMI-450) and ~CT Module Input (EMI-420) are in CAT II class.

3.3 Supply Voltage Input Connection of the Device

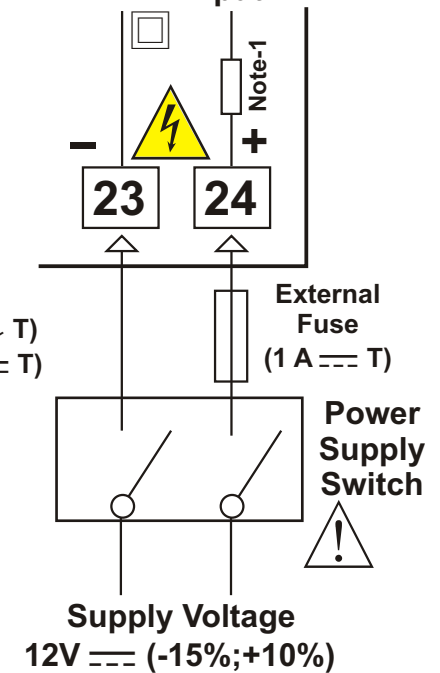
Connection of Universal Supply Voltage Input



Connection of Low Voltage 24 V ~ Supply Voltage Input



Connection of Low Voltage 12V === Supply Voltage Input



Note-1 : There is an internal 33R Ω fusible flameproof resistor in 100-240 V ~ 50/60Hz
There is an internal 4R7 Ω fusible flameproof resistor in 24V ~ 50/60Hz , 24V === and 12V ===

Note-2 : "L" is (+), "N" is (-) for 24V === Supply Voltage



Supply voltage range must be determined in order. While installing the unit, supply voltage range must be controlled and appropriate supply voltage must be applied to the unit. Controlling prevents damages in unit and system and possible accidents as a result of incorrect supply voltage.



There is no power switch or fuse on the device. So a power switch and a fuse must be added to the supply voltage input. Power switch and fuse must be put to a place where user can reach easily.



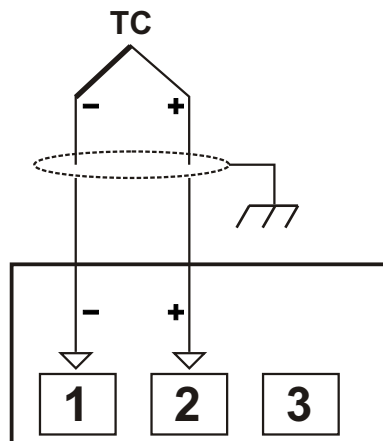
Power switch must be two poled for seperating phase and neutral. On/Off condition of power switch is very important in electrical connection. On/Off condition of power switch must be signed for preventing the wrong connection.





External fuse must be on phase connection in ~ supply input.
External fuse must be on (+) line connection in === supply input.

3.4 Process Input Connection

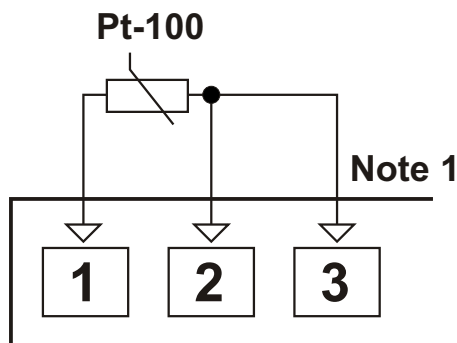
3.4.1 TC (Thermocouple) Connection



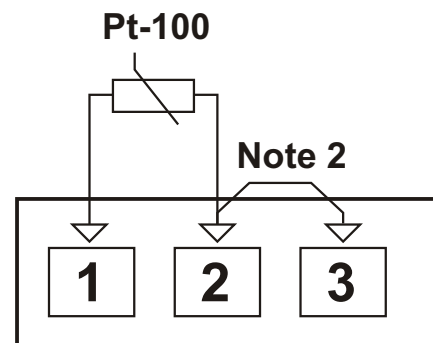
Connect the wires with the polarity as shown in the figure left.

-  Always use compensation wire corresponding to the thermocouple used. If present, the shield must be connected to a proper ground.
-  Input resistance is greater than $10\text{M}\Omega$.

3.4.2 RTD Connection



3-wire Pt-100 connection
(with line compensation)
(Max. Line impedance is 10Ω)




2-wire Pt-100 connection
(without line compensation)

Note 1 : In 3-wire system, use always cables of the same diameter (min 1mm^2) Always use wires of the same gauge and type whether a 2-wire or 3-wire system.

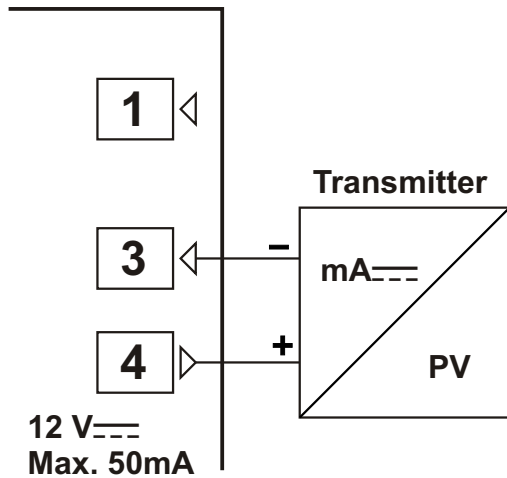
Note 2 : Install a jumper between terminals 2 and 3 when using a 2-wire RTD.

Note 3 : If the distance is longer than 10 meters, use 3-wire system

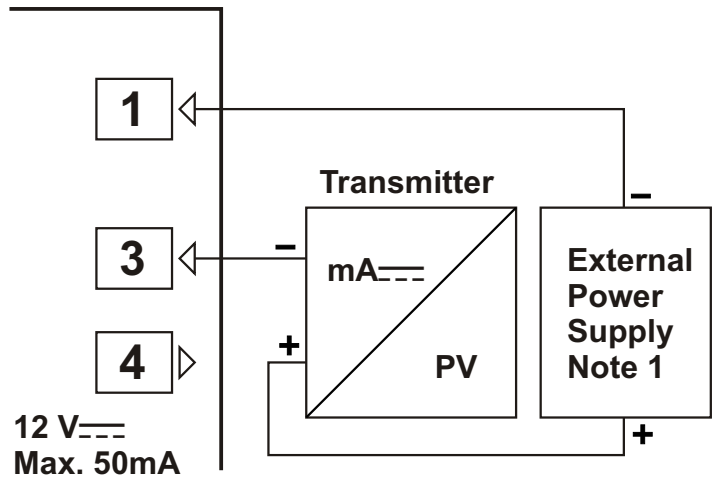
-  Input resistance is greater than $10\text{M}\Omega$.

3.4.3 Process Input Connection of Serial Transmitters with Current Output (Loop Powered)

Transmitter connection by using supply voltage on the device



Transmitter connection by using external supply voltage source.



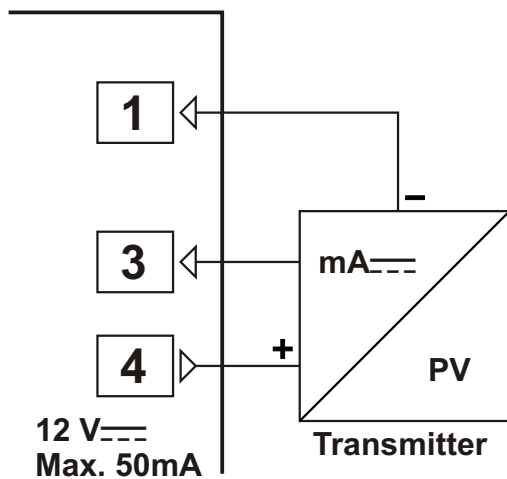
Note 1 : External power supply must be selected according to supply voltage range and required current for transmitter.



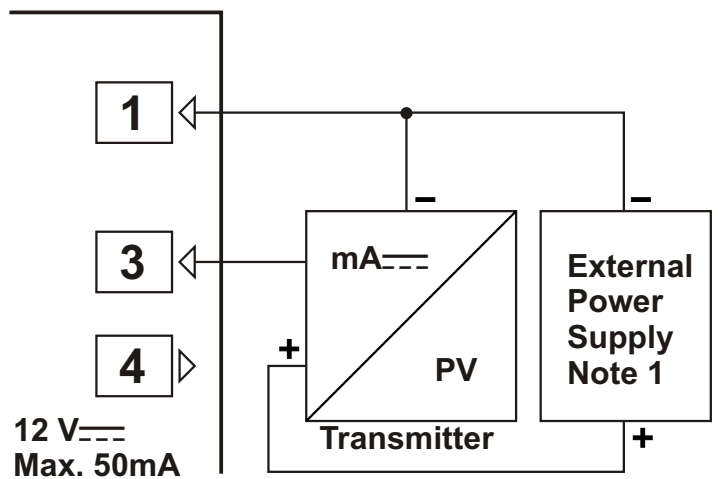
Input Resistance is $2R7 \Omega$.

3.4.4 Process Input Connection of 3-wire Transmitters with Current Output

Transmitter connection by using supply voltage on the device



Transmitter connection by using external supply voltage source.



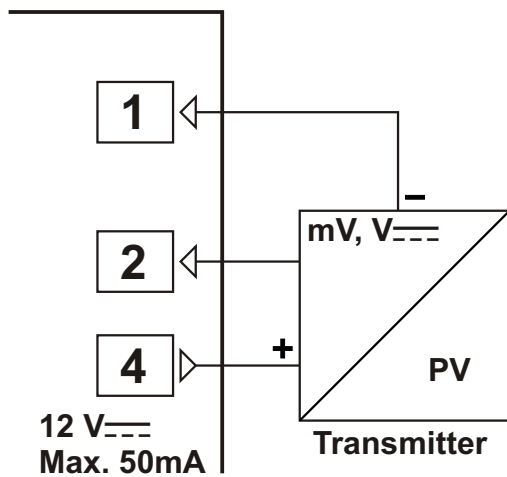
Note 1 : External power supply must be selected according to supply voltage range and required current for transmitter.



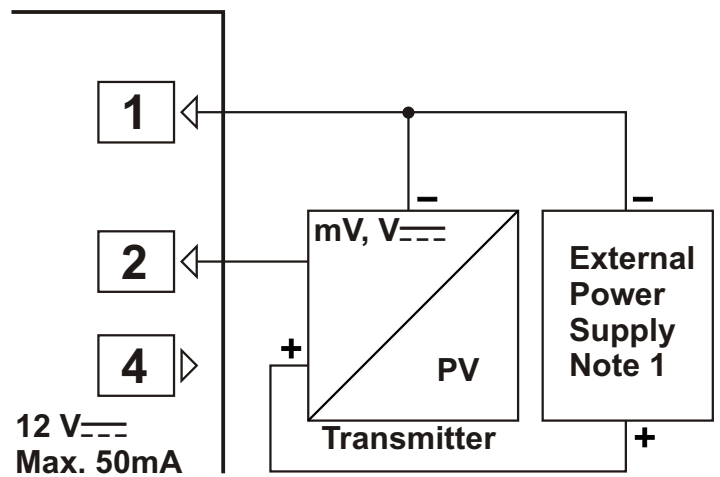
Input Resistance is $2R7 \Omega$.

3.4.5 Connection of Transmitters with Voltage Output to Process Input

Transmitter connection by using supply voltage on the device



Transmitter connection by using external supply voltage source.

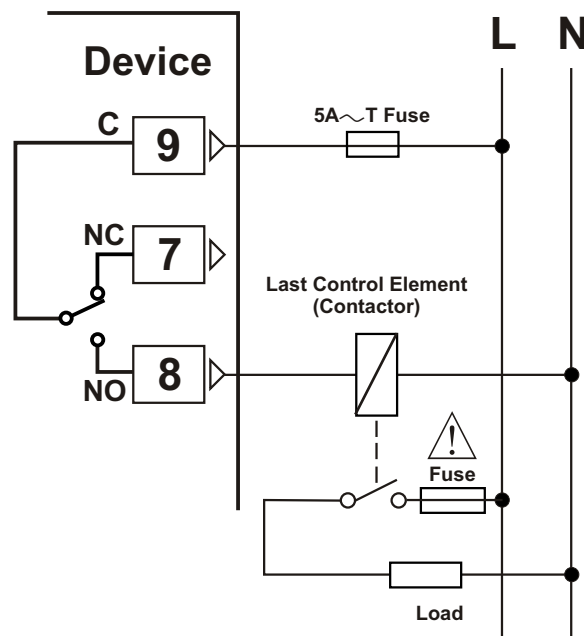


Note 1 : External power supply must be selected according to supply voltage range and required current for transmitter.



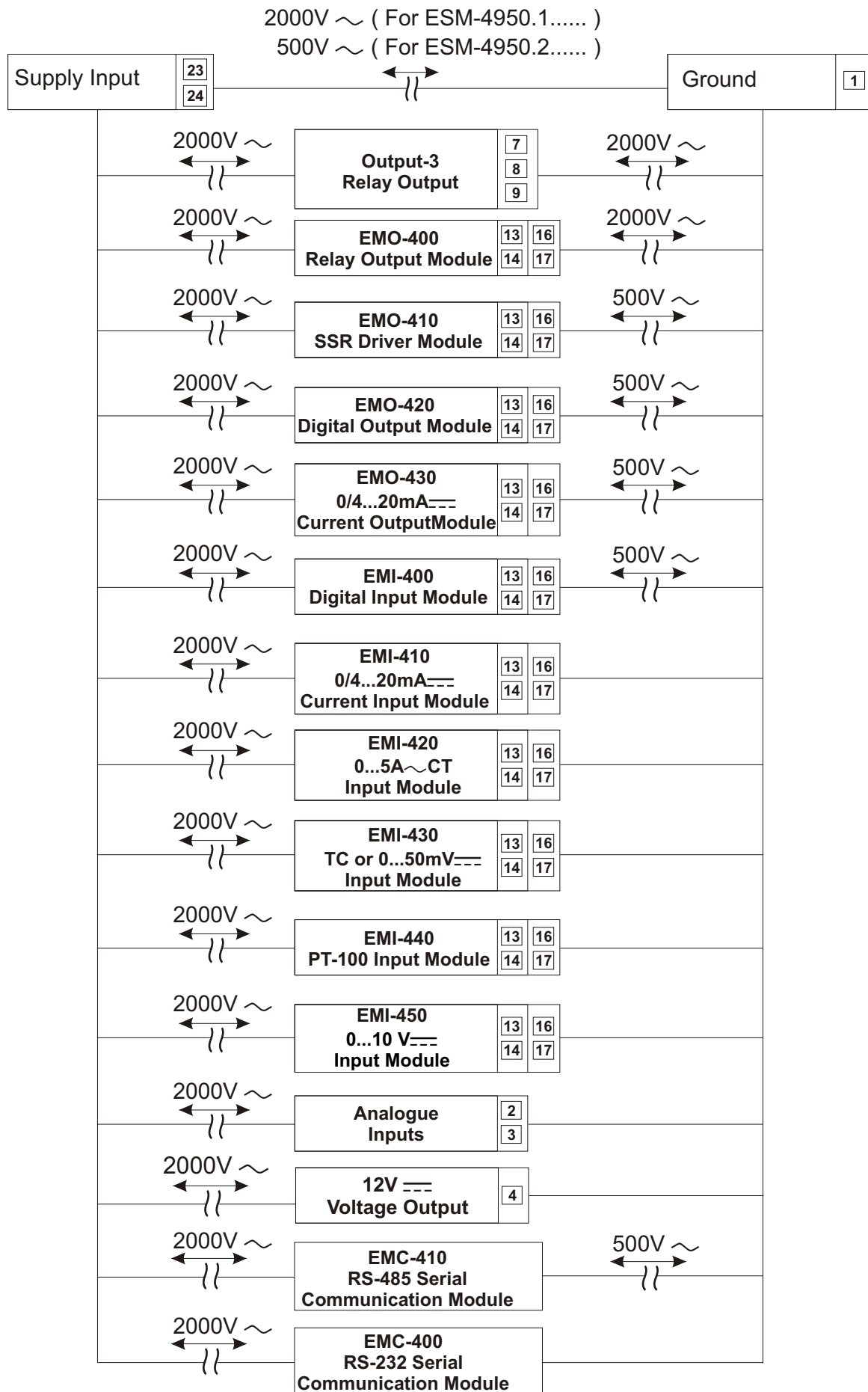
Input resistance is greater than $10\text{M}\Omega$ for $0\ldots 50\text{mVDC}$
Input resistance is $43\text{K}\Omega$ for $0\ldots 10\text{VDC}$

3.5 Relay Output Connection



Fuses must be selected according to the application.

3.6 Galvanic Isolation Test Values of ESM-4950 Process Controller and Input/Output Modules

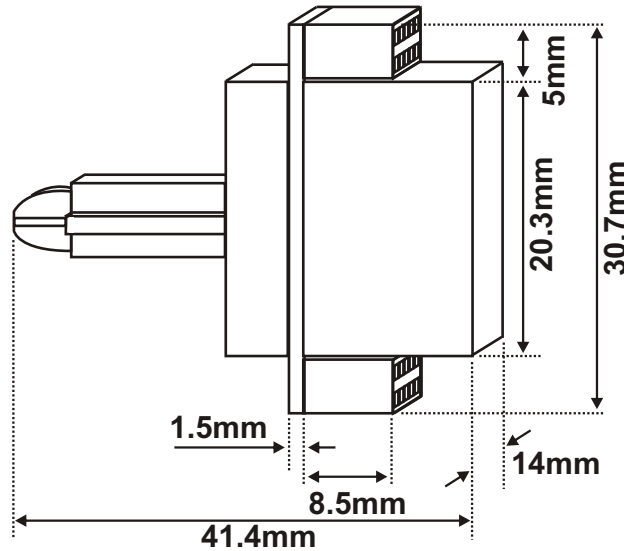


4. Definitions and Specifications of Modules

ESM-4950 process controller is a modular product which is designed to operate with additional analogue and digital input/output units which user may need.

Two input/output modules can be plugged in the device by the user. User may configure the product for different applications according to the system requirements with the input/output modules which are described in this section.

Dimensions of Input/Output Modules



4.1 Input Modules

4.1.1 EMI-400 Digital Input Module

EMI-400 Digital input module can be installed to Module-1 or Module-2 socket for using the digital input functions.

Specifications of EMI-400 Digital Input Module

Input Type : Normally Open Contact, NPN , PNP , Voltage Input (2 Volt and below 2 Volt is Logic "0", 4 Volt and above 4 Volt is Logic "1". Maximum 30V can be applied)

Dimensions : 14x30.7x41.4mm

Input Resistance : 2K2 Ω .

Applications of EMI-400 Digital Input Module

It is used to run, stop and pause ramp-soak functions in RAMP/SOAK applications.

It can be used to operate the process control output as AUTOMATIC/MANUAL, start the PID tune operation and latch canceling.



Detailed information about functions of Digital Input Module functions are given in parameters section. For using these functions EMI-400 Digital Input Module must be installed to Module-1 or Module-2 socket.



This module can not be used in 12V $\overline{\text{---}}$ type.

4.1.2 EMI-410 0/4...20mA $\overline{\text{---}}$ Current Input Module

EMI-410 0/4...20mA $\overline{\text{---}}$ current input module can be plugged in Module-1 or Module-2 socket to use as 2nd sensor input, for measuring process value or for using alarm functions which are related to measured value.

Also, "remote set" function can be used by installing the module. Please refer to Section 8.2.3 or 8.2.4 for detailed information ($\overline{\text{rE51}}$, $\overline{\text{rE52}}$ parameters)

 **EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.**


Specifications of EMI-410 0/4...20mA $\overline{\text{---}}$ Current Input Module

Input Type : 0/4...20 mA $\overline{\text{---}}$ Current Input
Accuracy : 0.3%
Dimensions : 14x30.7x41.4mm
Input Resistance : 2R7 Ω .

Applications of EMI-410 0/4...20mA $\overline{\text{---}}$ Current Input Module

It can be used to measure any process value and use it with an alarm function in applications that 2nd sensor input is necessary.

The current value (0/4...20mA $\overline{\text{---}}$) on the module input can be used as process set value when "remote set" function is activated and system can be controlled with analogue signal (0/4...20 mA $\overline{\text{---}}$) which is applied from remote point.

 **Detailed information about functions of EMI-410 0/4...20mA $\overline{\text{---}}$ Current Input Module functions are given in parameters section. For using these functions EMI-410 0/4...20mA $\overline{\text{---}}$ Current Input Module must be installed to Module-1 or Module-2 socket.**

 **For using EMI-410 0/4...20mA $\overline{\text{---}}$ current input module as 0...20mA $\overline{\text{---}}$, $\overline{\text{uR51}}$ Or $\overline{\text{uR52}}$ must be $\overline{\text{0000}}$**

4.1.3 EMI-420 0...5A \sim CT Input Module

EMI-420 0...5A \sim CT Input Module can be plugged in Module-1 or Module-2 socket for detecting heater failures in any applications.


 **Two EMI-420 \sim CT input modules can not be plugged in Module-1 and Module-2 socket at the same time.**

Specifications of EMI-420 0...5A \sim CT Input Module

Input Type : 0...5A \sim
Accuracy : 2% FS
Dimensions : 14x30.7x41.4mm
Input Resistance : 23m Ω .

Applications of EMI-420 0...5A \sim CT Input Module

It can be used for observing heater current with current transformer and detecting heating failure.

 **Detailed information about functions of EMI-420 0...5A \sim CT Input Module functions are given in parameters section. For using these functions EMI-420 0...5A \sim CT Input Module must be installed to Module-1 or Module-2 socket.**

4.1.4 EMI-430 TC (Thermocouple) or 0...50mV $\frac{mV}{^{\circ}C}$ Input Module

EMI-430 TC or 0...50mV $\frac{mV}{^{\circ}C}$ input module can be plugged in Module-1 or Module-2 socket to use as 2nd sensor input, for measuring process value or for using alarm functions which are related to measured value.

Also "remote set" function can be used by plugging this module. Please refer to Section 8.2.3 or 8.2.4 for detailed information. ($rE51$, $rE52$ parameters)



EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

Specifications of EMI-430 TC or 0...50mV $\frac{mV}{^{\circ}C}$ Input Module

Please refer to Section 8.2.3 or 8.2.4 for selection of input type and scale of TC input type (L, J, K, R, S, T, B, E, N,C)

Accuracy : 0.3%

Dimensions : 14x30.7x41.4mm

Input Resistance : Greater than 10M Ω

Applications of EMI-430 0...50mV $\frac{mV}{^{\circ}C}$ Input Module

It can be used to measure any process value and use it with an alarm function in applications that 2nd sensor input is necessary.

The voltage value (0...50mV $\frac{mV}{^{\circ}C}$) on the module input can be used as process set value when "remote set" function is activated and system can be controlled with analogue signal (0...50mV $\frac{mV}{^{\circ}C}$) which is applied from remote point.



Detailed information about functions of EMI-430 TC or 0...50mV $\frac{mV}{^{\circ}C}$ Input Module are given in parameters section. For using these functions EMI-430 TC or 0...50mV $\frac{mV}{^{\circ}C}$ Input Module must be installed to Module-1 or Module-2 socket.



For using EMI-430 TC or 0...50mV $\frac{mV}{^{\circ}C}$ input module as 0...50mV $\frac{mV}{^{\circ}C}$, $rS1$ or $rS2$ must be 0000

4.1.5 EMI-440 Pt-100 Input Module

EMI-440 Pt-100 input module can be plugged in Module-1 or Module-2 socket to use as 2nd sensor input, for measuring process value or for using alarm functions which are related to measured value.

Also "remote set" function can be used by plugging this module. Please refer to Section 8.2.3 or 8.2.4 for detailed information. ($rE51$, $rE52$ parameters)



EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

Specifications of EMI-440 Pt-100 Input Module

Please refer to Section 8.2.3 or 8.2.4 for selection of input type and scale

Accuracy : 0.5%

Dimensions : 14x30.7x41.4mm

Input Resistance : Greater than 10M Ω

Applications of EMI-440 Pt-100 Input Module

It can be used to measure any process value and use it with an alarm function in applications that 2nd sensor input is necessary.

The Pt-100 value on the module input can be used as process set value when “remote set” function is activated and system can be controlled with analogue signal which is applied from remote point.



Detailed information about functions of EMI-440 Pt-100 input module are given in PARAMETERS section. For using these functions EMI-440 Pt-100 input module must be installed to Module-1 or Module-2 socket.

4.1.6 EMI-450 0...10V_{DC} Input Module

EMI-450 0...10V_{DC} input module can be plugged in Module-1 or Module-2 socket to use as 2nd sensor input, for measuring process value or for using alarm functions which are related to measured value. (In some sections it is defined as analogue input module)

Also “remote set” function can be used by plugging this module. Please refer to Section 8.2.3 or 8.2.4 for detailed information. (rE51, rE52 parameters)



EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

Specifications of EMI-450 0...10V_{DC} Input Module

Accuracy : 0.3%

Dimensions : 14x30.7x41.4mm

Input Resistance : 43KΩ.

Applications of EMI-450 0...10V_{DC} Input Module

It can be used to measure any process value and use it with an alarm function in applications that 2nd sensor input is necessary.

(0...10V_{DC}) value on module input can be used as process set value when “remote set” function is activated and system can be controlled with analogue signal(0...10V_{DC}) which is applied from remote point.



Detailed information about functions of EMI-450 0...10mV_{DC} Input Module are given in parameters section. For using these functions EMI-450 0...10mV_{DC} Input Module must be installed to Module-1 or Module-2 socket.



For using EMI-450 0...10V_{DC} input module as 0...10V_{DC}, rAS1 or rAS2 must be 0000

4.2 Output Modules

4.2.1 EMO-400 Relay Output Module

EMO-400 Relay output module can be plugged in Module-1 or Module-2 socket to use functions which are defined for relay output.

Specifications of EMO-400 Relay Output Module

Output : 3A @ 250V~, Single Open Contact
Dimensions : 14x30.7x41.4mm
Electrical Life : 100.000 Operation (Full Load)

Applications of EMO-400 Relay Output Module

It can be used with heating or cooling functions as process control output, as alarm output by programmable different alarm functions, as logic output to transfer some datas on the device to the system. These alternatives are explained in parameters section as logic output function.



Detailed information about functions of EMO-400 Relay Output Module are given in parameters section. For using these functions EMO-400 Relay Output Module must be installed to Module-1 or Module-2 socket.

4.2.2 EMO-410 SSR Driver Output Module

EMO-410 SSR Driver Output Module can be plugged in Module-1 or Module-2 socket to use functions which are defined for SSR driver output.

Specifications of EMO-410 SSR Driver Module

Output : Maximum 20 mA, 15-18V \pm 10%, isolated
Dimensions : 14x30.7x41.4mm

Applications of EMO-410 SSR Driver Output Module

It can be used with heating or cooling functions as process control output, as alarm output by programmable different alarm functions, as logic output to transfer some datas on the device to the system.

Note 1 : If short output period is needed in a system, using SSR Driver output module is recommended. (Relay must not be used for short output periods because of limited life of their relay contact (open/close events))



Detailed information about functions of EMO-410 SSR Driver Output Module are given in parameters section. For using these functions EMO-410 Output Module must be installed to Module-1 or Module-2 socket.



This module can not be used in 12V \pm type.

4.2.3 EMO-420 Digital (Transistor) Output Module

EMO-420 Digital (Transistor) Output Module can be plugged in Module-1 or Module-2 socket to use functions which are defined for digital output.

Specifications of EMO-420 Digital (Transistor) Output Module

Output : Maximum 40 mA, 15-18V \pm 10%, isolated

Dimensions : 14x30.7x41.4mm

Applications of EMO-420 Digital (Transistor) Output Module

It can be used with heating or cooling functions as process control output, as alarm output by programmable different alarm functions, as logic output to transfer some datas on the device to the system. These alternatives are explained in parameters section as logic output function.



Detailed information about functions of EMO-420 Digital (Transistor) Output Module are given in parameters section. For using these functions EMO-420 Digital (Transistor) Output Module must be installed to Module-1 or Module-2 socket.



This module can not be used in 12V type.

4.2.4 EMO-430 0 / 4 ...20mA \pm Current Output Module

EMO-430 0/4...20mA \pm Current Output Module can be plugged in Module-1 or Module-2 socket to use functions which are defined for current output.

Specifications of EMO-430 0/4...20mA \pm Current Output Module

Output : 0/4...20mA \pm current output

Accuracy : 1%

Note : To get 0...10V \pm , 500 Ω resistor with 0.05% tolerance must be connected in parallel as a shunt resistor to module output (Please refer to Section 5.2.5 for detailed information)

Maximum load impedance : 600 Ω

Dimensions : 14x30.7x41.4mm

Applications of EMO-430 0/4...20mA \pm Current Output Module

It can be used in heating or cooling functions as process control output.

Process value, error between process and set value or set value can be retransmitted to the system as 0...20mA \pm or 4...20mA \pm output. Retransmission is explained in parameters section.

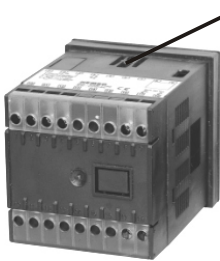


Detailed information about functions of EMO-430 Current Output Module are given in parameters section. For using these functions EMO-430 0/4...20mA \pm current Output Module must be installed to Module-1 or Module-2 socket.

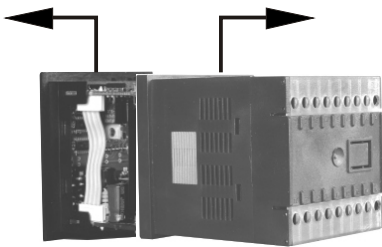
4.3 Installing and Pulling Out Input/Output Modules



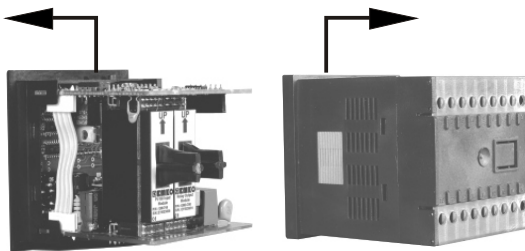
First, detach all cable connections from the device and uninstall it from the panel.



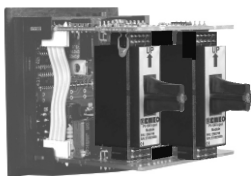
Suppress to the lock pins where top and bottom of the device



Pull the cover case with your other hand from front panel to rear side.

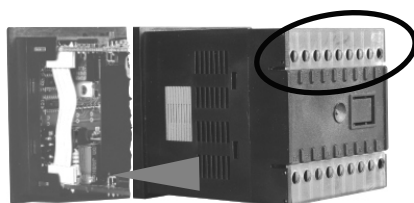


Pull out the cover case from the device



Slide input/output modules into socket.

Pull out the module from it's socket, instead of this module install the new one or other module user wants to use.



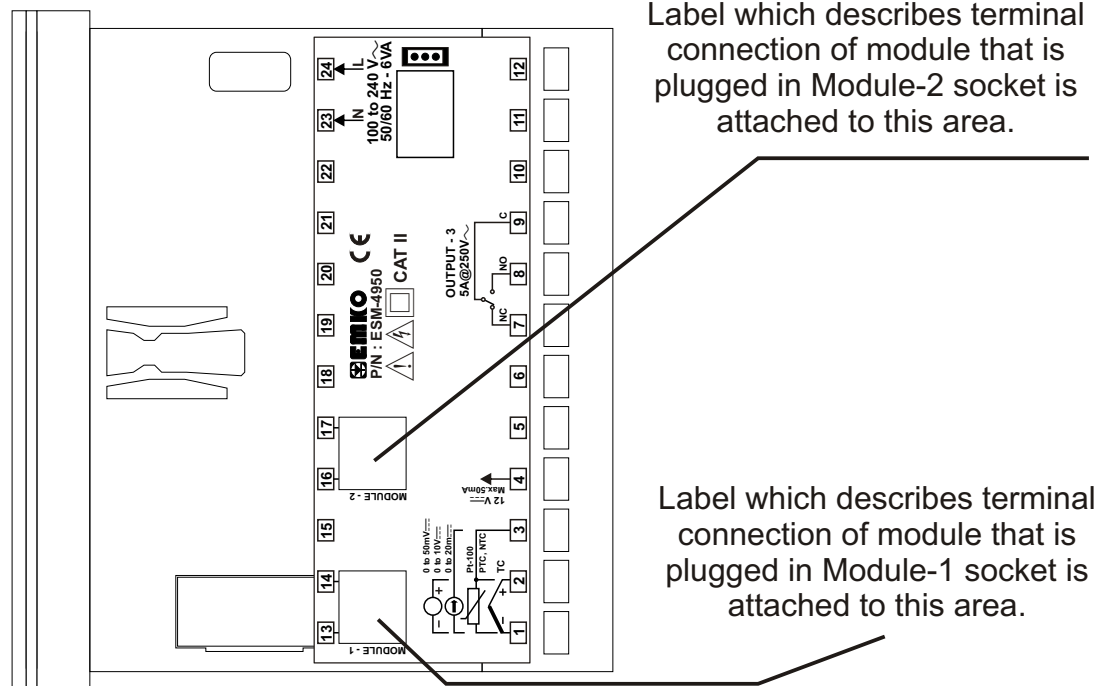
Replace the cover case by taking care of the terminal numbers should be at right position.



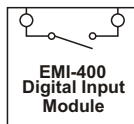
After adding or changing modules to the unit, these changes must be taken into consideration while mounting of the unit to the system. If mounting is incorrect, it can cause accidents to harm system, operator or person who does the mounting. Responsibility of these kind of harmful events belongs to the user.

4.4 To Stick Input/Output Modules' Labels to the Device

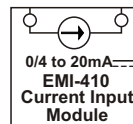
Every module which is plugged in Module-1 or Module-2 socket has labels' for showing the relation between connection terminal and the device. These labels are attached to empty boxes which are separated for Module-1 and Module-2 on the device. Labels for all modules and attachment places are shown below.



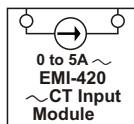
LABELS FOR INPUT MODULES



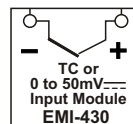
Label for EMI-400 Digital Input Module



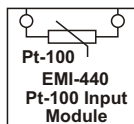
Label for EMI-410 0/4...20mA --- Current Input Module



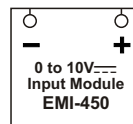
Label for EMI-420 0...5A ~ CT Input Module



Label for EMI-430 TC or 0...50mV --- Input Module

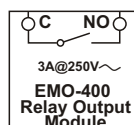


Label for EMI-440 Pt-100 Input Module

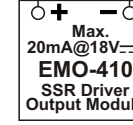


Label for EMI-450 0...10V --- Input Module

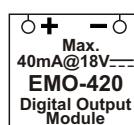
LABELS FOR OUTPUT MODULES



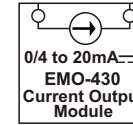
Label for EMO-400 Relay Output Module



Label for EMO-410 SSR Driver Module

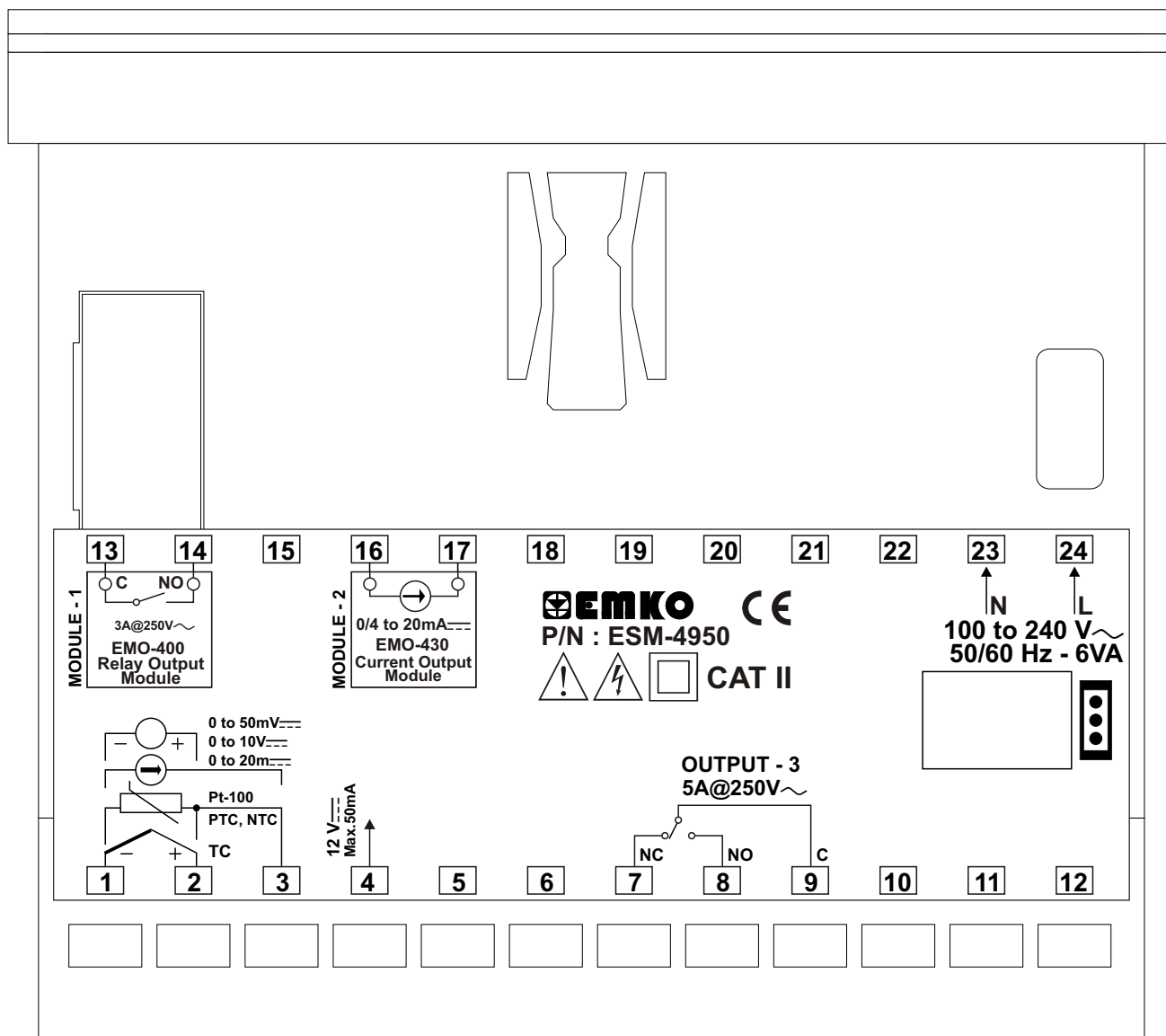


Label for EMO-420 Digital Output Module



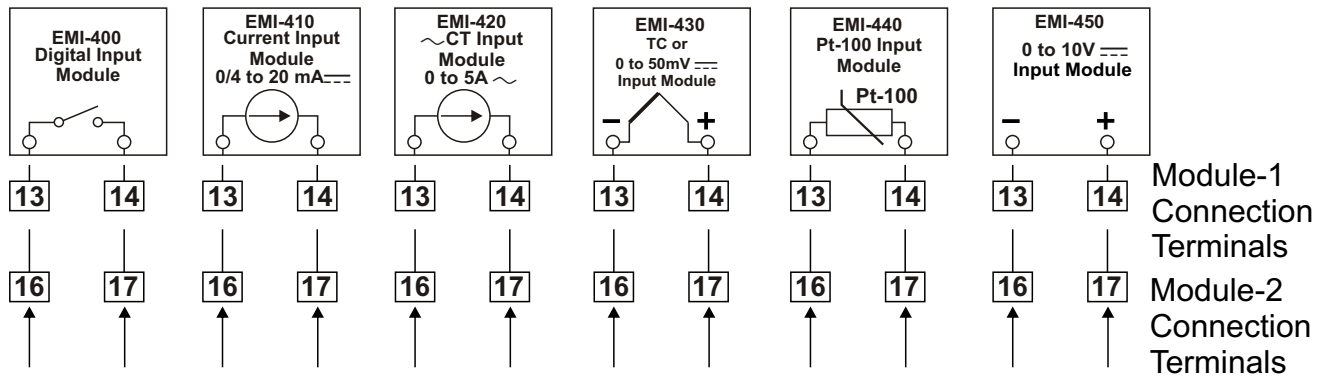
Label for EMO-430 0/4...20mA --- Current Output Module

Example : If user installs EMO-400 Relay Output Module to Module-1 socket, EMO-430 0/4...20mA Current Output Module to Module-2 socket and attach the appropriate labels on the device view will be like below :

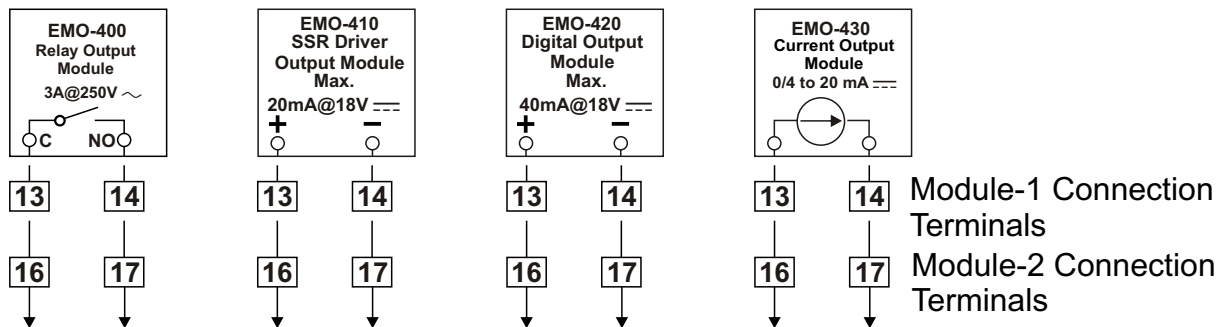


5. Connection Terminals of Input/Output Modules and Connection Wirings

Module-1 / Module-2 Optional Input Modules

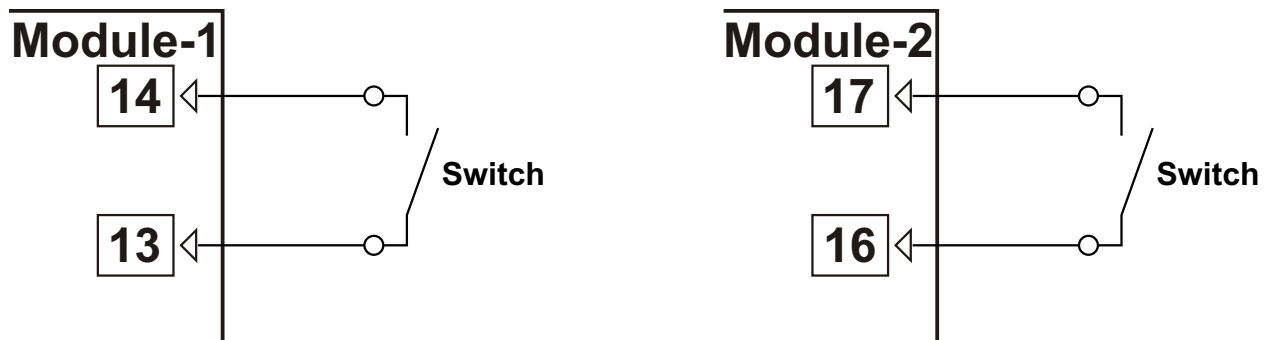


Module-1 / Module-2 Optional Output Modules



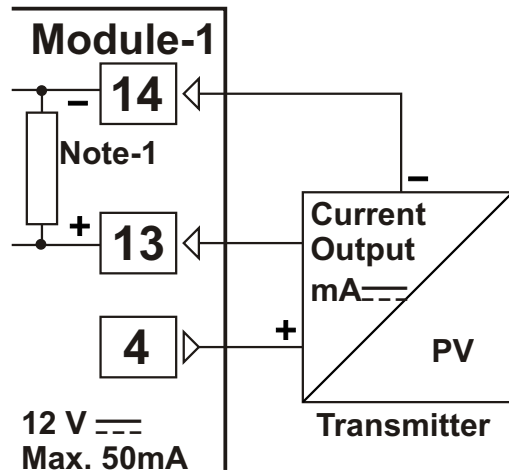
5.1 Connection Wirings for Input Modules

5.1.1 Connection of EMI-400 Digital Input Module

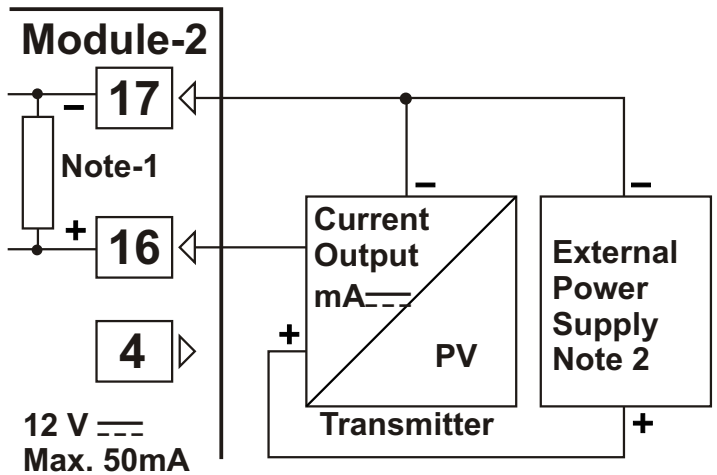
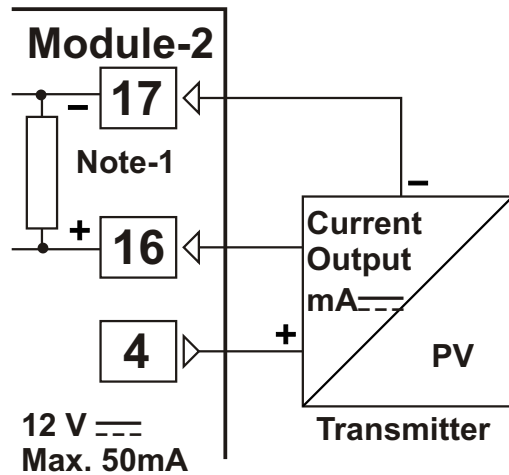
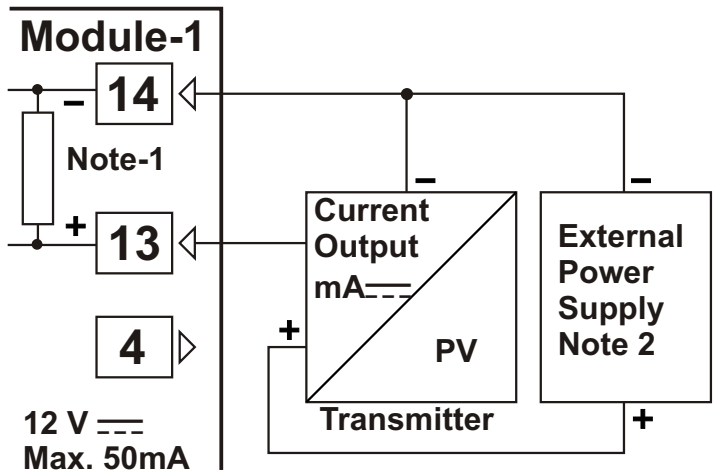


5.1.2 Connection of 3-Wire Transmitter to EMI-410 0/4...20 mA Current Input Module

Transmitter connection by using supply voltage on the device



Transmitter connection by using external supply voltage source.



Note-1 : There is internal 2R7 Ω shunt

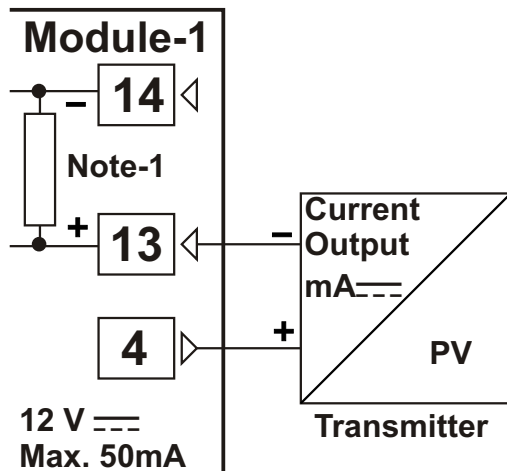
Note 2 : External power supply must be selected according to power supply voltage range and required current for transmitter.



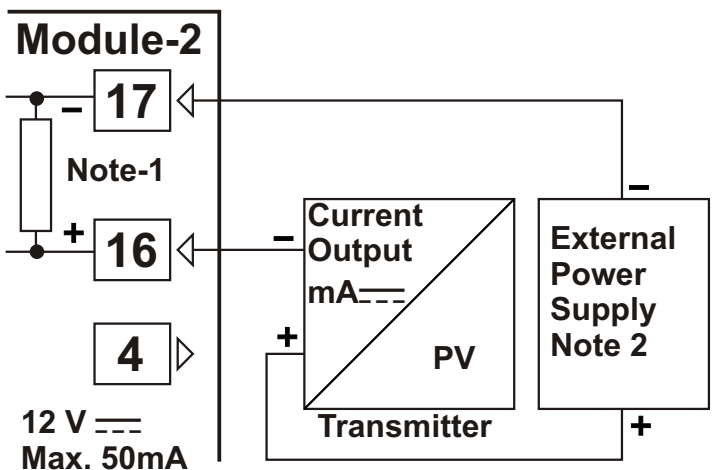
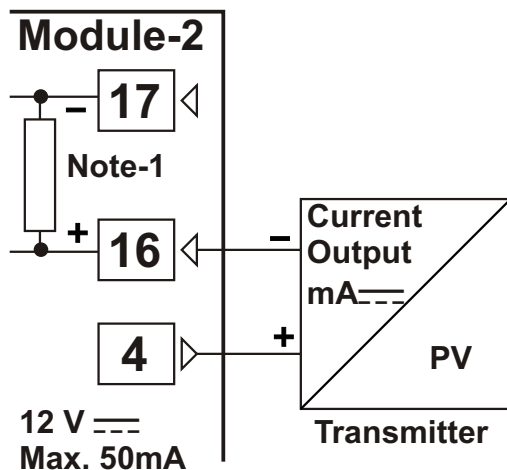
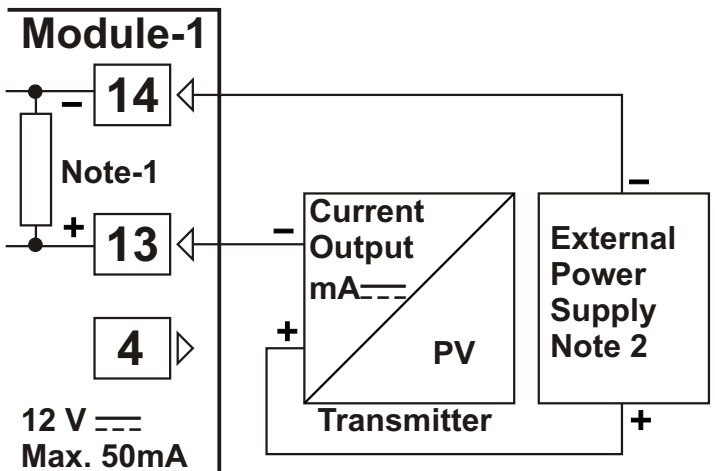
EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

5.1.3 Connection of Serial Transmitter(Loop Powered) to EMI-410 0/4...20 mA Current Input Module

Transmitter connection by using supply voltage on the device



Transmitter connection by using external supply voltage source.



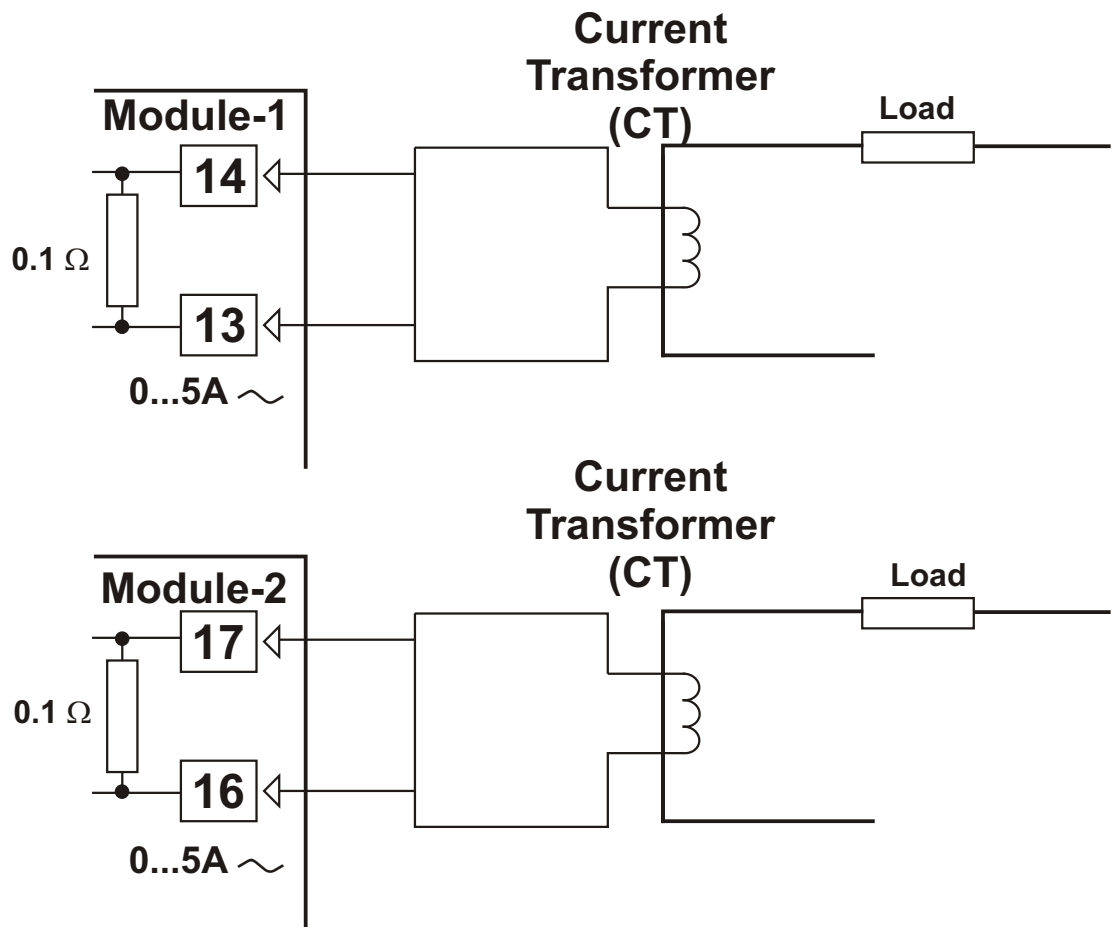
Note-1 : There is internal 2R7 Ω shunt

Note 2 : External power supply must be selected according to power supply voltage range and required current for transmitter.



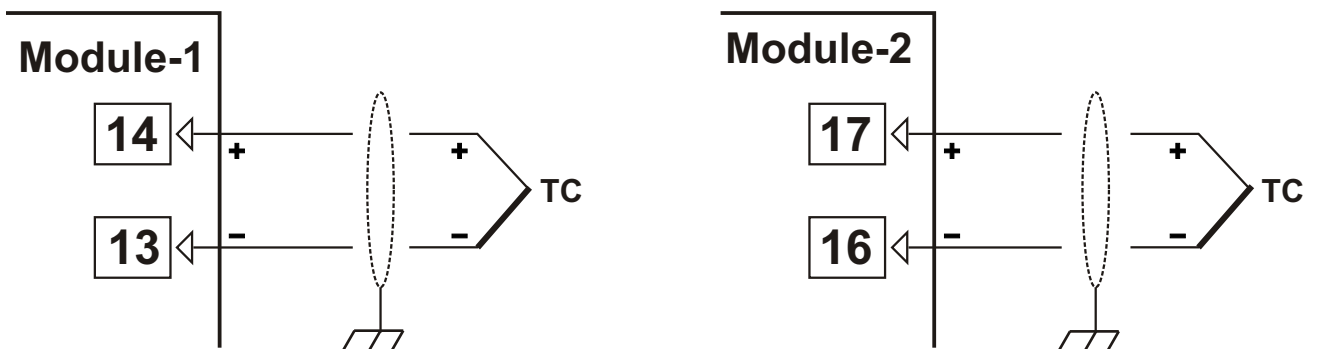
EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

5.1.4 Current Transformer Connection to EMI-420 0...5 A \sim CT Input Module



i Two EMI-420 \sim CT input modules can not be plugged in Module-1 and Module-2 socket at the same time.

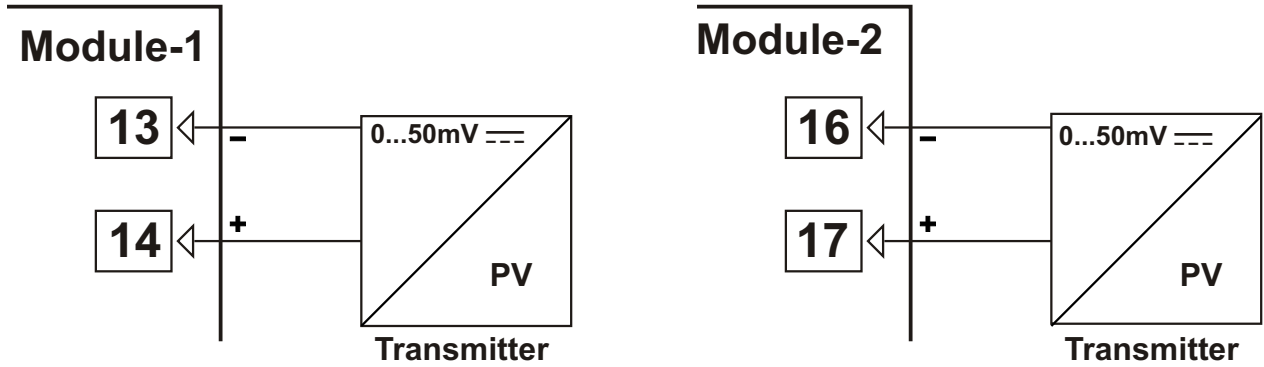
5.1.5 Connection of EMI-430 TC (Thermocouple) or 0...50mV \sim Input Module



Connect the wires with the polarity as shown above. Always use compensation wire corresponding to the thermocouple used. If present, the shield must be connected to a proper ground.

i EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

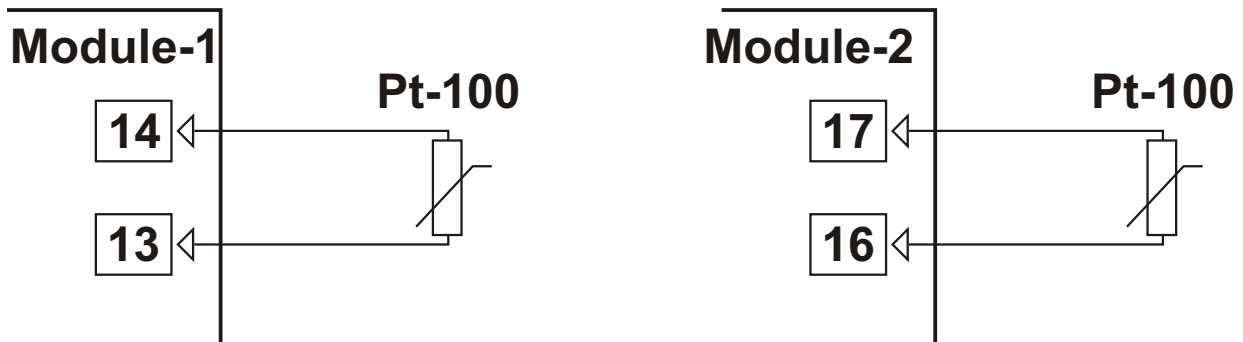
5.1.6 Using EMI-430 TC or 0...50mV $\frac{mV}{mV}$ Input Module as 0...50mV $\frac{mV}{mV}$ Input



By selecting Module-1 or Module-2 analogue input configuration parameter `.5L1` or `.5L2` `0002` And defining calibration points with dual point calibration property, EMI-430 TC or 0...50mV $\frac{mV}{mV}$ module can be used as 0...50mV $\frac{mV}{mV}$ input.

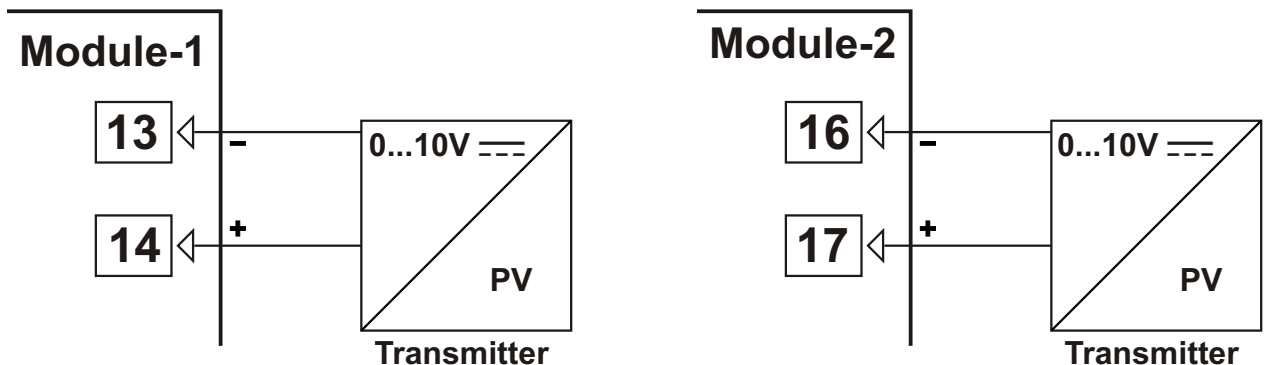
i EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

5.1.7 Connection of EMI-440 PT-100 Input Module



i There is no line compensation in PT-100 Input Module
EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

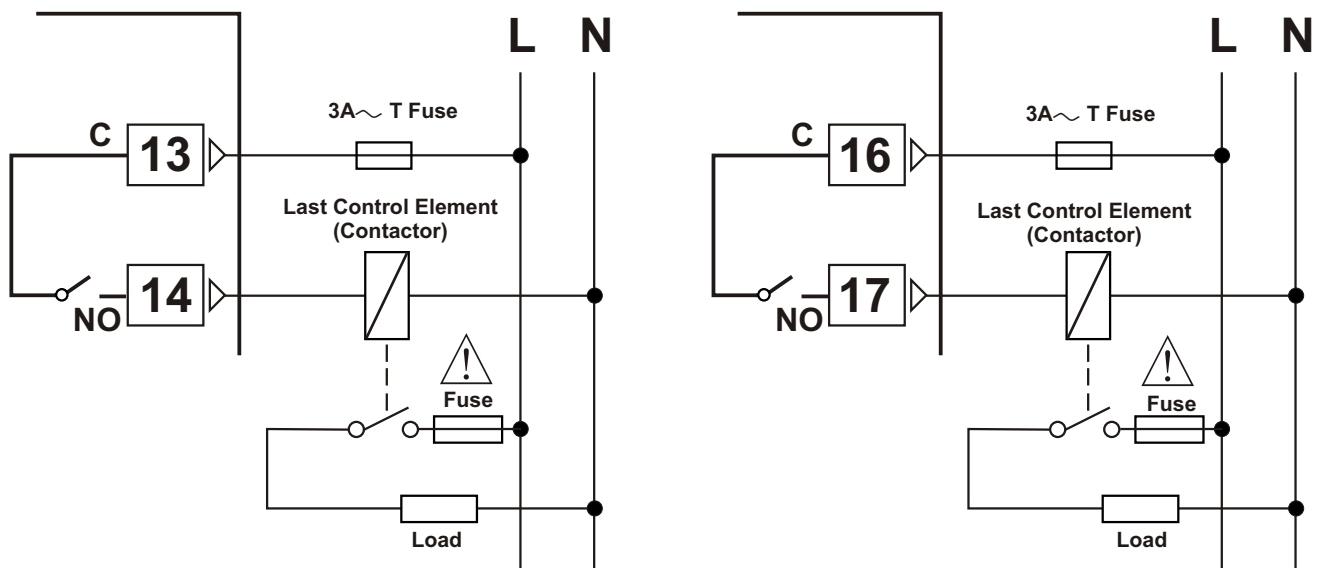
5.1.8 Connection of EMI-450 0...10V $\frac{mV}{mV}$ Input Module



i EMI-410, EMI-430, EMI-440 or EMI-450 analogue input modules can not be plugged-in Module-1 and Module-2 socket at the same time.

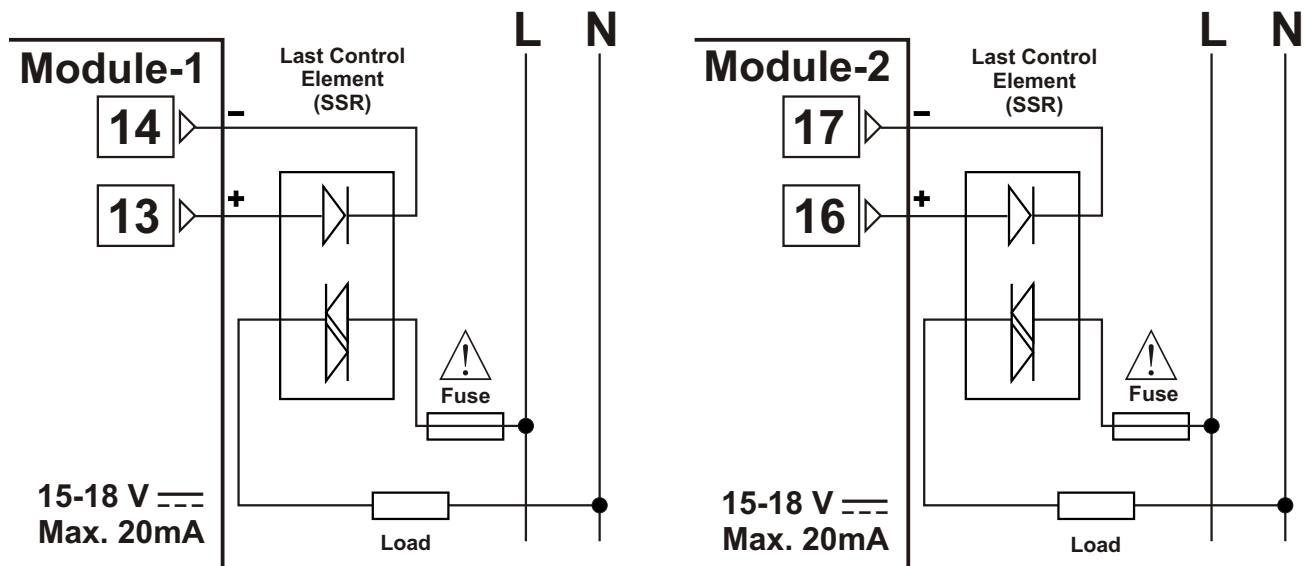
5.2 Connection Wirings for Output Modules

5.2.1 EMO-400 Relay Output Module Connection



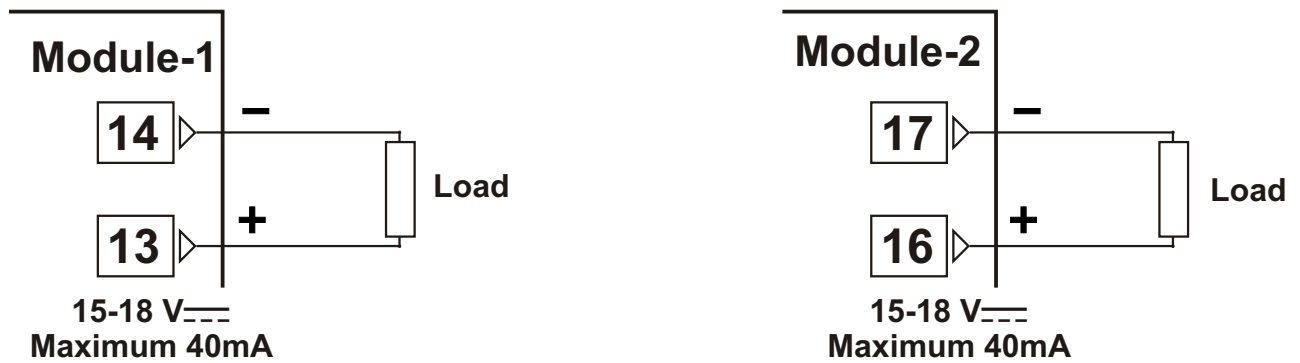
Fuses must be selected according to the applications.

5.2.2 EMO-410 SSR Driver Output Module Connection

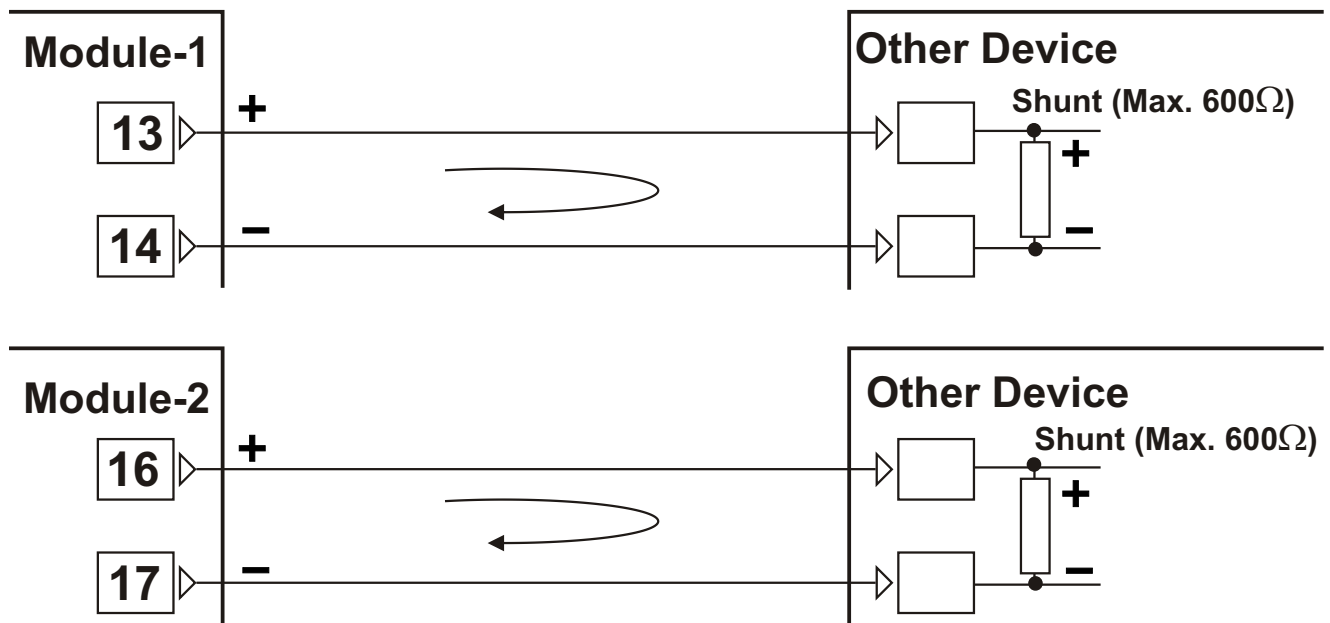


Fuses must be selected according to the applications.

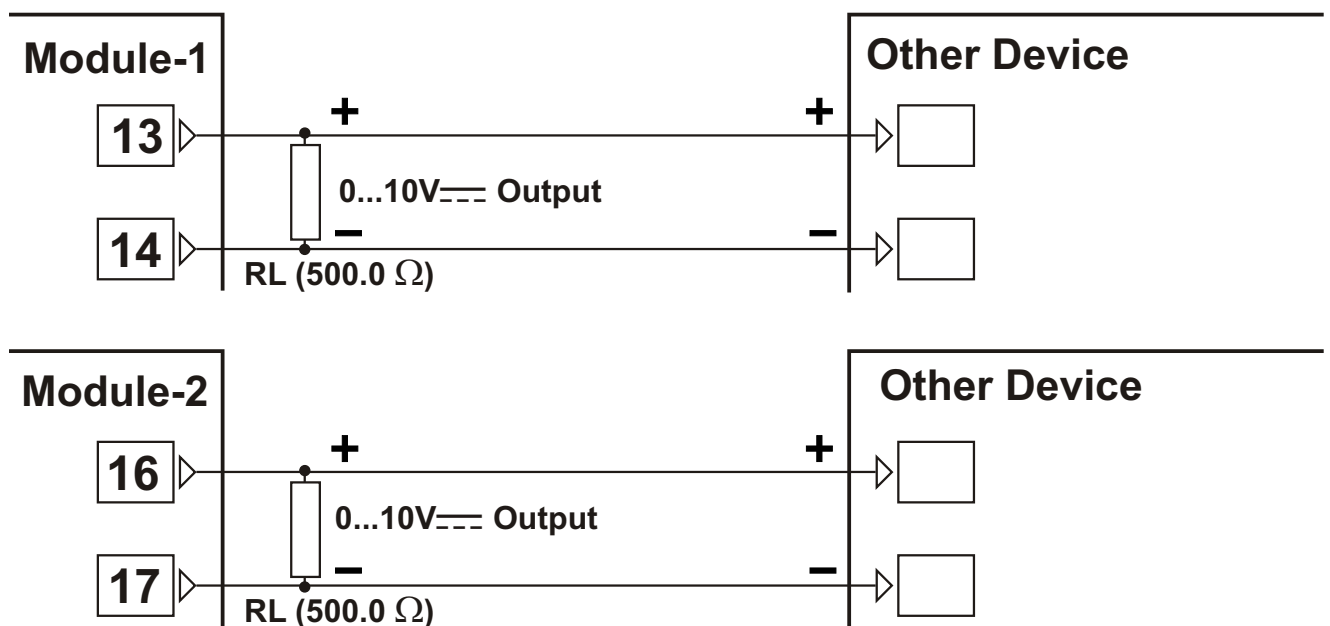
5.2.3 EMO-420 Digital (Transistor) Output Module Connection



5.2.4 EMO-430 0/4... 20 mA --- Current Output Module Connection

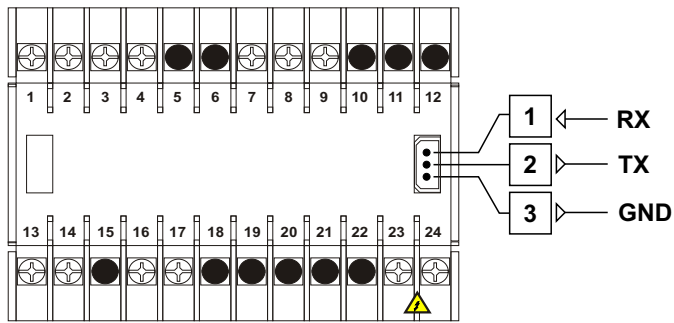


5.2.5 To Get 0...10V --- with EMO-430 0/4...20 mA --- Current Output Module

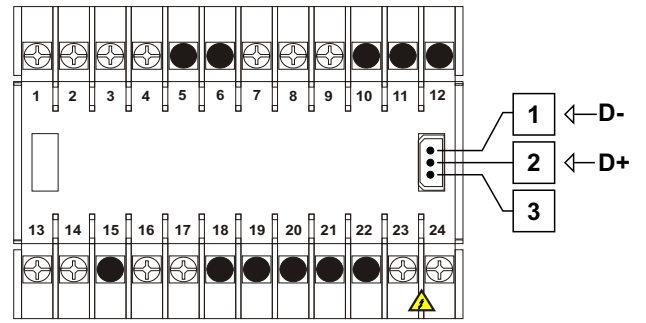


6.Connections for RS-232 / RS-485 Serial Communication

RS-232 Terminal Definitions

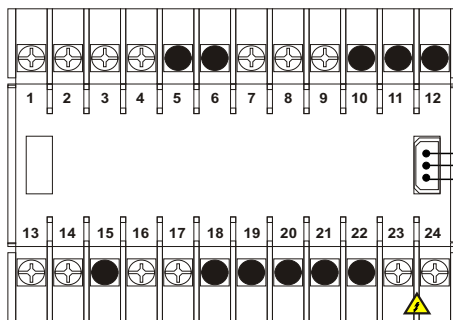


RS-485 Terminal Definitions



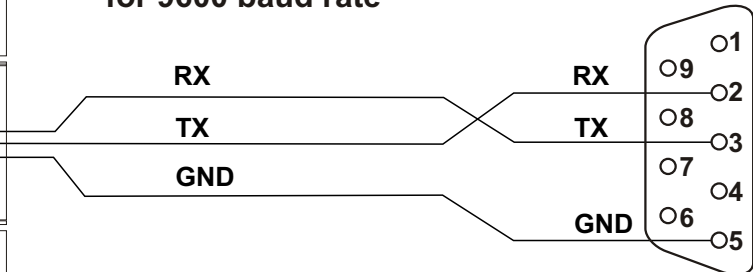
6.1 Cable Connection Between RS-232 Terminal of the Device and PC

ESM-4950

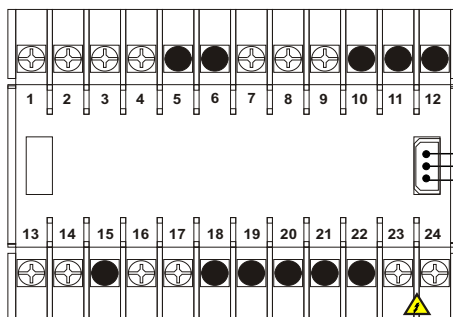


Cable Length must be max. 12 meters for 9600 baud rate

PC (Personal Computer)
9 Pin DCON connection

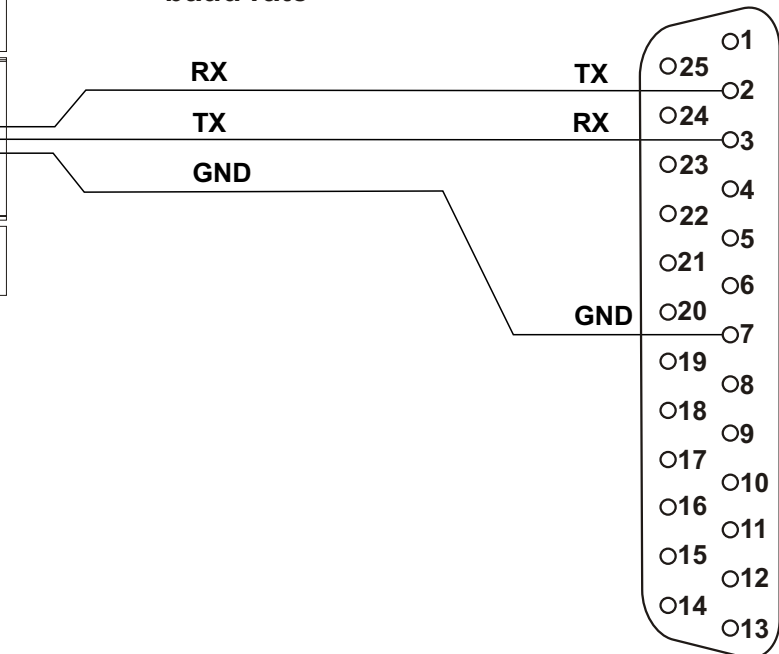


ESM-4950

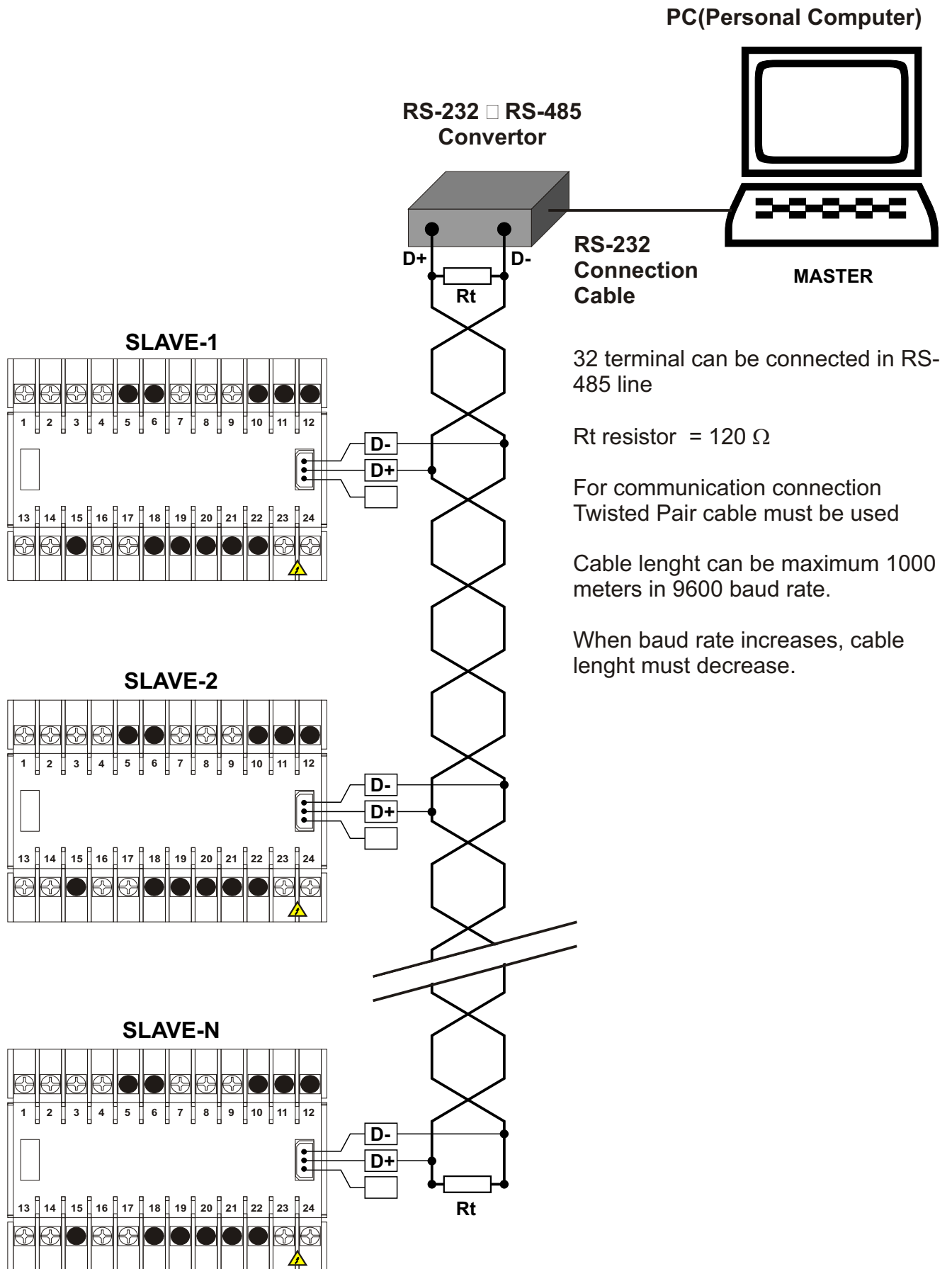


Cable Length must be max. 12 meters for 9600 baud rate

PC (Personal Computer)
25 Pin DCON connection



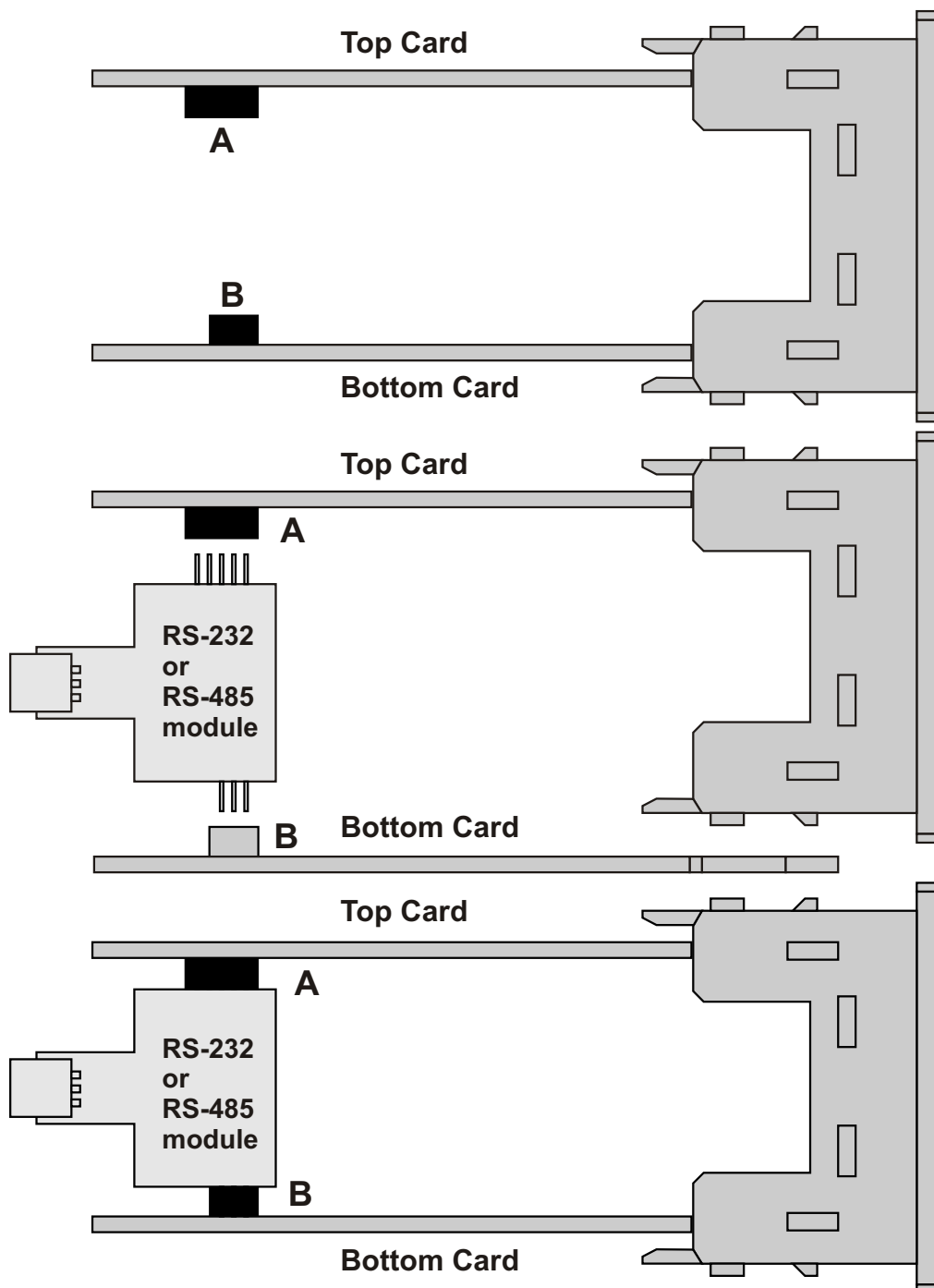
6.2 Connection for RS-485 Serial Communication



6.3 Installing RS-232 / RS-485 Serial Communication Modules to the Device

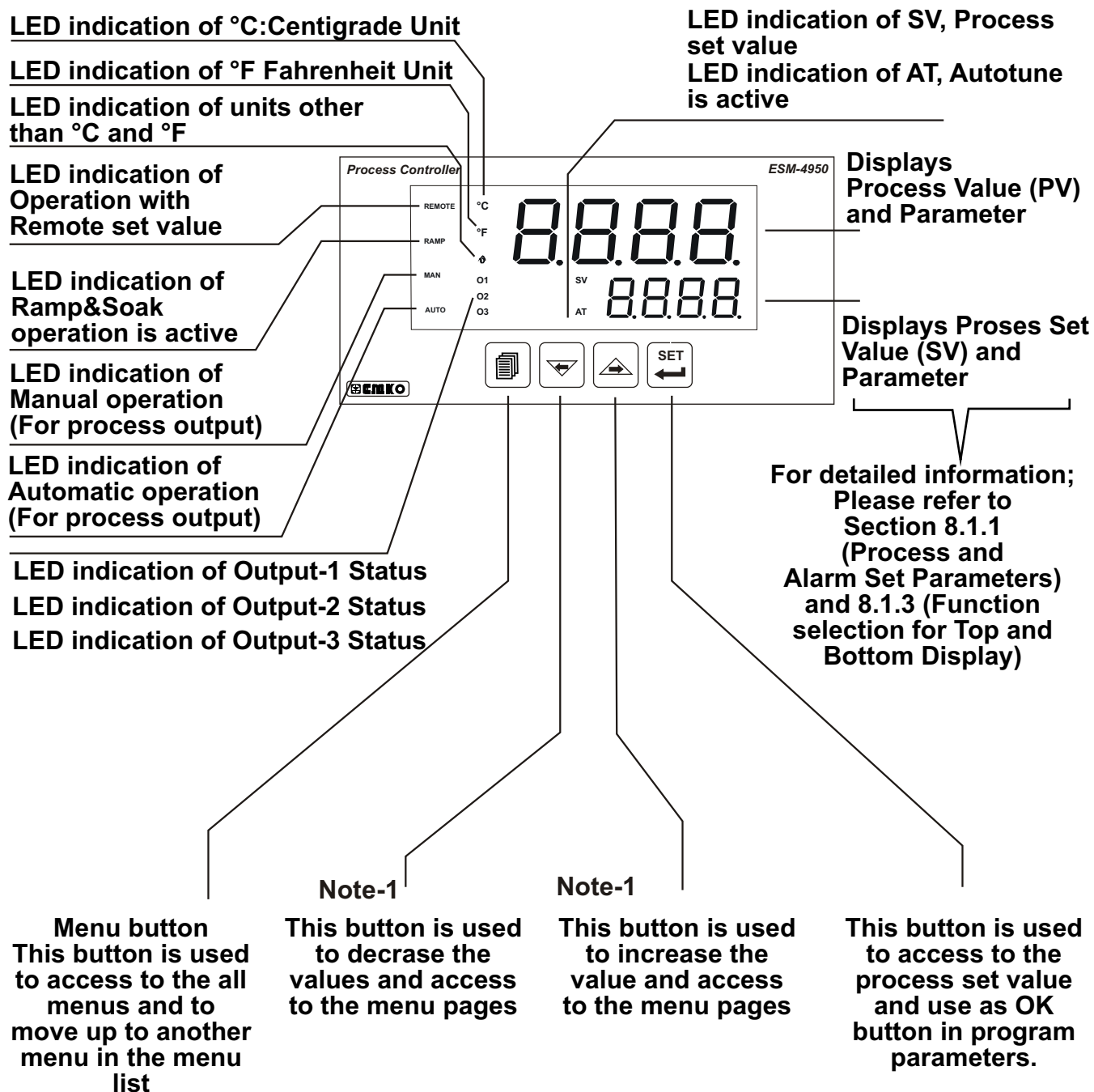
Pull the cover case with your hand through rear side as explained in “Installing and Pulling Out Input/Output Modules” section. Pull the modules in Module-1 and Module-2 socket through rear side. Separate supply card which is at the bottom of the equipment by lifting the locking tabs located on front panel. Pay attention to cable connection between top and bottom cards. Damages in this cable makes the equipment not to work.

RS-232 or RS-485 module is plugged into socket signed as A and B. Hold the equipment to be it's front panel is on your right, communication socket is on your left and module connection socket with 5 terminals on above. Plug in module connection socket with 5 terminals to the socket on Top Card. Do the same things for terminal socket in bottom card and connection socket with 3 terminals. Plug in bottom card to the place in front panel. Install the modules which are pulled out to Module-1 and Module-2 socket. Replace the cover case by taking care of the terminal numbers should be at right position.



7. Definition of Front Panel and Accessing to the Parameters

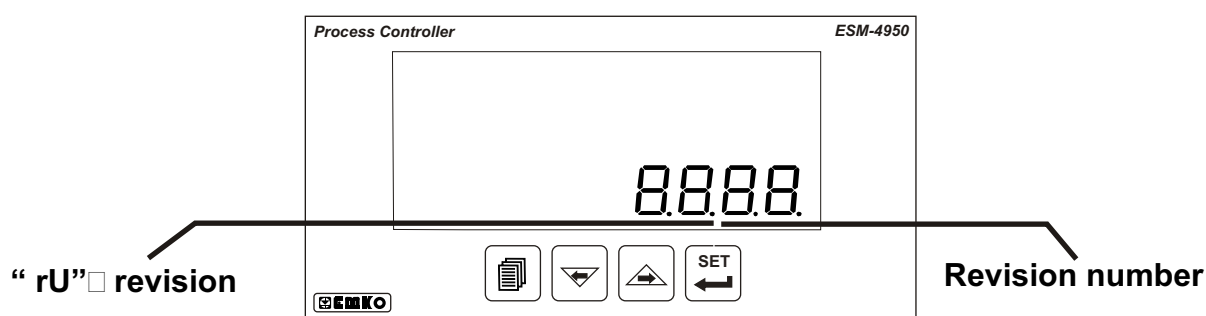
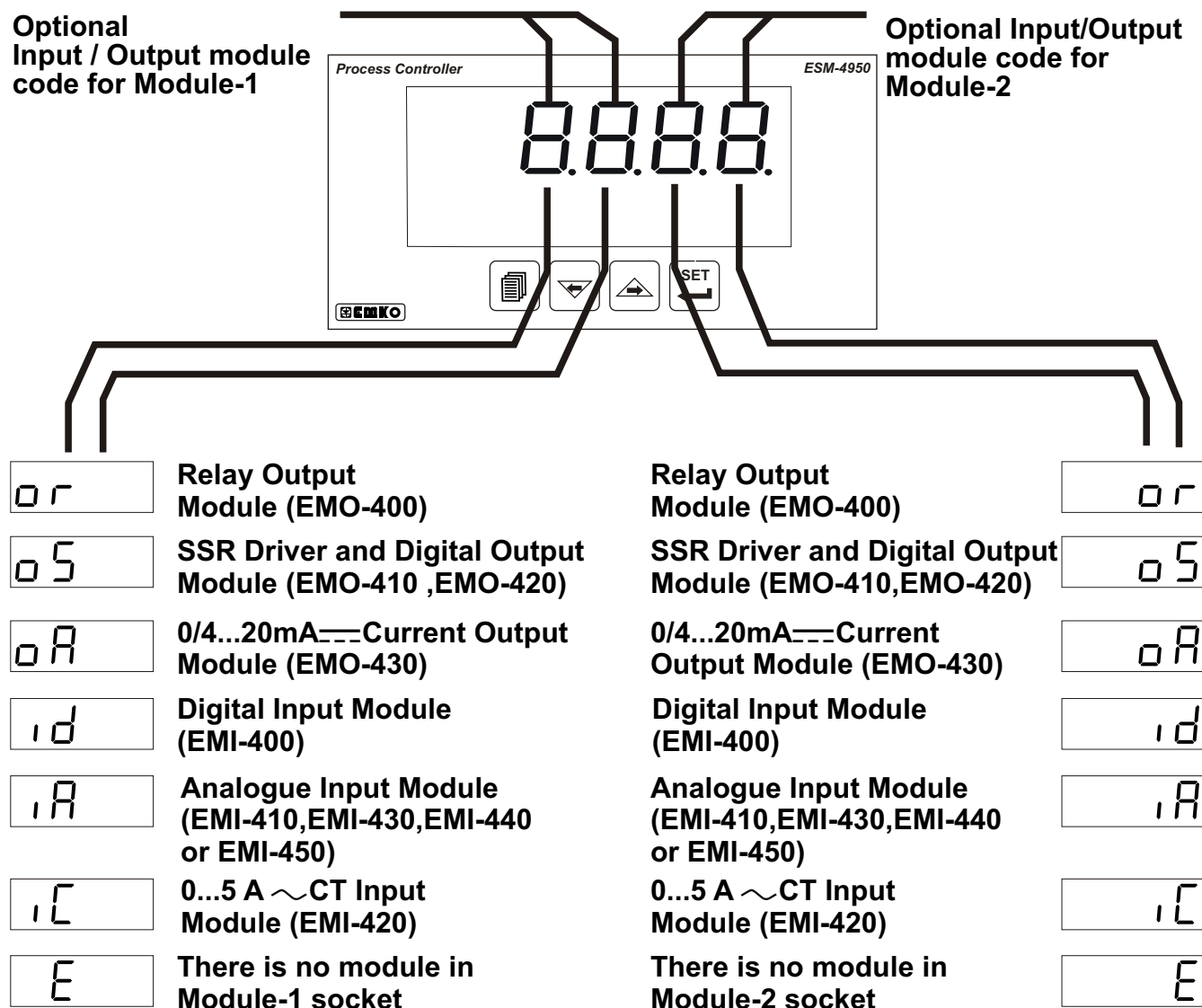
7.1 Definition of Front Panel



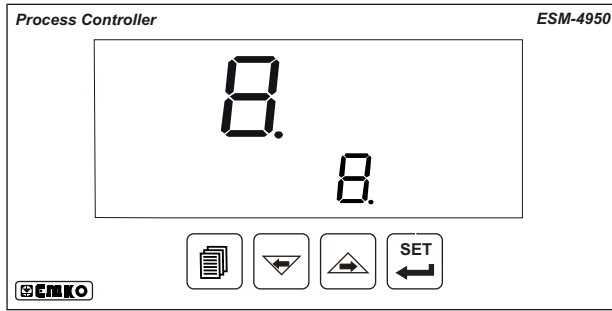
Note-1: If increment or decrement button is pressed for 5 seconds continuously, increment and decrement number become 10, if increment or decrement button is pressed for 10 seconds continuously, increment and decrement number become 100.

7.2 Observation of Optional Modules and Software Revision on the Displays

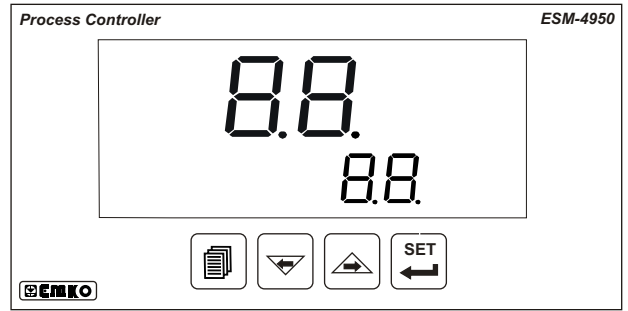
There are two sockets for plugging optional modules to the device. These modules are recognized by the device automatically. When the power is applied to the device all led indicators and display segments are momentarily illuminated for testing. Software revision number of the controller on the bottom display and module definition codes on the top display are momentarily illuminated. Module definition codes and how to observe these codes of optional modules in Module-1 and Module-2 socket are explained below :



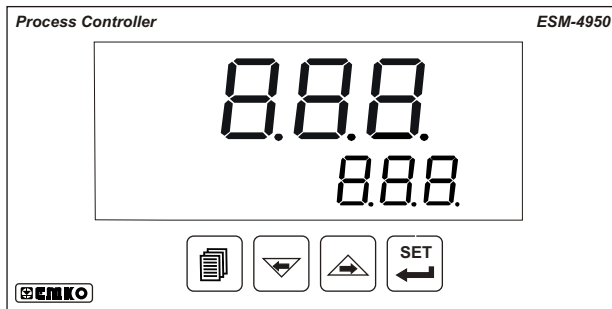
When power on, display of the device is like below:



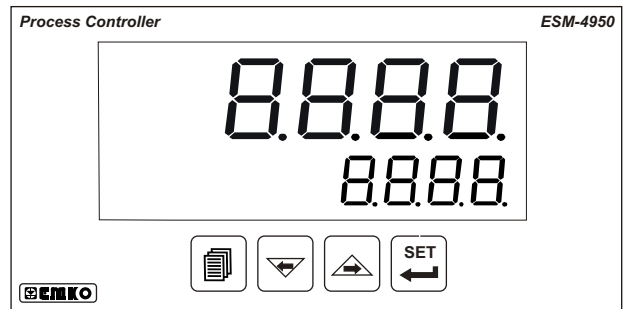
First segments of top and bottom displays are tested



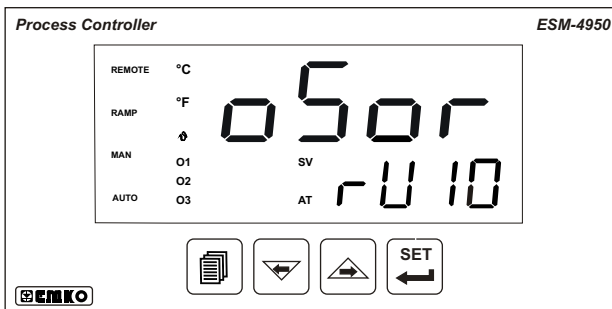
Second segments of top and bottom displays are tested.



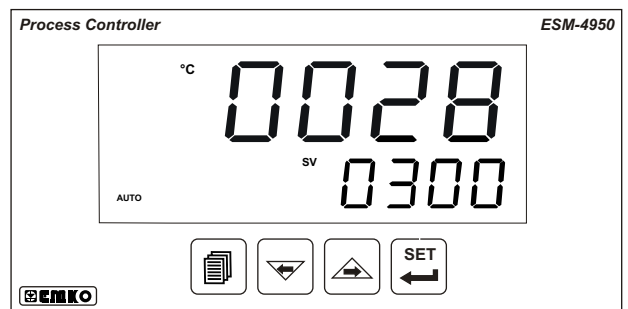
Third segments of top and bottom displays are tested.



Fourth segments of top and bottom displays are tested.



On top display which modules are plugged in Module-1 and Module-2 socket and on bottom display revision number are shown. All leds are energised. Above, there is EMO-410 SSR Driver Output module in Module-1 socket and EMO-400 Relay Output Module in Module-2 socket. Revision number is "10".

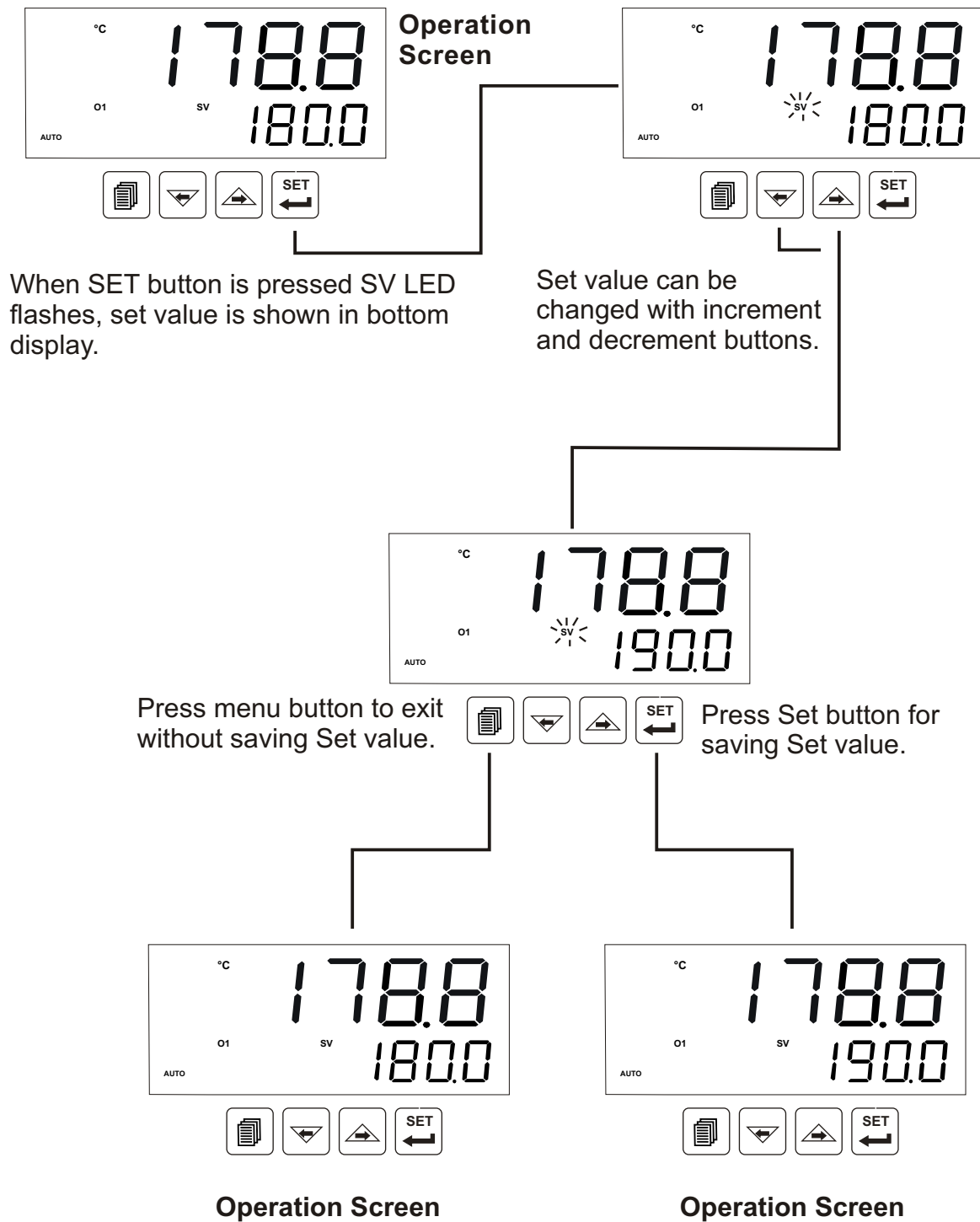


Main operation screen is shown



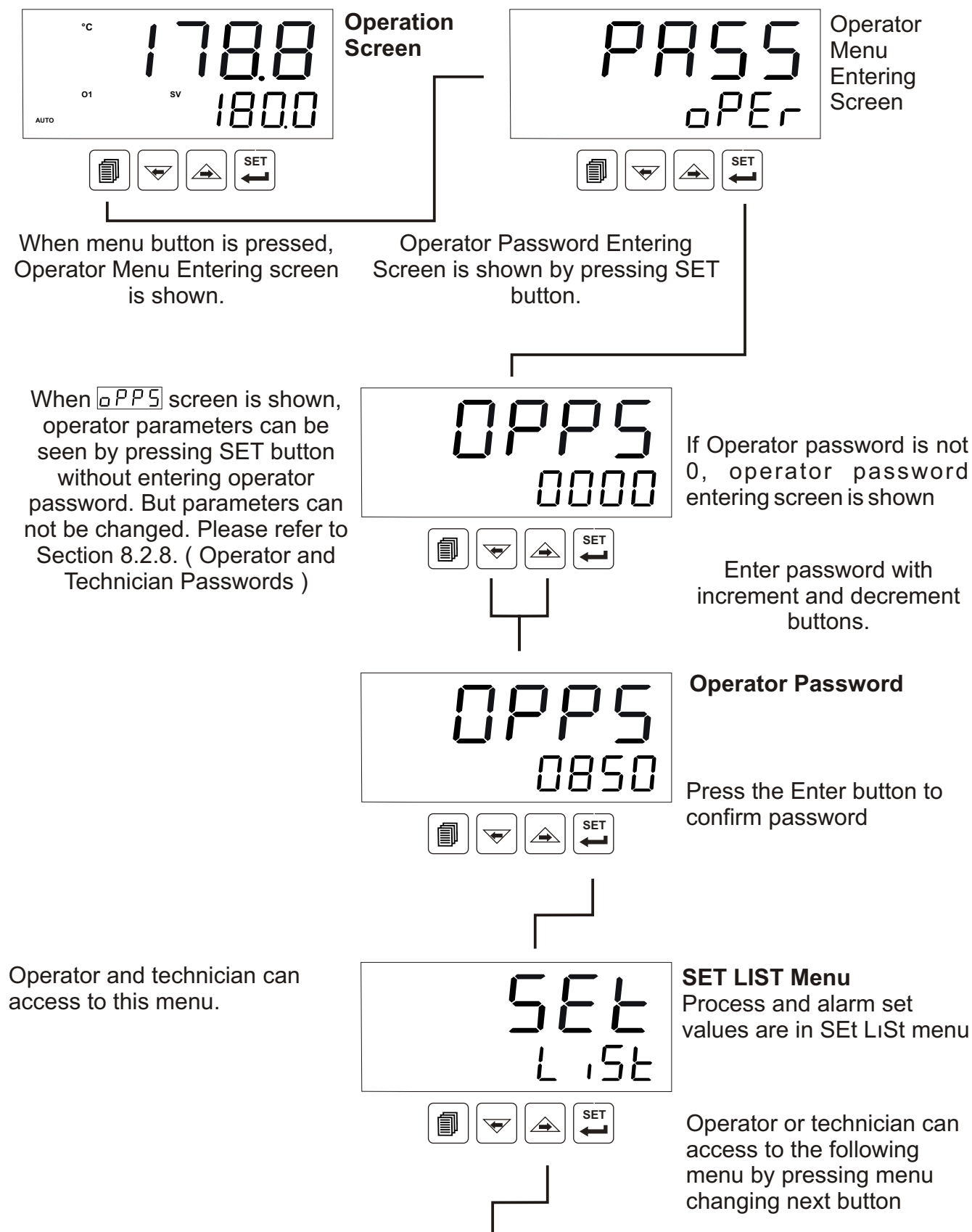
If there is an unexpected situation while opening the device, power off the device and inform a qualified personnel.

7.3 Adjustment of Process Set Value

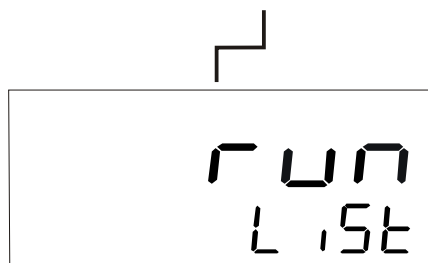


7.4 Accessing to the Operator Menu

The parameters have been divided into groups according to their functions. Every group has a title and firstly user must determine the title (menu) for accessing to the parameters. Refer to the parameters section for detailed information about parameters.



Operator and technician can access to this menu.

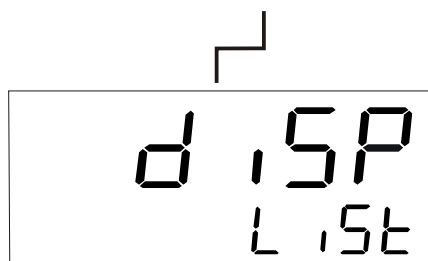


RUN LIST Menu

Operating form selection parameters are in run LIST menu.

Operator or technician can access to the former menu by pressing menu changing back button

Operator and technician can access to this menu.



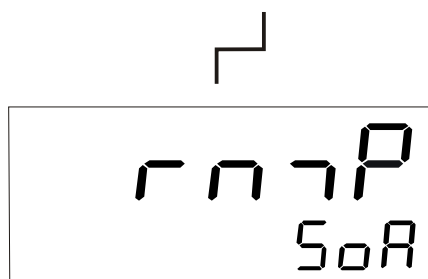
Operator or technician can access to the following menu by pressing menu changing next button.

DISPLAY LIST Menu

This menu determines which parameter is shown in top and bottom display.

Operator or technician can access to the former menu by pressing menu changing back button

Operator and technician can access to this menu.



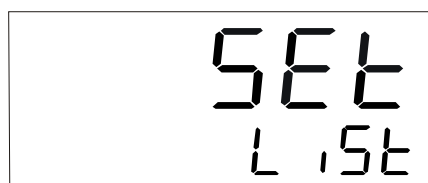
Operator or technician can access to the following menu by pressing menu changing next button.

RAMP&SOAK Menu

Configuration of Ramp/Soak function and step set value parameters are in this menu.

Operator or technician can access to the former menu by pressing menu changing back button

Operator and technician can access to this menu.



Operator or technician can access to the following menu by pressing menu changing next button.

SET LIST Menu

SET LIST menu exists after RAMP/SOAK menu.

Operator or technician can access to the former menu by pressing menu changing back button

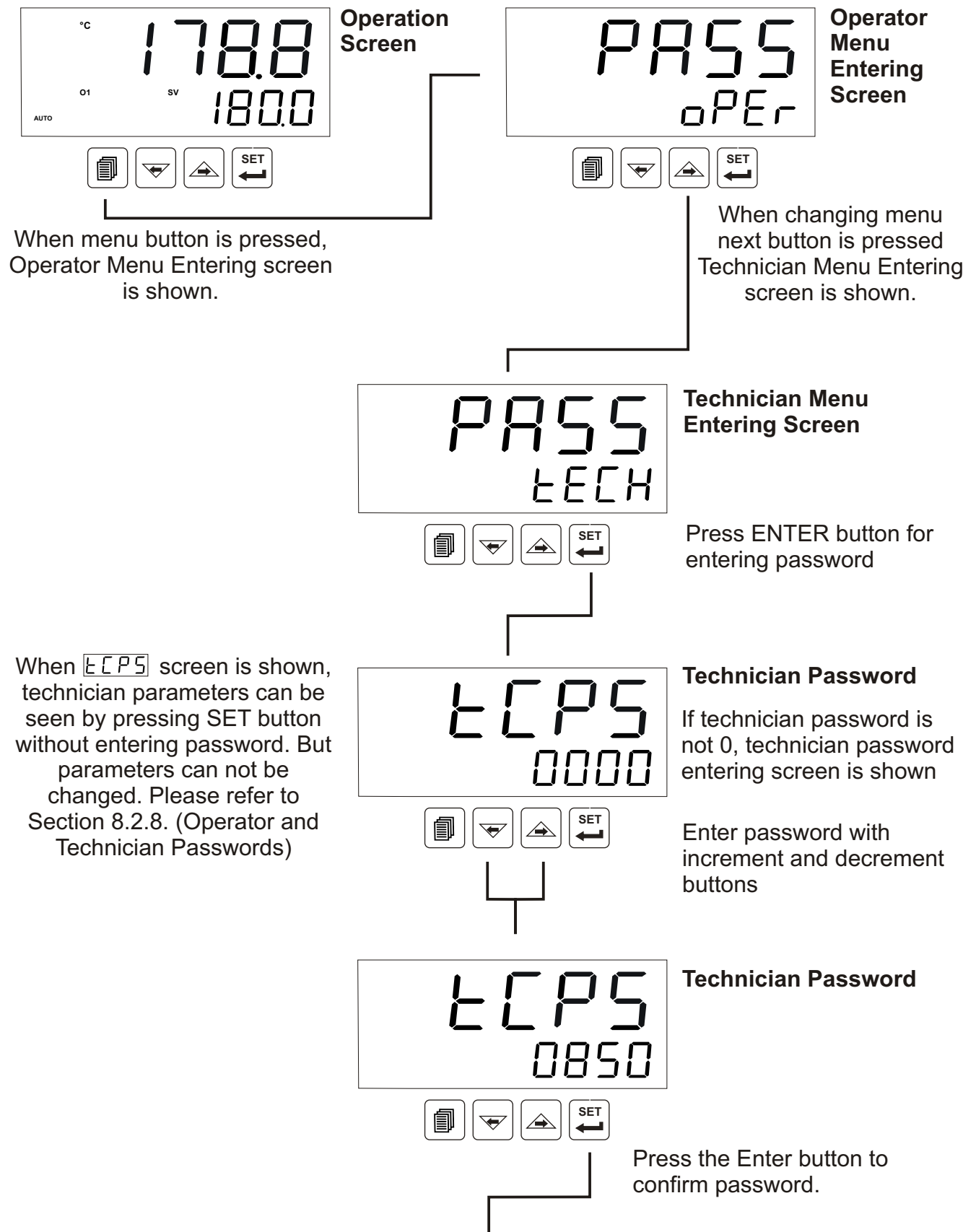
Press menu button to exit from MENU list and turn to operation screen.

Continue to press menu changing next and back buttons to change the menu.

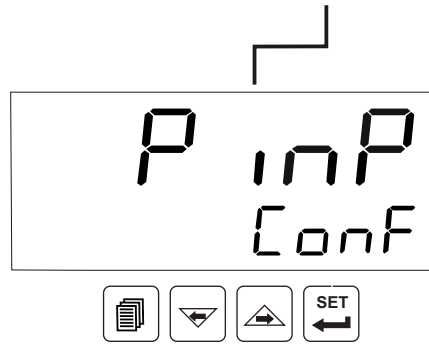
By pressing ENTER button, user can access to the menu page and to all parameters in this menu page.

7.5 Accessing to the Technician Menu

The parameters have been divided into groups according to their functions. Every group has a title and firstly user must determine the title (menu) for accessing to the parameters. Refer to the parameters section for detailed information about parameters.



Operator can not access to this menu.

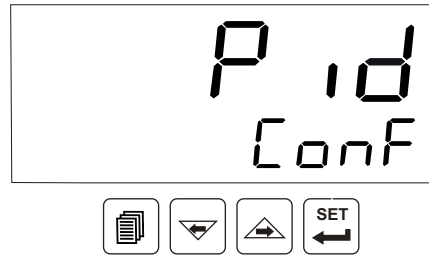


PINP CONF Menu

Configuration parameters of process input.

Technician can access to the following menu by pressing menu changing next button.

Operator can not access to this menu.



PID CONF Menu

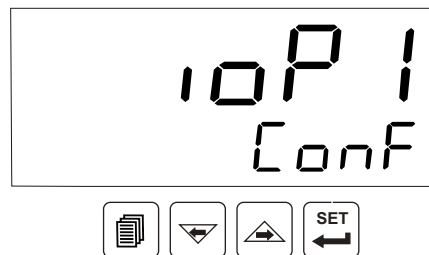
Parameters about PID algorithm.

Technician can access to the former menu by pressing changing menu back button.

Technician can access to the following menu by pressing menu changing next button.

Operator can not access to this menu.

This menu is not visible if there is no module in Module-1 socket.



IOP1 CONF Menu

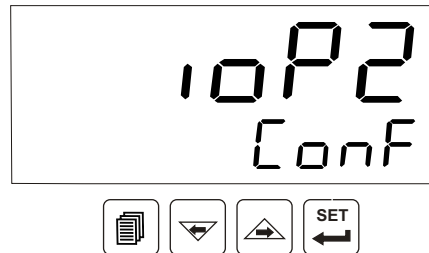
This menu defines configuration parameters of input/output modules in Module-1 socket.

Technician can access to the former menu by pressing changing menu back button.

Technician can access to the following menu by pressing menu changing next button.

Operator can not access to this menu.

This menu is not visible if there is no module in Module-2 socket.



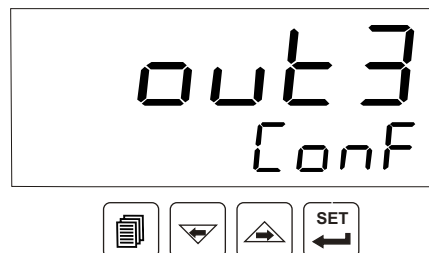
IOP2 CONF Menu

This menu defines configuration parameters of input/output modules in Module-2 socket.

Operator or technician can access to the former menu by pressing menu changing back button

Technician can access to the following menu by pressing menu changing next button.

Operator can not access to this menu.



OUT3 CONF Menu

This menu defines configuration parameters of output-3.

Operator or technician can access to the former menu by pressing menu changing back button

Technician can access to the following menu by pressing menu changing next button.

Operator can not access to this menu.

Technician can access to the former menu by pressing changing menu back button.

Operator can not access to this menu.

Technician can access to the former menu by pressing changing menu back button.

Operator can not access to this menu.

This menu is not visible if Technician Parameters Section is entered by pressing SET button but not entering Technician Password.

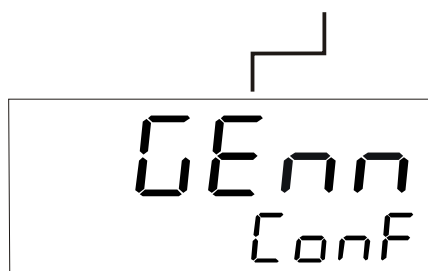
Technician can access to the former menu by pressing changing menu back button.

Operator and technician can access to this menu.

Technician can access to the former menu by pressing changing menu back button.

Operator and technician can access to this menu.

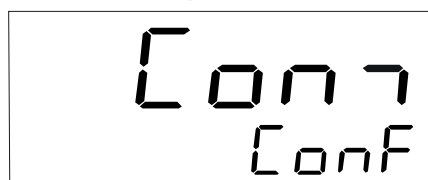
Technician can access to the former menu by pressing changing menu back button.



GENN CONF Menu

This menu defines general parameters

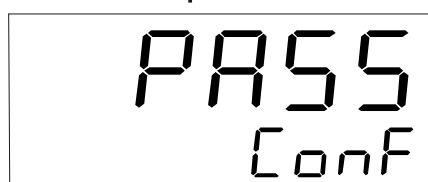
Technician can access to the following menu by pressing menu changing next button.



COM CONF Menu

This menu defines configuration parameters for serial communication

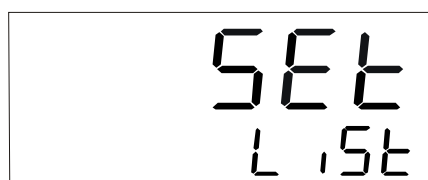
Technician can access to the following menu by pressing menu changing next button.



PASS CONF Menu

Operator and technician passwords are in this menu.

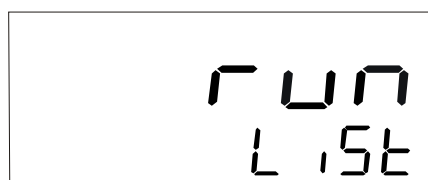
Technician can access to the following menu by pressing menu changing next button.



SET LIST Menu

Process and alarm set values are in SET LIST menu.

Technician can access to the following menu by pressing menu changing next button.

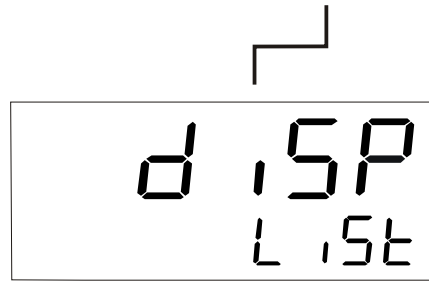


RUN LIST Menu

Operating form selection parameters are in RUN LIST menu.

Technician can access to the following menu by pressing menu changing next button.

Operator and technician can access to this menu.



DISP LIST Menu

It defines which parameter will be shown on top and bottom displays.

Technician can access to the former menu by pressing changing menu back button.



Technician can access to the following menu by pressing menu changing next button.

Operator and technician can access to this menu.



Ramp&Soak Menu

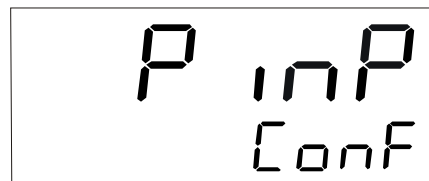
Configuration of Ramp/Soak functions and step set value parameters are in this menu.

Technician can access to the former menu by pressing changing menu back button.



Technician can access to the following menu by pressing menu changing next button.

Operator can not access to this menu.



PINP CONF Menu

PINP CONF Menu exists after RAMP/SOAK menu.

Technician can access to the former menu by pressing changing menu back button.



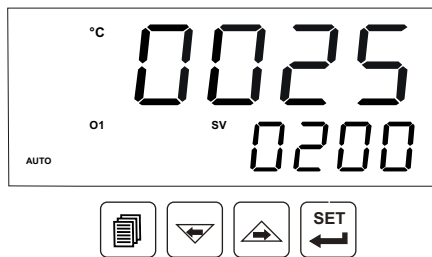
Press Menu button to exit from Menu list and turn to operation screen.

Continue to press menu changing back and next buttons to change menu pages

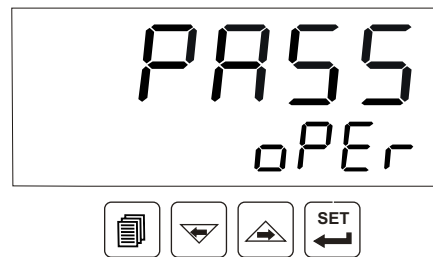
By pressing ENTER button, user accesses to the menu page and to all parameters in this menu page.

7.6 Adjustment of Alarm Set Values

If standard output (Output-3), Module-1 or Module-2 is configured as an alarm output, alarm set values of these outputs are in "SEt LISt" menu. User can access to "SEt LISt" menu both from operator and technician menus.



Operation Screen

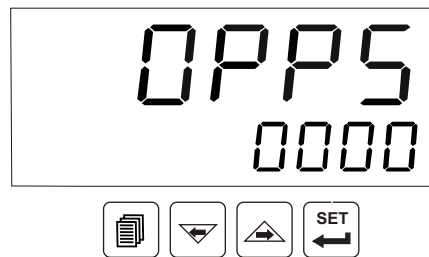


Operator Menu Entering Screen

When menu button is pressed, Operator Menu Entering screen is shown

Operator Password Entering screen is accessed by pressing SET button.

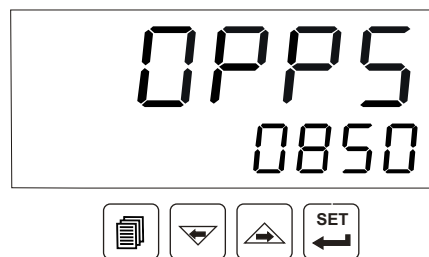
When **PPS** screen is shown, operator parameters can be seen by pressing SET button without entering operator password. But operator can not change the parameters. Please refer to Section 8.2.8 (Operator and Technician Passwords)



Operator Password

If Operator password is not 0, operator password entering screen is shown

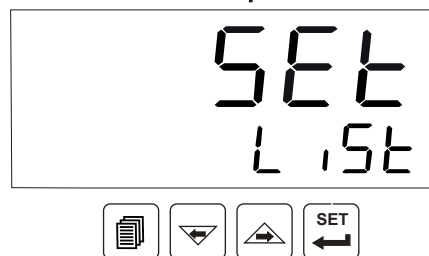
Enter password with increment and decrement buttons.



Operator Password

Press Enter button to confirm password

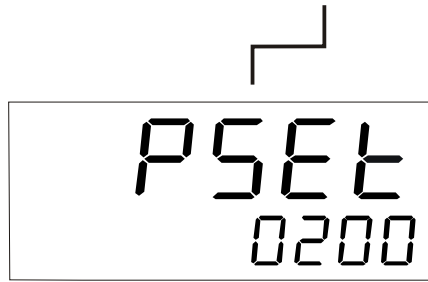
Operator and technician can access to this menu.



SET LIST Menu

Process and alarm set values are in SEt LISt menu.

Press menu changing next parameter to access to the next menu.



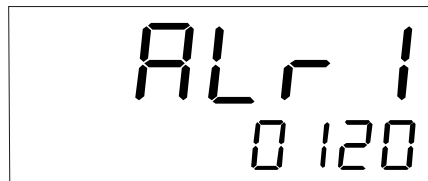
Process Set Value

Operator and technician can change the parameter with increment and decrement buttons



Press Enter button to confirm the changed value and access to the following parameter.

This parameter is not visible if there is no output module in Module-1 socket or output module is not configured as an alarm output.



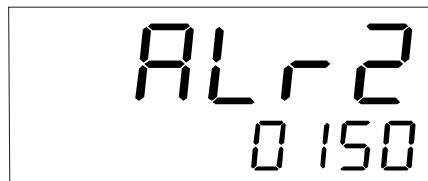
Alarm-1 Set Value

Operator and technician can change the parameter with increment and decrement buttons



Press Enter button to confirm the changed value and access to the following parameter.

This parameter is not visible if there is no output module in Module-2 socket or output module is not configured as an alarm output.



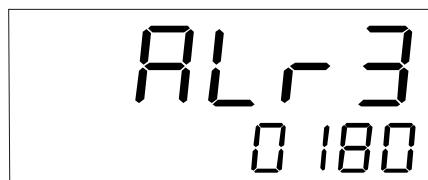
Alarm-2 Set Value

Operator and technician can change the parameter with increment and decrement buttons



Press Enter button to confirm the changed value and access to the following parameter.

This parameter is not visible if Output-3 is not configured as an alarm output

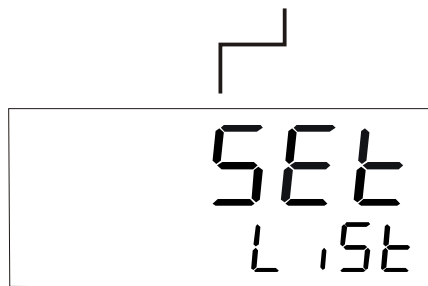


Alarm-3 Set Value

Operator and technician can change the parameter with increment and decrement buttons.

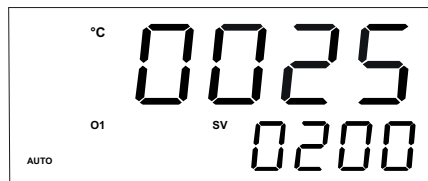


Press menu button to turn to operation screen



SET LIST Menu

Process and alarm set values are in SET LIST menu.



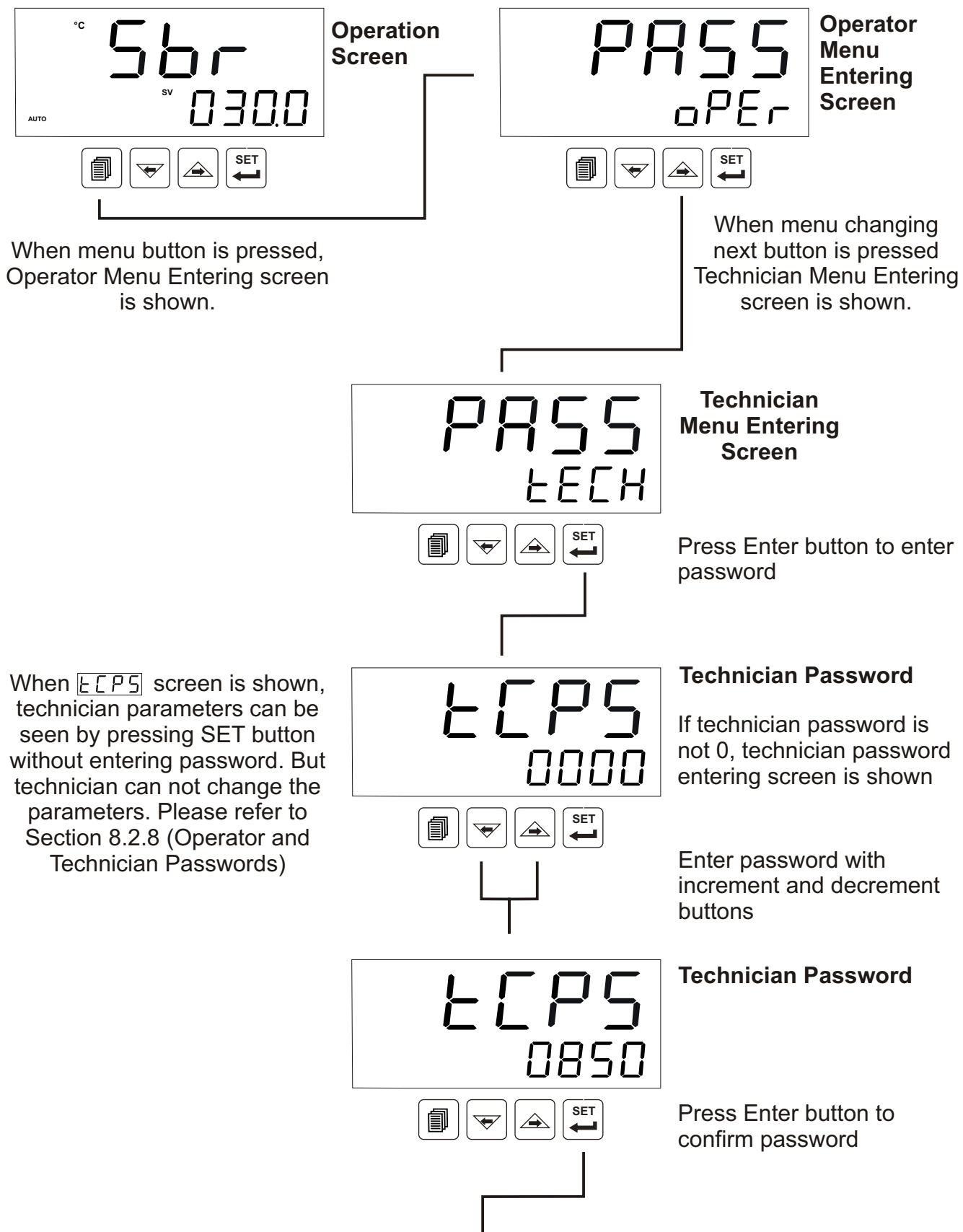
Press menu button to turn to operation screen



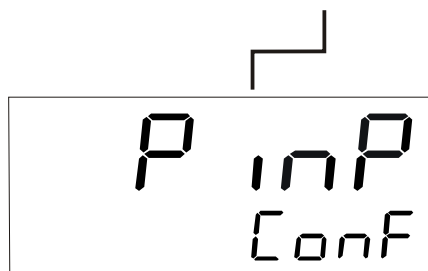
Operation Screen

7.7 Changing and Saving Parameter Values

Example-1 : To change Process Input Type parameter 155L in “PinP Conf” menu, user must access to PinP ConF menu firstly.



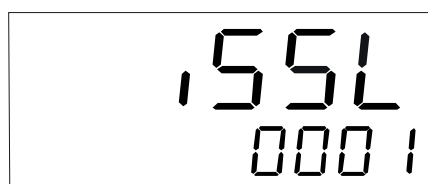
Operator can not access to this menu.



PINP CONF Menu

Press Enter button to access to PinP Conf menu

Operator can not access to this parameter

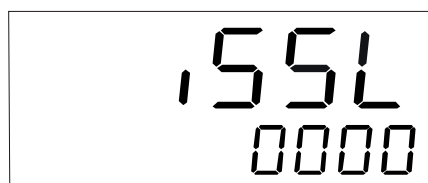


Selection of Process Input Type

155L is 0001 means, input type is RTD.

Parameter can be changed with increment and decrement buttons

Operator can not access to this parameter

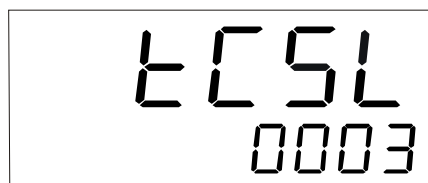


Selection of Process Input Type

TC input type is selected

Press Enter button to confirm the changed value and access to the following parameter.

Operator can not access to this parameter



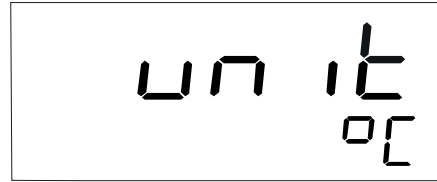
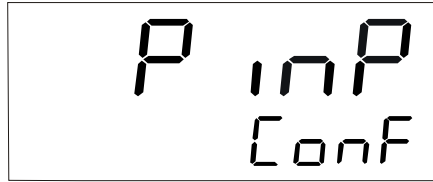
Selection of TC Input Type

Technician can access to the following menu by pressing Enter button

If Menu button is pressed again, operation screen is shown.

PINP CONF Menu
When Menu button is pressed, menu pages are shown.

Press Enter button to access to the following parameter.



Unit selection

Continue to press menu changing back and next buttons to change menu pages

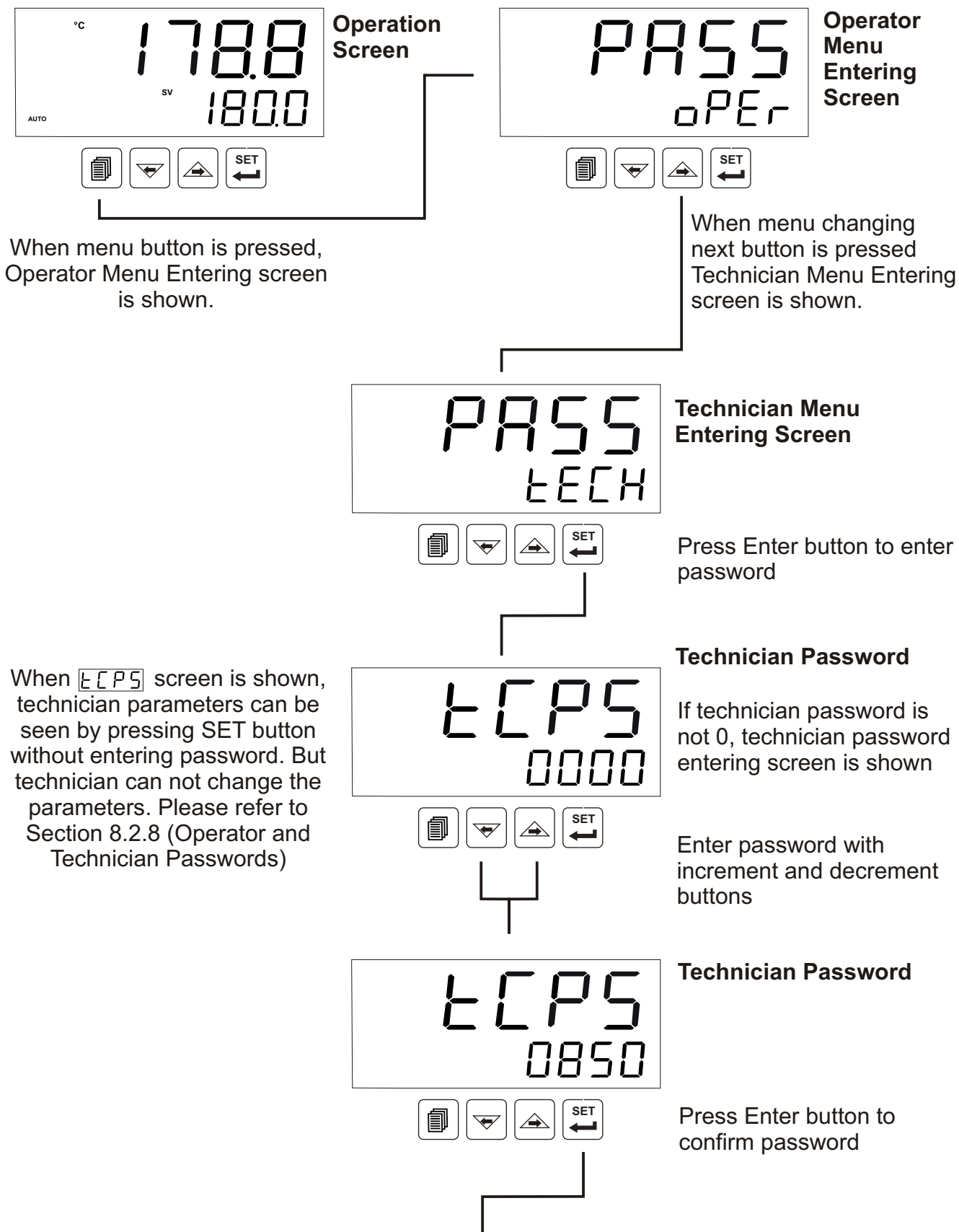
If Menu button is pressed again, operation screen is shown.



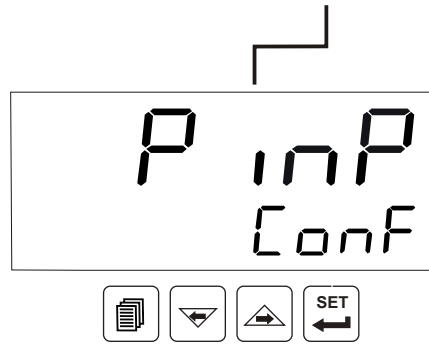
Operation Screen

Example-2 : To change heating proportional band parameter $P-HL$ in “Pid Conf” menu

$P-HL$ Parameter is on Pid ConF menu. For accessing to this parameter, user must access to “Pid ConF” menu firstly.



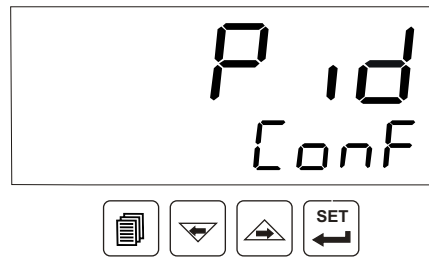
Operator can not access to this menu.



PINP CONF Menu

Technician can access to the following menu by entering menu changing next button

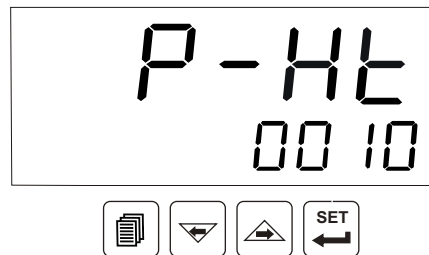
Operator can not access to this menu.



Pid CONF Menu

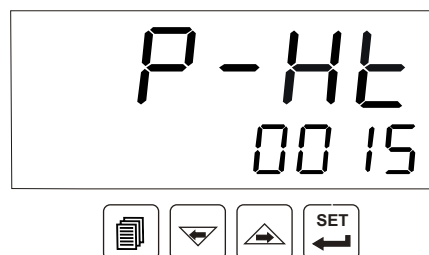
Technician can access to Pid ConF menu by pressing Enter button

Operator can not access to this parameter



Heating Proportional Band Selection

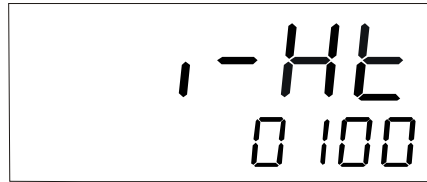
Parameter can be changed with increment and decrement buttons.



Heating Proportional Band Selection

Press Enter button to confirm the changed value and access to the following parameter.

Operator can not access to this parameter



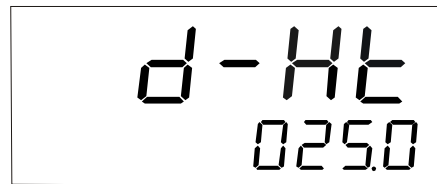
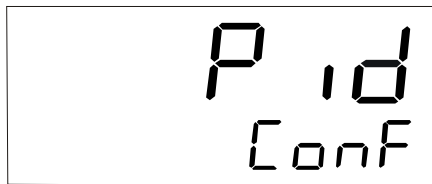
Heating Integral Time

PID CONF Menu

Technician turns to Menu pages by pressing Menu button.



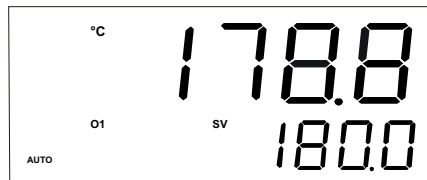
Technician can access to the following menu by entering menu changing next button.



Heating Derivative Time

Continue to press menu changing back and next buttons to change menu pages

If Menu button is pressed again, operation screen is shown.

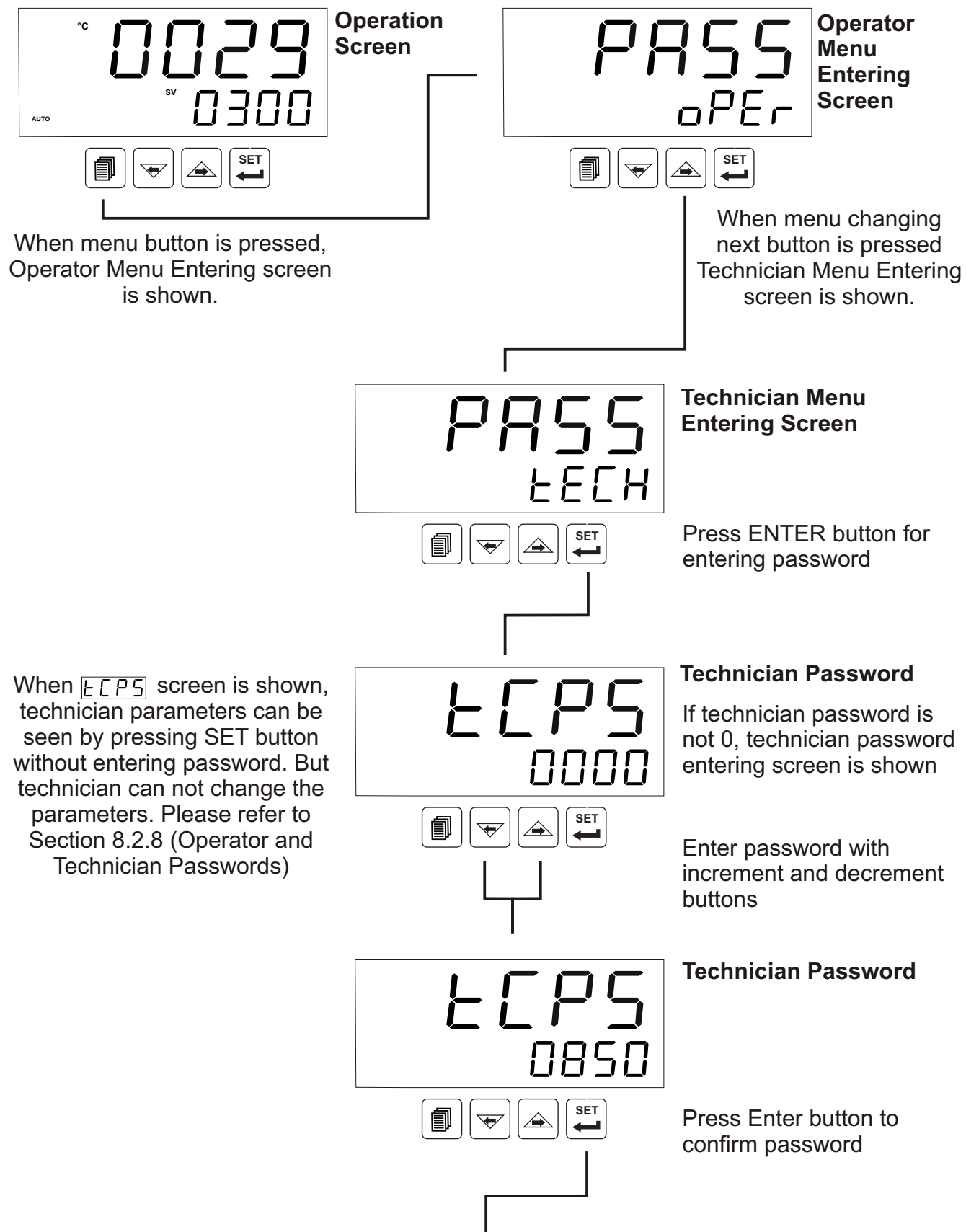


Operation Screen

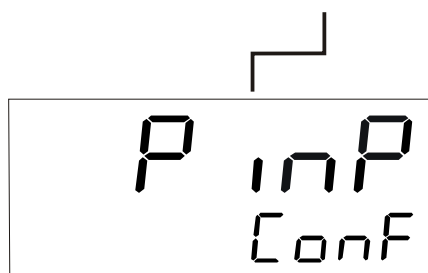
Example-3 : To change \equiv Voltage / Current Input Calibration Type Selection parameter

$\square\square\square$ In “PinP Conf” menu

$\square\square\square$ Parameter is on “PinP ConF” menu. For accessing to this parameter, technician must access to “PinP ConF” menu firstly. In this example, changing input type of a device from thermocouple to \equiv Voltage/Current and dual point calibration selection is shown.



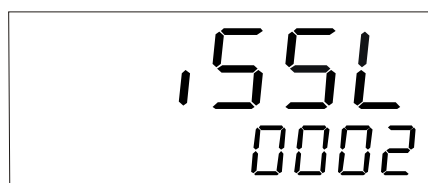
Operator can not access to this menu



PINP CONF Menu

Access to the parameters in PinP ConF menu by pressing Enter button

Operator can not access to this parameter

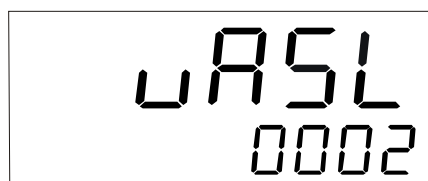


Selection of Process

For accessing to uCARL Parameter, 155L Parameter must be 2. If this parameter is not 2, change this parameter 2 with increment button.

Press Enter button to confirm the changed value and access to the following parameter.

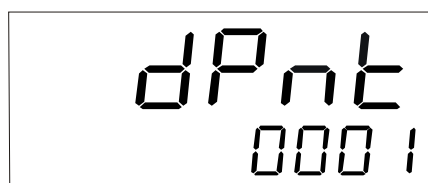
Operator can not access to this parameter



Voltage / Current Input Type selection

Technician can access to the following parameter by pressing Menu button

Operator can not access to this parameter



Decimal Point Position Selection

Technician can access to the following menu by pressing Enter button

Operator can not access to this parameter

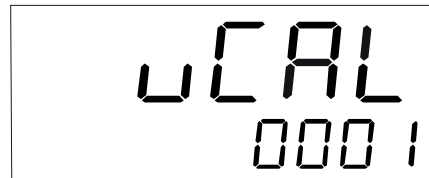


---Voltage / Current Input Calibration Type



Technician can change the parameter with increment and decrement buttons

Operator can not access to this parameter

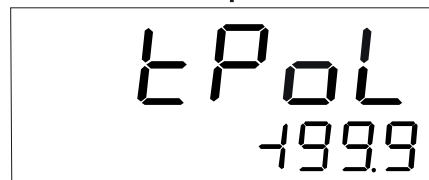


---Voltage / Current Input Calibration Type Selection



Press Enter button to confirm the changed value and access to the following parameter.

Operator can not access to this parameter

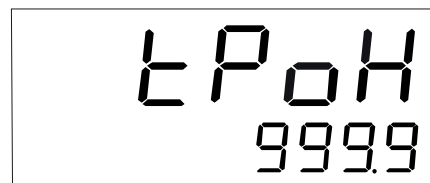
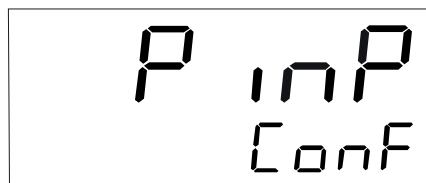


Minimum value for selectable dual point calibration



Press Enter button to confirm the changed value and access to the following parameter

PINP CONF Menu
Technician turns to Menu pages by pressing Menu button.



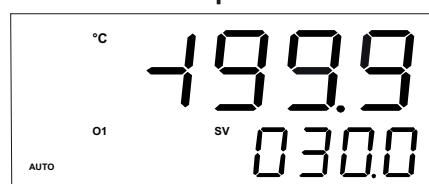
If Menu button pressed again, Operation Screen is shown.



Continue to press menu changing back and next buttons to change menu pages



Maximum value for selectable dual point calibration



Operation Screen



8. Parameters

Parameters are divided into two groups. These can be accessed by operator and technician. Also, they are grouped into subgroups according to their functions. The subgroups are named as menu pages.

8.1 Operator Parameters

SET
L.5t

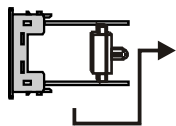
8.1.1 Process and Alarm SET Parameters

PSET

This is the device's process set value. Controlling is done according to this value by process control outputs.

Process set value can be adjusted from minimum value of set scale

5U-L To maximum value of set scale 5U-U



EMO-400
EMO-410
EMO-420

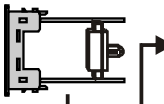
ALr 1

If EMO-400 Relay, EMO-410 SSR Driver or EMO-420 Digital (Transistor) output module is plugged in Module-1 socket and output is configured as an alarm output, this parameter defines the set value of the alarm output.

ALr 1 Set value can be adjusted from minimum value of set scale

5U-L To maximum value of set scale 5U-U

MODULE-2



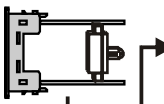
EMI-410
EMI-430
EMI-440
EMI-450

If one of the analogue input modules is plugged in Module-2 socket and measurement input selection parameter ALS1 which is explained in Section 8.2.3 for Module-1 alarm output is 0001, ALr 1 can be defined alarm set value for analogue input module in Module-2.

ALr 1 Parameter can be adjusted from minimum set value of 2nd sensor input 5UL2 to maximum set value of 2nd sensor input 5UU2. Also point position of ALr 1 parameter and measured value from analogue input module (2nd sensor input) is the same.

In this conditions, alarm output operates according to 2nd sensor input value and ALr 1 parameter.

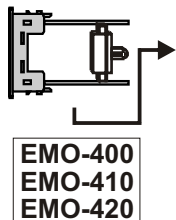
MODULE-2



EMI-420

Set value of Heating Failure Alarm

If ~CT input module (EMI-420) is plugged in Module-2 socket and Module-1 alarm type parameter ALtwh which is explained in Section 8.2.3 is 0006, ALr 1 parameter can be adjusted from 0.0 to 100.0A~

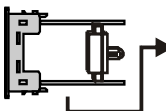


ALr2

If EMO-400 Relay, EMO-410 SSR Driver or EMO-420 Digital (Transistor) output module is plugged in Module-2 socket and output is configured as an alarm output, this parameter defines the set value of the alarm output.

ALr2 Set value can be adjusted from minimum value of set scale **SU-L** To maximum value of set scale **SU-U**

MODULE-1

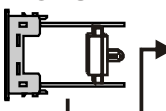


If one of the analogue input modules is plugged in Module-1 socket and measurement input selection parameter **ALS2** which is explained in Section 8.2.3 for Module-1 alarm output is **0001**, **ALr2** can be defined alarm set value for analogue input module in Module-2.

ALr2 Parameter can be adjusted from minimum set value of 2nd sensor input **SUL1** and maximum set value of 2nd sensor input **SUU1**. Also point position of **ALr2** parameter and measured value from analogue input module (2nd sensor input) is the same.

In this conditions, alarm output operates according to 2nd sensor input value and **ALr2** parameter.

MODULE-1



Set value of Heating Failure Alarm

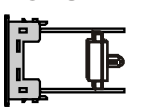
If \sim CT input module (EMI-420) is plugged in Module-1 socket and Module-1 alarm type parameter **ALT2** which is explained in Section 8.2.3 is **0006**, **ALr2** parameter can be adjusted from 0.0 to 100.0A \sim

ALr3

If OUT-3 relay output module is configured as alarm output, this parameter defines the set value of the alarm output.

ALr3 Set value can be adjusted from minimum value of set scale to maximum value of set scale

**MODULE-1
or
MODULE-2**

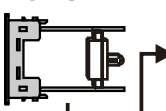


If one of the analogue input modules is plugged in Module-1 or Module-2 socket and measurement input selection parameter **ALS3** which is explained in Section 8.2.5 for Module-1 alarm output is **0001**, **ALr3** can be defined alarm set value for analogue input module in Module-1 or Module-2 socket.

ALr3 Parameter can be adjusted from minimum set value of 2nd sensor input **SUL2** and maximum set value of 2nd sensor input **SUU2**. Also point position of **ALr3** parameter and measured value from analogue input module (2nd sensor input) is the same.

In this conditions, alarm output operates according to 2nd sensor input value and **ALr3** parameter.

**MODULE-1
or
MODULE-2**



Set value of Heating Failure Alarm

If \sim CT input module (EMI-420) is plugged in Module-1 or Module-2 socket and Module-1 alarm type parameter **ALT3** which is explained in Section 8.2.5 is **0006**, **ALr3** parameter can be adjusted from 0.0 to 100.0A \sim

run
List

8.1.2 Selection of PID Tune and Operation Form

tunn

TUNE SELECTION

By selecting one of the methods below, device can determine the PID parameters.

no

Device operates according to the defined PID parameters

Auto

Auto tune (Limit Cycle Tuning) operation

Self

Self tune (Step Response Tuning) operation

Auto-Self

Auto-Self Tune

Self Tune operation is performed, if the conditions are realized when power on firstly. In normal operation, it controls the tune conditions in **Auto Tune** selection which explained below. If any of the conditions is realized, it performs the **Auto Tune** operation.

Auto

AUTOMATIC TUNE SELECTION

no

Device does not do **Auto** (Limit Cycle Tuning) operation or while **Auto** operation runs, this selection is adjusted **no** and **Auto Tune** operation is canceled.

yes

If **tunn** parameter is **Auto** or **Auto-Self**, when the conditions for Auto Tune parameter that are explained in Tune Methods section are realized, it starts to perform Auto Tune (Limit Cycle Tuning) operation.

TUNE METHODS :

There are 2 different methods for determining PID parameters by the device. These are **Auto tune** (Limit Cycle Tuning) and **Self Tune** (Step Response Tuning) methods.

Determining of PID parameters with **Auto Tune** is started in these conditions :

1- By the user in any time,

2- By the device when system gets unstable and starts oscillation

If process value is out of **Set ± Process value stabilisation** **Set** value (Please refer to Section 8.2.2) and starts to oscillate, then device changes the **Auto** Parameter to **yes** and Auto Tune operation is started.

3- After changing set value, if difference between newly defined set value and former set value is greater than proportional band, device will start it.

If set value is changed to a value that is greater than;

$\pm [\text{Scale} * (\text{Heating or Cooling Proportional Band})] / 1000$ value,

Auto Parameter is adjusted **yes** by the device and **Auto Tune** operation is started.



For Auto Tune (Limit Cycle Tuning) operation :

1- Tune selection parameter **tunn** in “run List” menu must be selected **Auto** **Auto tune** or **Auto-Self** **Auto-Self tune** .

2 - For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.

3 - If process set value is changed while Tune operation is being performed, Tune operation is canceled

Example -1 : Starting Auto Tune operation by the user ;

- Enter operator or technician menu.
- Adjust tune selection parameter `ETnn` in "run List" menu , **Auto Tune** `ATun` Or **Auto-Self Tune** `ATSE`
- Adjust automatic tune selection parameter `ATEn` in "run List" menu `YES` And return to main operation screen.
- Observe that "AT" led is active.

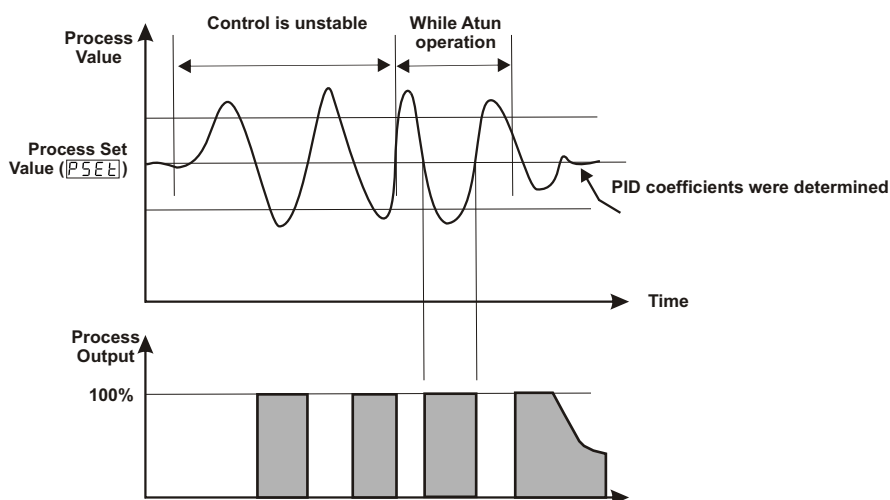
If **Auto Tune** operation finishes without any problem, device saves the PID coefficients to memory and continue to run. `ATEn` Parameter is adjusted `no` automatically.

Canceling **Auto Tune** operation:

- 1- If sensor breaks ;
 - 2- If **Auto Tune** operation can not be completed in 8 hours
 - 3- If user adjusts `ETnn` parameter `no` or `SEun`
 - 4- If user adjusts `ATEn` parameter `no`
 - 5- If process set value is changed while Tune operation is being performed
 - 6- While Tune operation is being performed, if operation type selection is changed as "Manual" when it is "Automatic" (If operation type selection is changed as "Automatic" when it is "Manual", then Tune operation is started again)
 - 7- If output function is changed while Tune operation is being performed (Heat \square Cool, Cool \square Heat)
 - 8- While Tune operation is being performed, if control form is changed as "ON/OFF" when it is "PID" (If control form is changed as "PID" when it is "ON/OFF", the Tune operation is started again)
- Auto Tune is canceled. Then, without doing any changes in PID parameters and `ATEn` Parameter, device continues to run with former PID parameters.

Auto Tune (Limit Cycle Tuning) operation ;

Process control output runs according to heating if heating or heating-cooling function and PID control form is selected,
Process control output runs according to cooling if cooling function and PID control form is selected.



For Auto Tune (Limit Cycle Tuning) operation :

- 1- Tune selection parameter `ETnn` in "run List" menu must be selected `ATun` **Auto tune** or `ATSE` **Auto-Self tune** .
- 2 - For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD, PID.
- 3 -If process set value is changed while Tune operation is being performed, Tune operation is canceled

Self Tune (Step Response Tuning) :

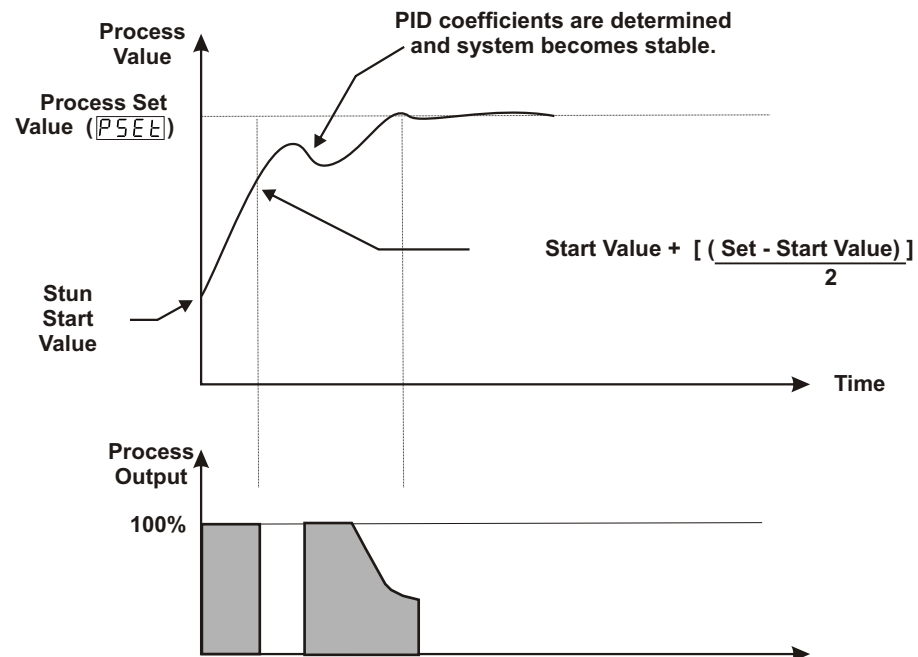
When power is on, while process value starts to change for being equal to process set value, PID parameters are determined by the device with **Self Tune** method. For starting **Self Tune (Step Response Tuning)** operation firstly power the device off and then on. Also difference between process value and set value must be too much.

Example 2 : Determination of PID parameters with Self Tune method

- Enter operator or technician menu
- Select tune selection parameter `tunn` in "run List" menu `Stun` or `AtSt` and turn to operation screen.
- Power off the device.
- Wait system to be in first conditions.
(For example : Decreasing of the temperature to ambient temperature while controlling the temperature)
- Apply power to the device
- See that "AT" led is active

If heating or heating-cooling function and PID control form is selected for the system;

If set value is greater than process value, process output becomes active till to the **Temperature + [(Set - Temperature) / 2]** value. When process value reaches to this value, process output reduces to 0% and it calculates the PID coefficients.



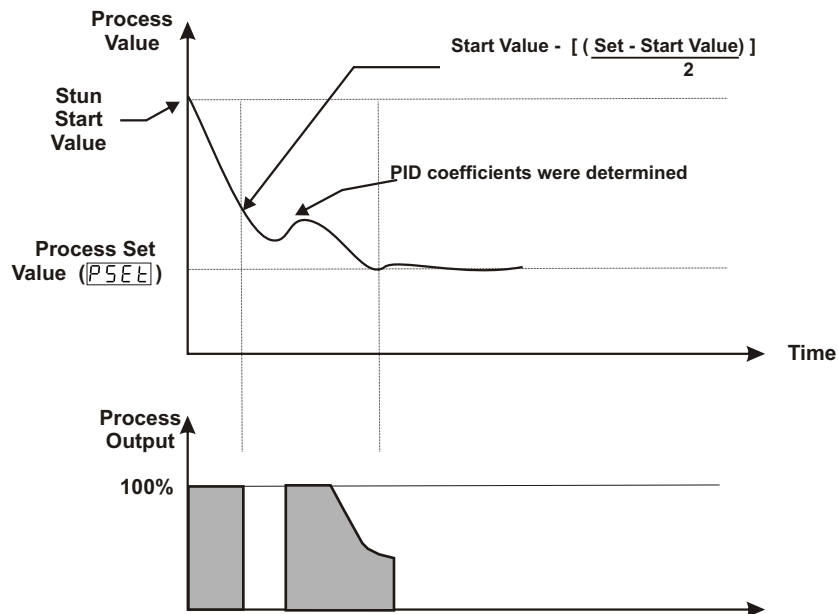
If cooling function and PID control form is selected for the system;

If set value is less than process value, process output becomes active till to the **Temperature - [(Set - Temperature) / 2]** value. When process value reaches to this value, process output is reduced to 0% and it calculates PID coefficients.



For Self Tune (Step Response Tuning) operation :

- 1 - Tune selection parameter `tunn` in "run List" menu must be selected **Self tune** `Stun` Or **Auto-Self Tune** `AtSt`
- 2 - For **Self Tune (Step Response Tuning)** operation, firstly power off and then apply power to the device.
- 3 - For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.
- 4- If process set value is changed while Tune operation is being performed, Tune



If **Self Tune** operation is finished without any problem, device saves new PID parameters to memory and runs. It changes `tunn` parameter.

If `tunn` parameter is `Stun` it is changed to `no`, if it is `RelSt`, it is changed to `Relun`

If **Self Tune** operation is interrupted at half, PID parameters and `tunn` parameter are not changed, device continues to run with former PID parameters. When power is off and then on, device starts to complete the **Self Tune** operation.

Canceling **Self Tune** operation :

- 1- If sensor breaks ;
- 2- If **Self Tune** operation can not be completed in 8 hours ;
- 3- While heating **Self Tune** operation is running, if process value becomes greater than Set value ;
- 4- While cooling **Self Tune** operation is running, if process value becomes less than Set value ;
- 5- If user selects `tunn` parameter `no` or `Relun`
- 6- If process set value is changed while Tune operation is being performed
- 7- While Tune operation is being performed, if operation type selection is changed as "Manual" when it is "Automatic"
- 8- If output function is changed while Tune operation is being performed (Heat \square Cool, Cool \square Heat)
- 9- While Tune operation is being performed, if control form is changed as "ON/OFF" when it is "PID" (If control form is changed as "PID" when it is "ON/OFF", the Tune operation is started again)

Self Tune operation is canceled. Then device continues to run with former PID parameters without changing PID parameters.



For Self Tune (Step Response Tuning) operation :

- 1 - Tune selection parameter `tunn` in "run List" menu must be selected **Self tune** `Stun` Or **Auto-Self Tune** `RelSt`
- 2 - For **Self Tune (Step Response Tuning)** operation, firstly power off and then apply power to the device.
- 3 - For being started Tune operation (Auto Tune or Self Tune) control form must be P, PI, PD or PID.
- 4 - If process set value is changed while Tune operation is being performed, Tune operation is canceled

Auto OPERATION FORM SELECTION

Auto **Automatic Operation (Close-Loop Control)**
Device controls the process outputs by calculating the %output value automatically. (If there is a PID or ON/OFF output)

n r A n **Manual Operation (Open-Loop Control)**
In PID control formed systems, user can adjust %output value with increment and decrement buttons.
In ON/OFF control formed systems, user can adjust %output value "OFF", "HEAT" or "COOL" with decrement and increment buttons.
If manual operation form is selected, %output value is shown on bottom display whatever **b d S P** parameter is selected.

r S S L RAMP / SOAK CONTROL

o f f Ramp / Soak function is not active.

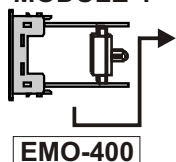
r u n Ramp / Soak function is active

H o l d Ramp / Soak function is paused.
Process set value becomes constant at last value and ramp or soak time does not take into consideration.



As explained in Section 8.1.4, when Soft-Start parameter **S t r A** is active, Ramp/Soak control parameter **r S S L** has no effect.

MODULE-1



U L S L MOTORIZED VALVE CONTROL

It defines motorized valve control form. Module-1 output operates for opening the valve, Output-3 operates for closing the valve.
If Module-1 is relay output, motorized valve control parameter **U L S L** is shown even motorized valve control is not used. If motorized valve control is used, Module-2 output can not be used as PID.

n o Motorized valve control is not active.

H E A T Motorized valve runs with heating PID

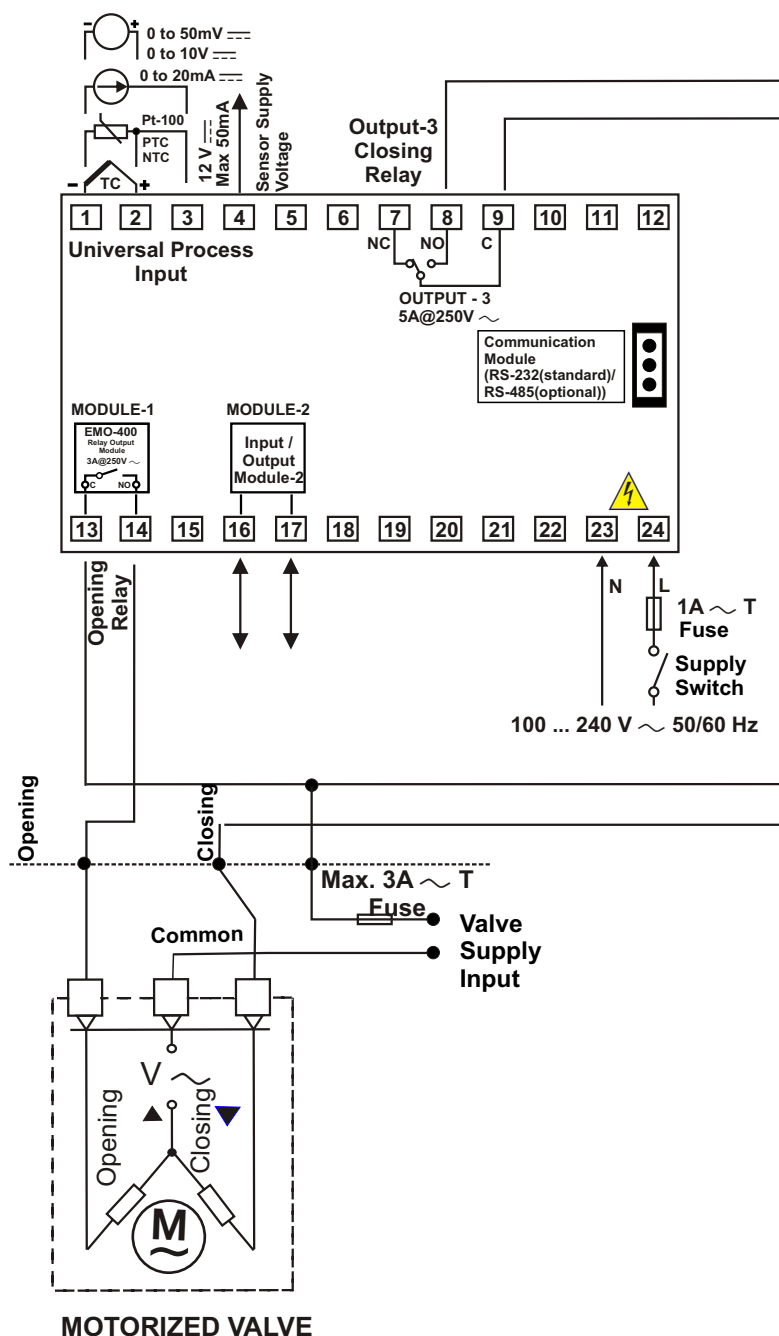
C o o l Motorized valve runs with cooling PID



Motorized valve control parameter must not be changed, if there is an electrical wiring.

Motorized valve control can be performed with UL5L parameter. For doing this operation, EMO-400 Relay output module must be plugged in Module-1 socket. Module-1 and output-3 controls the position of the valve with motorized valve control.

Motorized Valve Control Electrical Wiring Diagram for ESM-4950.1.20.1.1/01.00



RELEVANT PARAMETERS:

In PASS OPER or PASS tECH ☐ (run LiSt) menu page ;

UL5L **Parameter**: It defines how to perform the motorized valve control with the device.

If motorized valve control is activated by selecting the UL5L parameter

HERE Or COOL

In PASS tECH ☐ GEnn COnF menu page UL5E and ULH4 parameters are shown.

UL5E **parameter** : It can be adjusted from 5 to 600. The unit is "second".

It defines after how many seconds valve is completely opened. For determining the parameter correctly, close the valve manually. Be sure that valve is closed completely, then open it manually without stopping and measure that how many seconds have passed for opening it completely. Parameter must be entered measured value+5% of measured value and as second.

ULH4 **parameter** : It can be adjusted from 0,1 to 5,0. Unit is %. It is % of ULt parameter. Minimum movement steps of valve while opening or closing are determined as % ratio. If valve oscillates while controlling, INCREASE the parameter value!

bPLe

BUMPLESS TRANSFER

no

Process output value in manual control is not taken into consideration while passing from manual control to automatic control. New control output that is measured in automatic control is applied to process output.

Last %output value is taken output value of manual control and manual control continues while passing from automatic control to manual control.

YES

While passing from manual control to automatic control, last process output value in manual control is accepted as first process output value in automatic control and automatic control continues to run.

Last % process output value in automatic control is accepted as process output value of manual control and manual control continues to run.

LeCC

ALARM LATCH CANCELING

no

Alarm latch canceling is not performed.

YES

If there is an alarm output with latching and there is no alarm status, latching operation will be finished by the device. When it is finished, this parameter becomes ☐no Automatically.

d,SP
L,St

8.1.3 Function Selection for Top and Bottom Display

tdSP

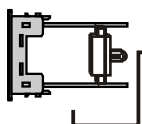
It defines the function of the top display. This parameter determines which value is shown in top display.

0000

Process value (PV) is shown in top display.

0001

Result of subtraction of process set value from process value (SV-PV) is shown in top display.



0002

If one of the analogue input modules is plugged in Module-1 or Module-2 socket, measured value from this module input is shown in top display.

EMI-410
EMI-430
EMI-440
EMI-450

bdSP

It defines the function of the bottom display. This parameter determines which value is shown in bottom display.

0000

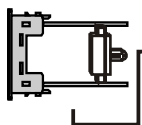
Process set value (SV) is shown in bottom display.

0001

%Output value that is applied to process control output is shown in bottom display.

0002

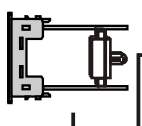
Status of the Ramp/Soak function is shown in bottom display.



0003

If one of the analogue input modules is plugged in Module-1 or Module-2 socket, measured value from this module input is shown in top display.

EMI-410
EMI-430
EMI-440
EMI-450



0004

If ~CT input module (EMI-420) is plugged in Module-1 or Module-2 socket, measured value from this module input is shown in bottom display.

EMI-420



In 'Run List' menu Section 8.1.2, if operation form is Auto, then bdSP parameter is considered. If operation form is rrrr, %output value is shown in bottom display whatever bdSP parameter is.

r n 7 P
SoA

8.1.4 Configuration of RAMP/SOAK Function and Step SET Values

St r A

Soft-Start parameter.

When the power is applied to the device, process value reaches to the set value at the end of this time. It can be adjusted from 0 to 99 hours 59 minutes.

When the power is applied to the device, if this parameter is 0, St r A Ramp function is not active.

r St o

Ramp / Soak Tolerance parameter. It can be adjusted from 0% to 50% of scale. In Ramp/Soak operation, if process value is out of the tolerance that is defined with this parameter, then time is stopped. To continue to count the Ramp/Soak time, process value must be between tolerances which are determined with this parameter. If parameter is 0, this function is not active.

r St y

Ramp/Soak program step selection parameter.

One program with 8 steps or two different programs with 4 steps can be defined.

0000

1.program 1-4 steps

0001

2.program 5-8 steps

0002

Steps between 1-8 is used as one program.

PU - 1

Ramp/Soak step set value.

-
-
-
-
-
-

For ramp operation ; process value reaches to step set values that are defined with these parameters at the end of the time that are defined in ramp time parameters.

For soak operation ; process value is constant in step set value that are defined in these parameters for time that are defined in soak time parameters.

Ramp/Soak step set values can be adjusted from minimum value of set scale St U - L to maximum value of set scale St U - U

PU - 8

t r - 1

Ramp time for Ramp/Soak

-
-
-
-

Process value reaches to step set values at the end of the time that are defined in these parameters.

It can be adjusted 0 to 99 hours 59 minutes

t r - 8

t S - 1

Soak time for Ramp/Soak

-
-
-
-

Process value is constant in step set value for time that are defined in these parameters.

It can be adjusted 0 to 99 hours 59 minutes.

t S - 8

RAMP ACTION DURING POWER ON (SOFT-START)

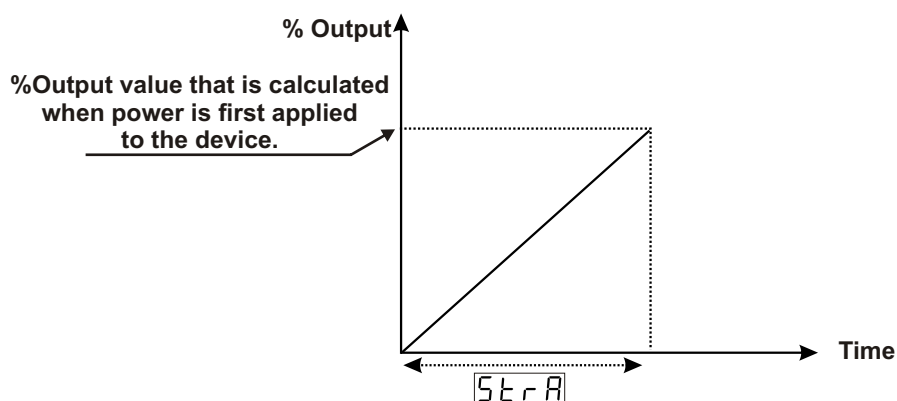
If $\boxed{S\boxed{t}\boxed{r}\boxed{A}}$ parameter is different from $\boxed{0000}$ and selection of operation form parameter is $\boxed{R\boxed{u}\boxed{t}\boxed{a}}$, Then Soft-Start starts to run. Ramp led blinks. By increasing the process output for $\boxed{S\boxed{t}\boxed{r}\boxed{A}}$ Parameter, process output reaches to the %output value that is measured when power first applied to the device at the end of the $\boxed{S\boxed{t}\boxed{r}\boxed{A}}$ time. When Soft-Start operation finishes, if operation form of the device is $\boxed{R\boxed{u}\boxed{t}\boxed{a}}$, device continues to run from $\boxed{P\boxed{S}\boxed{E}\boxed{t}}$ value.

If selection of operation form parameter is adjusted as $\boxed{n\boxed{r}\boxed{A}\boxed{n}}$

If $\boxed{S\boxed{t}\boxed{r}\boxed{A}}$ time is adjusted to a value that is less than the counted value or $\boxed{0000}$

If there is a sensor break failure

Then Soft-Start operation is canceled.



RAMP/SOAK IN NORMAL OPERATION :

Whatever operation form parameter is ; Normal Ramp/Soak operation is started by selecting $\boxed{r\boxed{S}\boxed{S}\boxed{L}}$ parameter $\boxed{r\boxed{u}\boxed{n}}$. Ramp led becomes active. Ramp/Soak operation can be paused by selecting $\boxed{r\boxed{S}\boxed{S}\boxed{L}}$ parameter $\boxed{H\boxed{o}\boxed{L}\boxed{d}}$. Ramp/Soak operation can be canceled by selecting $\boxed{r\boxed{S}\boxed{S}\boxed{L}}$ Parameter $\boxed{o\boxed{F}\boxed{F}}$

While Ramp / Soak operation continues, if $\boxed{r\boxed{S}\boxed{E}\boxed{Y}}$ parameter is $\boxed{0000}$ 1-4 numbered, if it is $\boxed{0001}$ 5-8 numbered, if it is $\boxed{0002}$, 1-8 numbered steps run.

When Ramp/Soak operation finishes, device operates in operation form which operation form device has before Ramp/Soak operation. ($\boxed{n\boxed{r}\boxed{A}\boxed{n}}$ Or $\boxed{R\boxed{u}\boxed{t}\boxed{a}}$)

If selection of operation form parameter before starting to Ramp/Soak operation is $\boxed{R\boxed{u}\boxed{t}\boxed{a}}$ then device continues to run from $\boxed{P\boxed{S}\boxed{E}\boxed{t}}$ set value.

If any Ramp time or Soak time is $\boxed{0000}$, then relevant ramp or soak step is skipped.

Ramp/Soak operation is canceled

If there is a sensor break failure, while Ramp/Soak operation is running or if power off while Ramp/Soak operation is running.

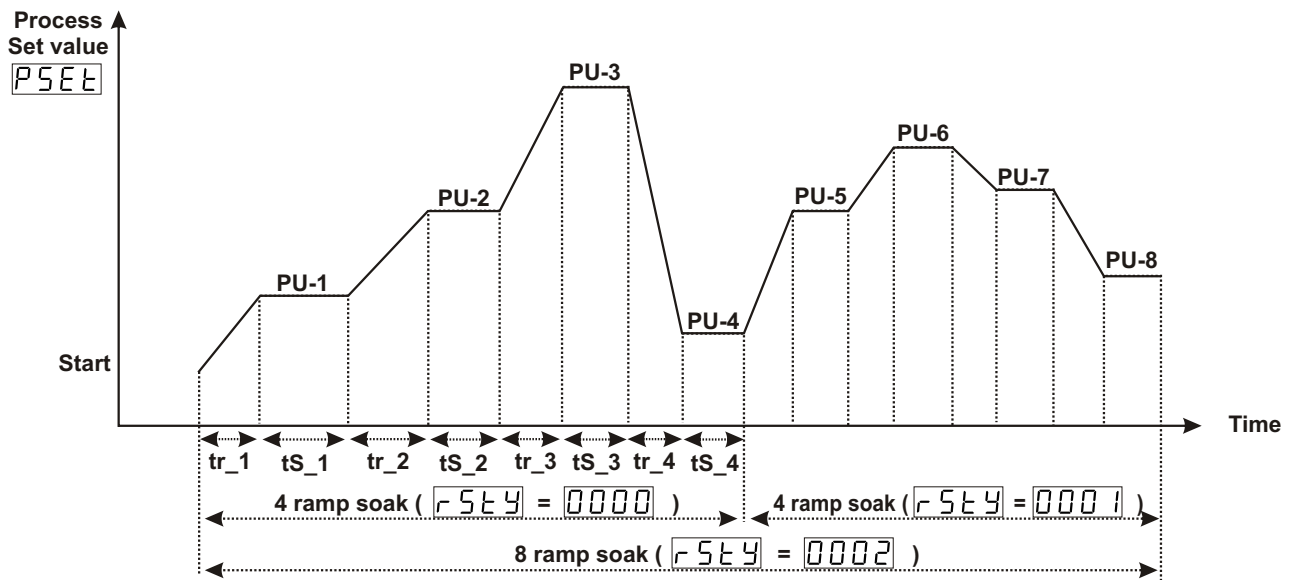


While any Ramp/Soak function is running, changing relevant time set value can cause unexpected effects in set value and process output.



If Ramp / Soak tolerance parameter $\boxed{r\boxed{S}\boxed{t}\boxed{a}}$ is $\boxed{0000}$, then it has no function. When it is different from 0 (While Ramp/Soak is running);

If (Calculated SET - $\boxed{r\boxed{S}\boxed{t}\boxed{a}}$) < Process Value < (Calculated SET + $\boxed{r\boxed{S}\boxed{t}\boxed{a}}$) condition is not true (process value is out of the tolerance), time counting is stopped till the condition is true.



Example : If Ramp / Soak step set , ramp time and soak time parameters

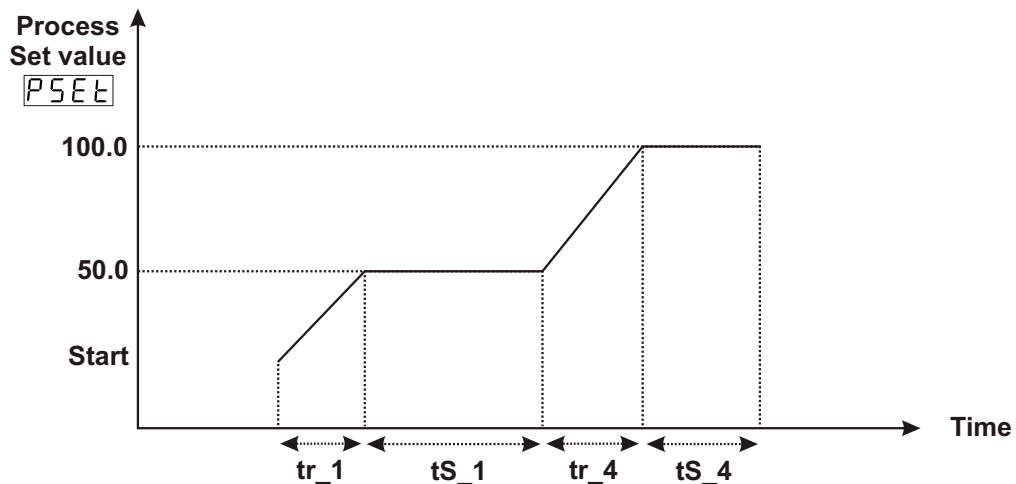
$PU-1 = 0500$, $tr-1 = 0050$, $tS-1 = 0140$;

$PU-2 = 0700$, $tr-2 = 0000$, $tS-2 = 0000$;

$PU-3 = 0900$, $tr-3 = 0000$, $tS-3 = 0000$;

$PU-4 = 1000$, $tr-4 = 0100$, $tS-4 = 0100$; are adjusted as on the left

Device operates as shown below:



8.2 Technician Parameters

P_{inP}
Conf

8.2.1 Process Input Type and Relevant Parameters with Process Input

155L

Defines the process input type.

0000

TC input type selection

0001

RTD input type selection

0002

---Voltage/Current input type selection.

155L

0000

155L

Defines type and scale of the thermocouple for TC input. It is active if TC input type is selected.

0000

L (-100°C;850°C) or (-148°F;1562°F)

0001

L (-100.0°C;850.0°C) or (-148.0°F;999.9°F)

0002

J (-200°C;900°C) or (-328°F;1652°F)

0003

J (-199.9°C;900.0°C) or (-199.9°F;999.9°F)

0004

K (-200°C;1300°C) or (-328°F;2372°F)

0005

K (-199.9°C;999.9°C) or (-199.9°F;999.9°F)

0006

R (0°C;1700°C) or (32°F;3092°F)

0007

R (0.0°C;999.9°C) or (32.0°F;999.9°F)

0008

S (0°C;1700°C) or (32°F;3092°F)

0009

S (0.0°C;999.9°C) or (32.0°F;999.9°F)

0010

T (-200°C;400°C) or (-328°F;752°F)

0011

T (-199.9°C;400.0°C) or (-199.9°F;752.0°F)

0012

B (44°C;1800°C) or (111°F;3272°F)

0013

B (44.0°C;999.9°C) or (111.0°F ; 999.9°F)

0014

E (-150°C;700°C) or (-238°F;1292°F)

0015

E (-150.0°C;700.0°C) or (-199.9°F;999.9°F)

0016

N (-200°C;1300°C) or (-328°F;2372°F)

0017

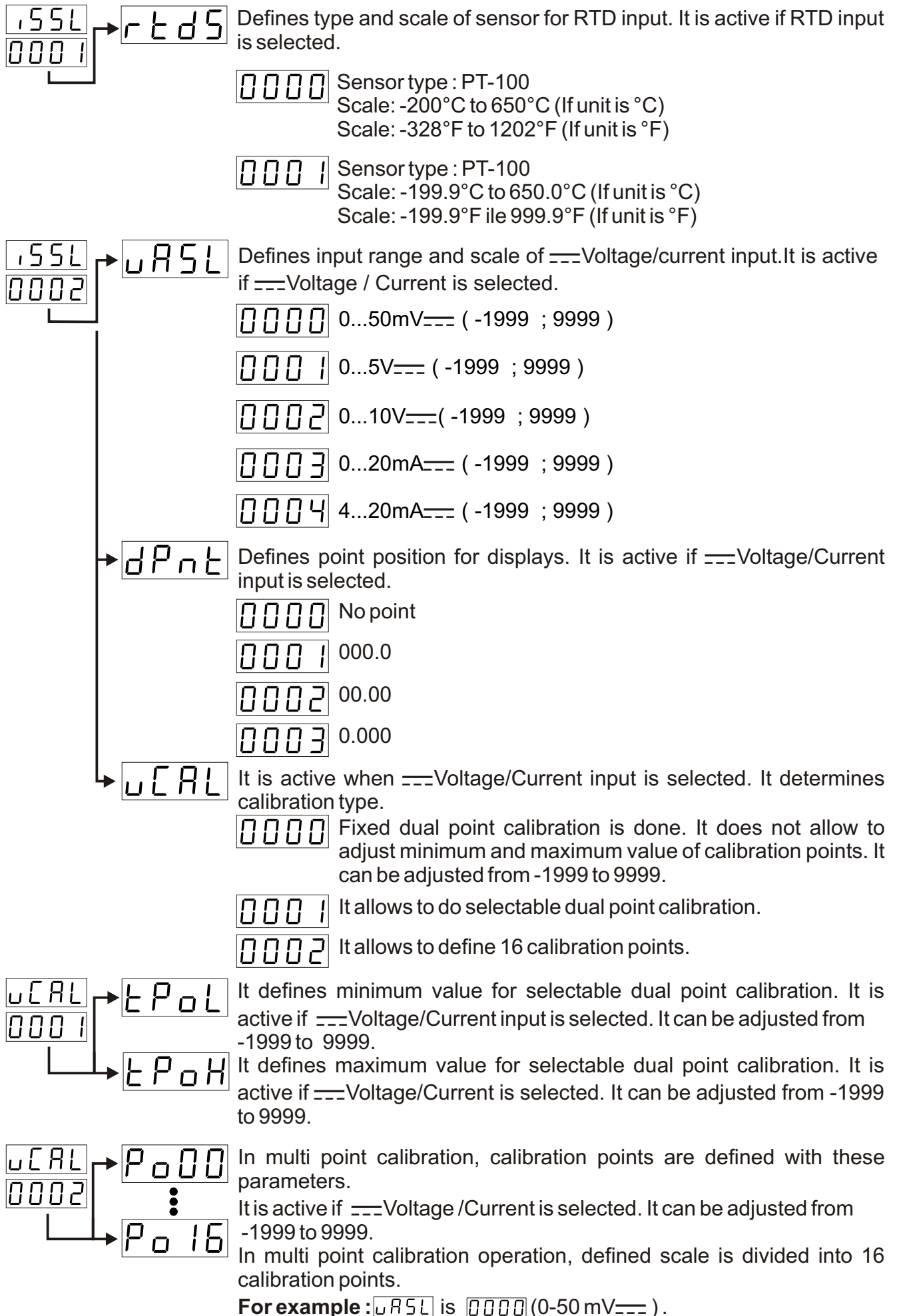
N (-199.9°C;999.9°C) or (-199.9°F;999.9°F)

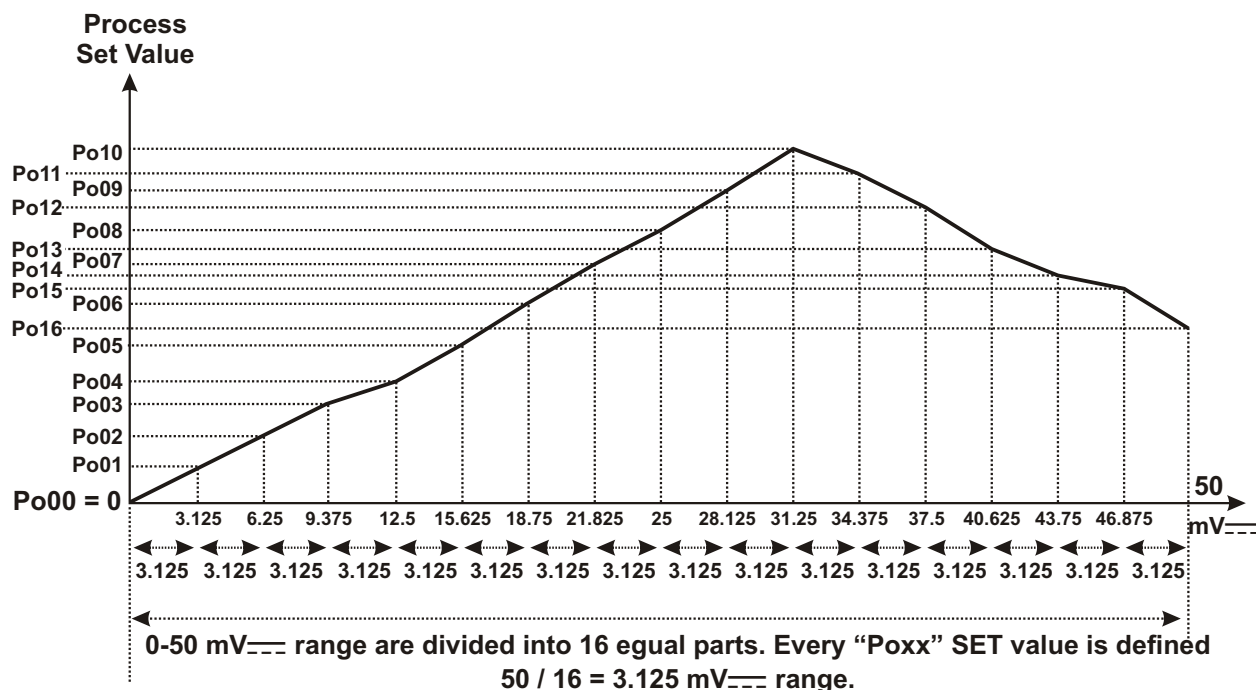
0018

C (0°C;2300°C) or (32°F;3261°F)

0019

C (0.0°C;999.9°C) or (32.0°F;999.9°F)





COEF Coefficient value for $\text{---Voltage / Current input}$. Process value is multiplied with this value.
It is active if $\text{---Voltage / Current input}$ is selected. It can be adjusted 1.000 to 9.999.

unit Unit selection
☐ °C Unit is °C
☐ °F Unit is °F

U Unit is U. It is active if $\text{---Voltage / Current input}$ is selected
☐ - No unit. It is active if $\text{---voltage / Current input}$ is selected

LoL Minimum value of operating scale. It can be changed according to input type and scale of the process.

uPL Maximum value of operating scale. It can be changed according to input type and scale of the process.

PUoF Display offset for process value. It can be adjusted -10% to +10% of scale. The defined value is added to process value.

FLT Defines filter time for input signal. It can be adjusted from 0.0 to 900.0.

CJnC It is active if process input is selected TC input. It decides if cold junction compensation is active or not.

YES Cold junction compensation is active.

no Cold junction compensation is not active.

8.2.2 PID Configuration Parameters

If any output is configured as heating PID ;

$P-Ht$, $I-Ht$, $d-Ht$, $Cl-H$, $oLLH$, $ouLH$, $oLtH$, Rr , $SUoF$, $PoFS$, $PoSS$, $Strn$, $o-db$, $Sbou$ parameters are visible.

If any output is configured as cooling PID ;

$CcOE$, $P-Cl$, $I-Cl$, $d-Cl$, $Cl-C$, $oLLC$, $ouLC$, $oLtC$, Rr , $SUoF$, $PoFS$, $PoSS$, $Strn$, $o-db$, $Sbou$ parameters are visible.

If no output is configured as PID ;

Only $o-db$, $Sbou$ parameters are visible in PID CONF menu.

IF
1oP1
OR
1oP2
OR
out3
Conf
↓
HEAT
AND
↓
Pid
IS
SELECTED

$P-Ht$ HEATING PROPORTIONAL BAND (000.0% , 999.9%)

Full Scale (uPL - LoL) %.

If uPL = 1000 °C, LoL = 0 °C and $P-Ht$ = 50.0 then

Proportional Band = (uPL - LoL) * $P-Ht$ / 100.0

Proportional Band = (1000-0)*50.0/100.0 = 500 °C

$I-Ht$ HEATING INTEGRAL TIME (0000 sec, 3600 secs)

It can be changed by the user. When Tune operation stops, it can be changed by the device. If it is 0, integral control part does not run. When tune operation stops if this parameter is 0, this parameter can not be changed because of integral control part does not run.

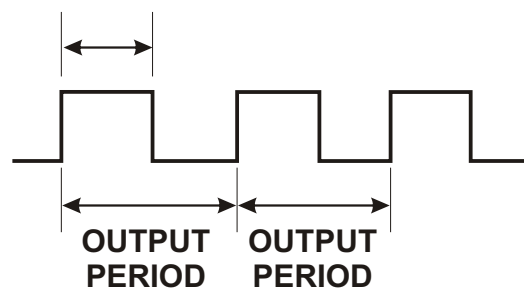
$d-Ht$ HEATING DERIVATIVE TIME (000.0 sec, 999.9 secs)

It can be changed by the user. When Tune operation stops, it can be changed by the device. If it is 0, derivative control part does not run. When tune operation stops if this parameter is 0, this parameter can not be changed because of derivative control part does not run.

$Cl-H$ CONTROL PERIOD FOR HEATING OUTPUT (1 sec, 150 secs)

It is control period for heating. While motorized valve control runs, if $ULSL$ Is heat or cool, this parameter is not visible.

OUTPUT : ON



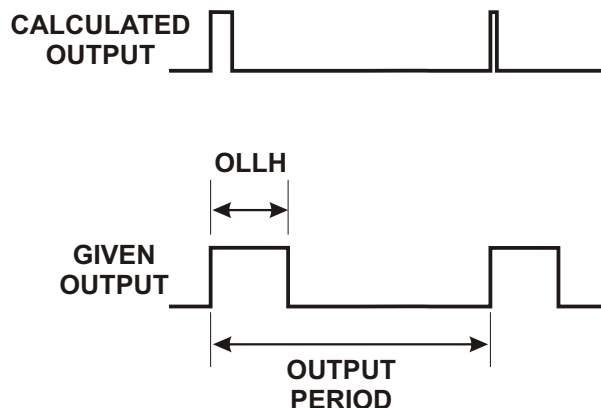
Relay Output : Output period must be short for stable process control. Relay must not be used in short output periods because of limited life of their relay contact (number of open/close events). Relay output must be used as control output in values near to 30 seconds or higher than this value.

SSR Output : If short output period is needed in a system (approximately 1-2 seconds) SSR driver output module as last control element is recommended.

IF
 10P1
 OR
 10P2
 OR
 out3
 Conf
 ↓
 HEAT
 AND
 ↓
 Pid
 IS
 SELECTED

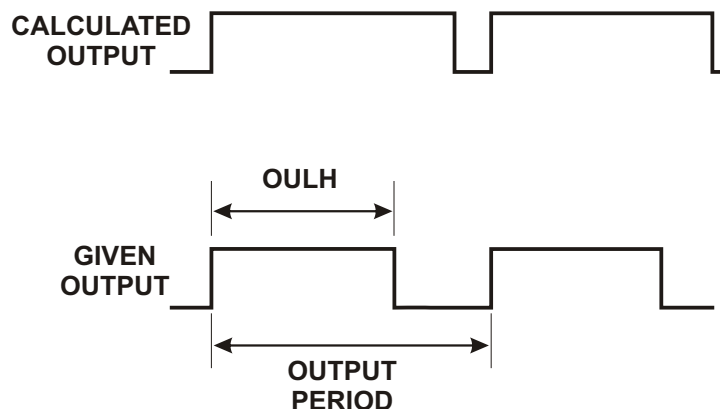
OLLH HEATING MINIMUM CONTROL OUTPUT (0.0% , OULH)

It is % of heating minimum output. If heating and cooling PID control functions operate together, this parameter is not considered. Even as a result of the heating PID calculation device calculates the % output value less than this parameter, heating output is active minimum for OLLH parameter.



OULH HEATING MAXIMUM CONTROL OUTPUT (OLLH , 100.0%)

It is % of heating maximum output. Even as a result of the heating PID calculation device calculates the % output value greater than this parameter, heating output is active maximum for OULH parameter.



OLtH HEATING MINIMUM CONTROL OUTPUT TIME (0.0 sec , CL-H)

Heating output can not be active less than this parameter. Even if this parameter is 0, this parameter is accepted 50 msecs for security. While motorized valve control is running if UL5L parameter is selected heating or cooling, this parameter is not accessible.

IF
 10P1
 OR
 10P2
 OR
 out3
 Conf
 ↓
 Cool
 AND
 ↓
 Pid
 IS
 SELECTED

CCoE

COOLING PROPORTIONAL BAND COEFFICIENT (0.0 , 100.0)

If heating and cooling PID is used in a system, tune operation is performed by heating output. Cooling proportional parameter $P-CL$ is calculated with heating proportional band value $P-HL$ and coefficient $CCoE$.

$$P-CL = P-HL * CCoE / 100.0$$

Example : If heating and cooling PID is used in a system at the end of the tune operation,

If $P-HL = 10.0\%$ and $CCoE = 50.0$ then

$$P-CL = P-HL * CCoE / 100.0 = 10.0 * 50.0 / 100.0 = 5.0\%$$

Note: It is recommended that cooling proportional band coefficient if cooling is done with air 100.0, with oil 80.0, with water 40.0 is accepted.

P-CL

COOLING PROPORTIONAL BAND (000.0% , 999.9%)

Full Scale ($uPL - LoL$) %

If $uPL = 1000\text{ }^{\circ}\text{C}$, $LoL = 0\text{ }^{\circ}\text{C}$ and $P-CL = 50.0$ then

$$\text{Proportional Band} = (uPL - LoL) * P-CL / 100.0$$

$$\text{Proportional Band} = (1000-0)*50.0/100.0 = 500\text{ }^{\circ}\text{C}$$

I-CL

COOLING INTEGRAL TIME (0000 sec, 3600 secs)

It can be changed by the user. When tune operation finishes, it can be changed by the device. If it is 0, integral control part does not perform. When tune operation finishes if this parameter is 0, it can not be changed because integral control part does not perform.

d-CL

COOLING DERIVATIVE TIME (000.0 sec, 999.9 secs)

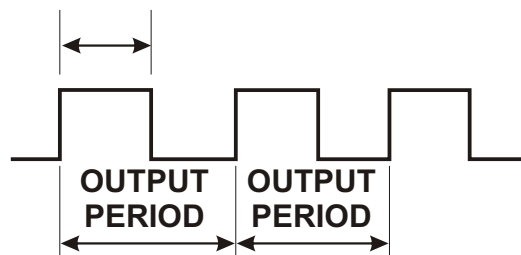
It can be changed by the user. When tune operation finishes, it can be changed by the device. If it is 0, derivative control part does not perform. When tune operation finishes if this parameter is 0, it can not be changed because derivative control part does not perform.

CL-CL

COOLING OUTPUT PERIOD TIME (1 sec, 150 secs)

It is control period of cooling output. While motorized valve control is running, if $ULSL$ is selected heating or cooling, this parameter is not visible.

OUTPUT : ON



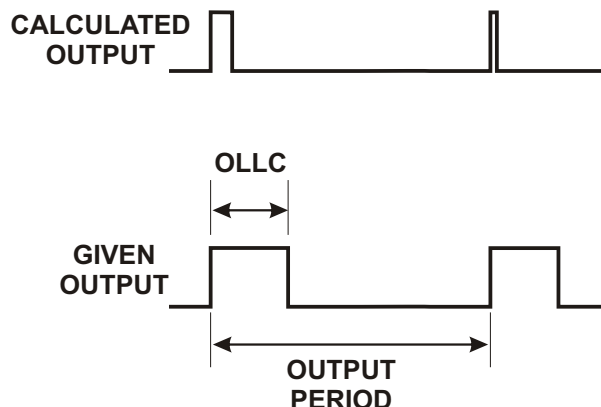
Relay Output : Output period must be short for stable process control. Relay must not be used in short output periods because of limited life of their relay contact (number of open/close events). Relay output must be used as control output in values near to 30 seconds or higher than this value.

SSR Output : If short output period is needed in a system (approximately 1-2 seconds) SSR driver output module as last control element is recommended.

IF
ioP1
OR
ioP2
OR
out3
[Conf]
↓
[Cool]
AND
↓
Pid
IS
SELECTED

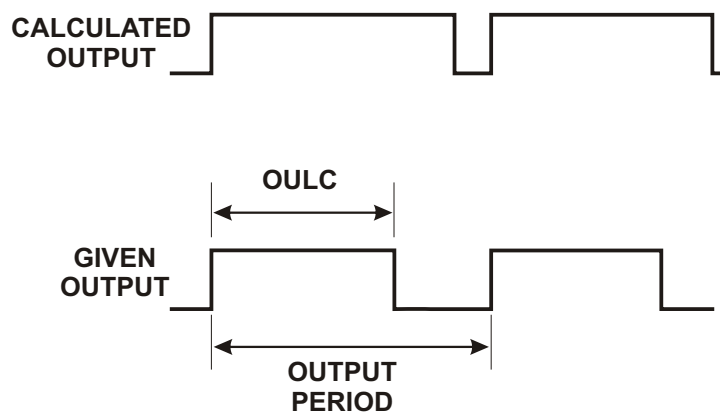
oLLC COOLING MINIMUM CONTROL OUTPUT (0.0% , ouLC)

It is % of cooling minimum output. If heating and cooling PID control functions operate together, this parameter is not considered. Even as a result of the cooling PID calculation device calculates the output value less than this parameter, cooling output is active minimum for OLLC parameter.



ouLC COOLING MAXIMUM CONTROL OUTPUT (oLLC , 100.0%)

It is % of cooling maximum output. Even as a result of the cooling PID calculation device calculates the output value greater than this parameter, cooling output is active maximum for OULC parameter.



oLlC COOLING MINIMUM CONTROL OUTPUT TIME (0.0 sec , Ct-C)

Cooling output can not be active less than this parameter. Even if this parameter is 0, this parameter is accepted 50 msecs for security. While motorized valve control is running if UL5L parameter is selected heating or cooling, this parameter is not accessible.

Ar

ANTI-RESET WINDUP (0, SCALE HIGH POINT)

While PID operation is running if

$PSET - Ar \leq \text{process value} \leq PSET + Ar$ condition is true, integral value is calculated. If the condition is not true, integral value is not calculated and last calculated integral value is used.

Scale High Point : Maximum process input value in Pt-100 and Tc inputs

9999 for fixed dual point calibration used inputs,

Scale high point is the biggest one from $EPoL$ or $EPoH$ for selectable dual point calibration used inputs

Scale high point is the biggest one from $Po00$ or $Po16$ for multi point calibration used inputs

Note: Point position changes according to process input type and scale,

Unit changes according to the selection in this $unit$ parameter.

IF
10P1
OR
10P2
OR
out3
Conf

HEAT
OR
Cool

Pid
IS
SELECTED

SUoF

SET VALUE OFFSET

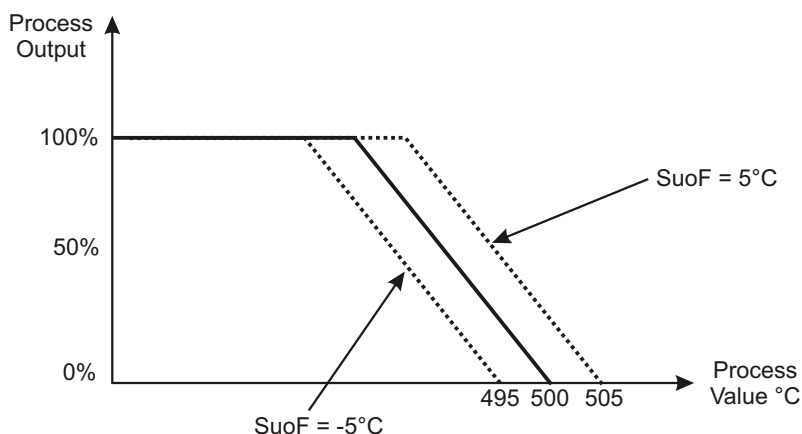
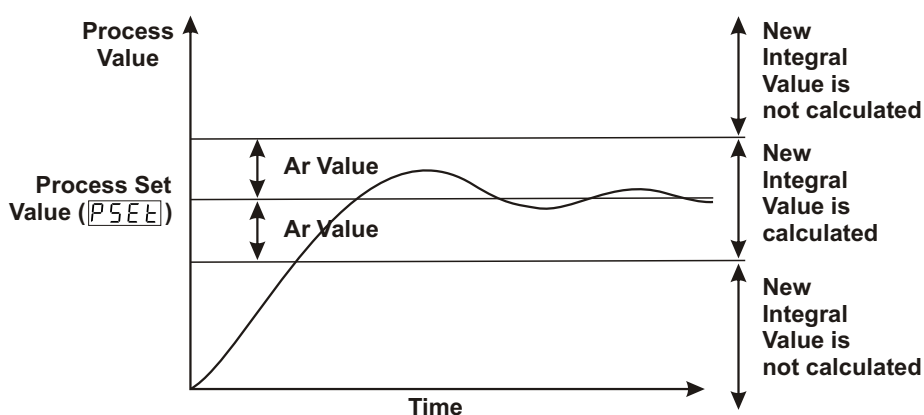
$((-SCALE\ HIGH\ POINT / 2), (SCALE\ HIGH\ POINT / 2))$

$PSET + SUoF$ Is used as set value in PID calculations. It is used for shifting the proportional band.

Example: If $PSET = 500^{\circ}C$, $SUoF = 5^{\circ}C$ or $SUoF = -5^{\circ}C$, shifting of the proportional band is shown below :

Note: Point position changes according to process input type and scale,

Unit changes according to the selection in this $unit$ parameter.



PoFS

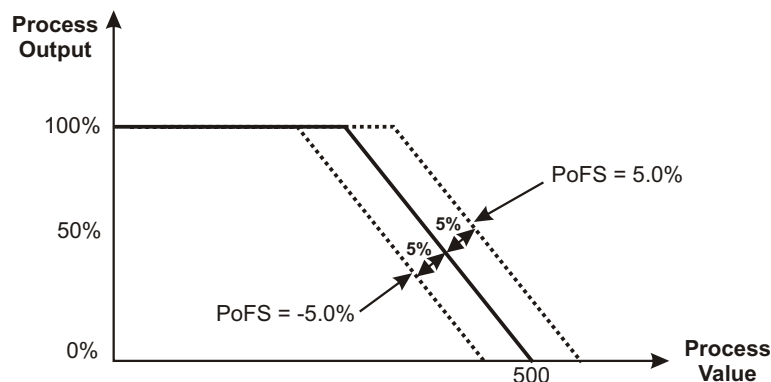
PID OUTPUT OFFSET

(FOR HEATING PID 0.0%, 100.0%)

(FOR COOLING PID -100.0%, 0.0%)

(FOR HEATING-COOLING PID -100.0%, 100.0%)

This parameter is added to "Output %" which is calculated at the end of the PID.



IF
1oP1

OR

1oP2

OR

oUt3

Conf



HEAT

OR

Cool



Pid

IS
SELECTED

PoSS

OUTPUT OFFSET RELATED TO PID SET

(FOR HEATING PID 0.0%, 100.0%)

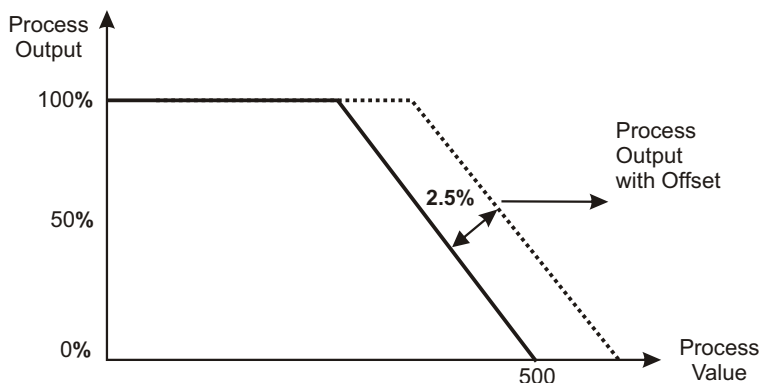
(FOR COOLING PID -100.0%, 0.0%)

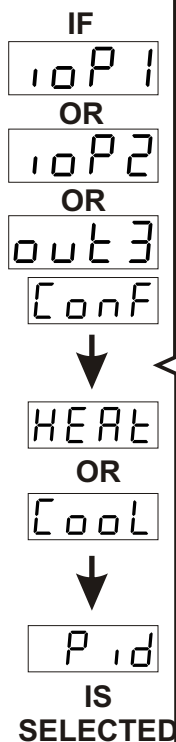
(FOR HEATING-COOLING PID -100.0%, 100.0%)

This parameter is added to the %process output that is calculated at the end of the PID according to process set value.

$$PoSS * PSEt / (uPL - LoL)$$

Example: If $PSEt = 500^{\circ}\text{C}$, $uPL = 1000^{\circ}\text{C}$, $LoL = 0$, $PoSS = 5.0\%$ then $PoSS * PSEt / (uPL - LoL) = 5.0 * 500 / (1000 - 0) = 2.5\%$ 2.5% is added to calculated process value.





5trn

PROCESS VALUE STABILIZATION (1, SCALE HIGH POINT)

It is used control if process value oscillates or not when Lunn Parameter is A Lun or A LSE

If;

$\text{PSEt} - \text{5trn} \leq \text{Process Value} \leq \text{PSEt} + \text{5trn}$ condition is not true and process value starts to oscillate (as shown in the diagram). If Lunn parameter is A Lun or A LSE , then A Ltn parameter is selected YES And then Limit Cycle Tune operation starts for determining new PID parameters.

Scale High Point : Maximum process input value in Pt-100 and Tc inputs

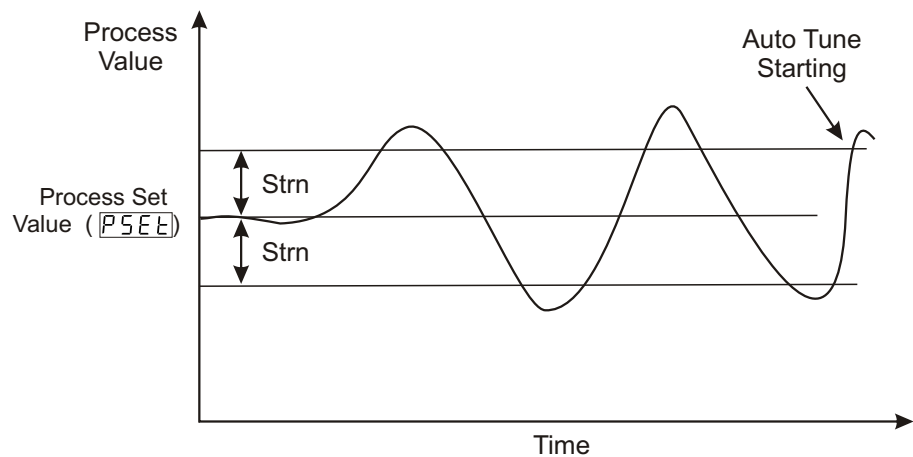
9999 for fixed dual point calibration used inputs,

Scale high point is the biggest one from LPoL or LPoH for selectable dual point calibration used inputs

Scale high point is the biggest one from Po00 or Po16 for multi point calibration used inputs

Note: Point position changes according to process input type and scale,

Unit changes according to the selection in this unit parameter.



o-db

PROPORTIONAL BAND SHIFTING ((- SCALE HIGH POINT / 2), (SCALE LOW POINT / 2))

If heating-cooling or only cooling function is performed ;

Cooling process set value is calculated by adding set value PSEt with parameter o-db

Control form can be ON/OFF or PID.

If set value for heating = $\text{PSEt} + \text{SUoF}$;

Then set value for cooling = $\text{PSEt} + \text{SUoF} + \text{o-db}$

Scale High Point : Maximum process input value in Pt-100 and Tc inputs

9999 for fixed dual point calibration used inputs,

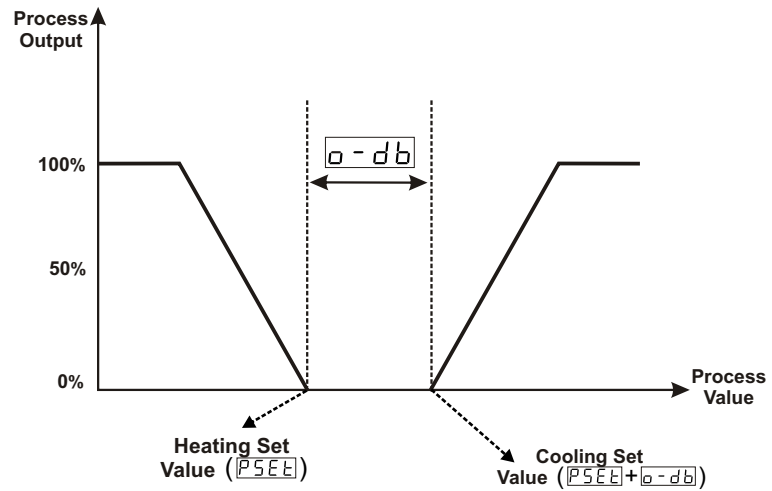
Scale high point is the biggest one from LPoL or LPoH for selectable dual point calibration used inputs

Scale high point is the biggest one from Po00 or Po16 for multi point calibration used inputs

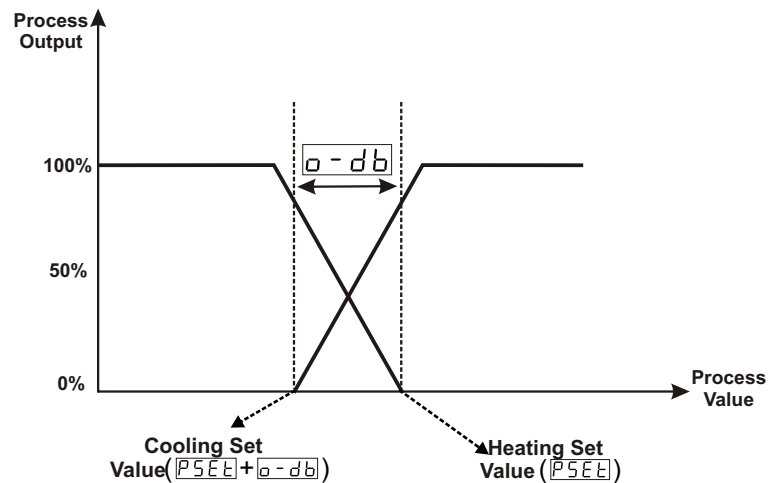
Note: Point position changes according to process input type and scale and scale ,

Unit changes according to the selection in this unit parameter.

If $o - db > 0$ (Dead Band)



If $o - db < 0$ (Overlap Band)



5600

SENSOR BREAK OUTPUT VALUE

(FOR HEATING PID 0.0%, 100.0%)

(FOR COOLING PID -100.0%, 0.0%)

(FOR HEATING-COOLING PID -100.0%, 100.0%)

When sensor breaks, controlling of the process can continue by entering %output value to **5600** parameter.

If this parameter 0.0, process control output does not perform an output when sensor breaks.

8.2.3 MODULE-1 Configuration Parameters

Module-1 configuration parameters are arranged automatically by the device according to the module type in Module-1 socket. These parameters are not accessible if there is no module in Module-1 socket.

EMO-400, EMO-410, EMO-420	—	out1	Defines output function.
	—	Con1	Defines control algorithm of output module.
	—	HYS1	Hysteresis value of output module
	—	Hyn1	Defines operation form of hysteresis
	—	tnr1	In ON/OFF operation, this time must be passed for the output to be energised again.
	—	Lou1	Defines logic output function
	—	ALS1	Selection of measurement input for alarm output. (There must be one of analogue input modules in Module-2 socket.)
	—	ALt1	Defines alarm type
	—	ALH1	Alarm hysteresis value
	—	Aon1	Alarm on delay time
	—	AoF1	Alarm off delay time
EMO-430	—	oAt1	Configuration of analogue output module
	—	ouA1	Function selection of analogue output
	—	rEt1	It determines “re-transmission” function for analogue output module
EMI-400	—	L in1	Configuration of logic input
EMI-410, EMI-430, EMI-440, EMI-450	—	isL1	Configuration of analogue input module
	—	tSL1	Selection of sensor type and scale for TC input module
	—	rLS1	Selection of sensor type and scale for PT-100 input module
	—	uAS1	It determines input type for $\overline{\text{---}}$ Voltage / Current input module
	—	dPn1	It determines point position for display.
	—	icA1	It determines calibration type.
	—	icL1	It defines minimum value for selectable dual point calibration.

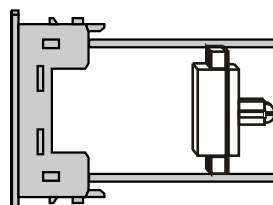
EMI-410, EMI-430, EMI-440, EMI-450	<code>.CH</code>	It defines maximum value for selectable dual point calibration.
	<code>unt</code>	Unit selection
	<code>LoL</code>	Minimum value of operating scale
	<code>uPL</code>	Maximum value of operating scale
	<code>.PU</code>	Display offset for measured value from analogue input module.
	<code>.FL</code>	Filter time for input signal
	<code>[Jn]</code>	It determines if cold junction compensation is active or not. It is active if input module is TC.
EMI-420	<code>rES</code>	Remote Set function
	<code>[tr]</code>	Current transfer ratio parameter for \sim CT input module

Module-1 configuration parameters are defined according to which input / output modules are plugged in Module-1 socket.

ioP1 Conf



These parameters are active if EMO-400 (Relay Output) , EMO-410 (SSR Driver) or EMO-420 (Digital Output) module is plugged in Module-1 socket.



EMO - 400
EMO - 410
EMO - 420

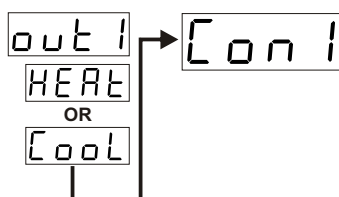
ioP1
Conf

out1 Defines output function for Module-1

HEAT Heating

COOL Cooling

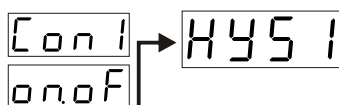
LOUT Logic output



Conf Defines control algorithm of output module in Module-1 socket. It is active if output function of Module-1 is heating or cooling.

onof ON/OFF control algorithm

PID PID control algorithm



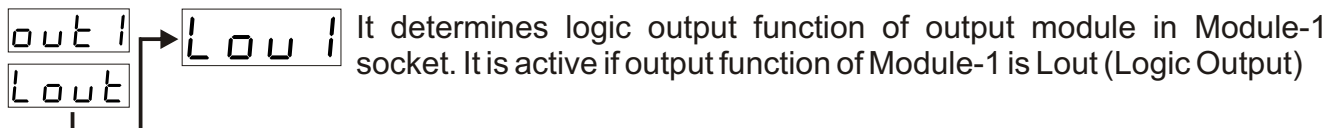
HYS1 Hysteresis value for OUT-1. It can be adjusted from 0% to 50% of defined scale. (It is active if ON/OFF control is selected)

HYN1 It determines operation form of hysteresis. (It is active if ON/OFF control is selected)

0000 SV + HYS/2 and SV - HYS/2

0001 SV and SV+HYS or SV and SV-HYS

EN1 In ON/OFF operation, this time must be passed for the output to be energised again. It can be adjusted from 0.0 to 100.0 seconds. (It is active if ON/OFF control is selected)



0000 Alarm output

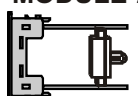
0001 Manual / Automatic data output

0002 Sensor break alarm output

0003 Output is active when the process value is out of the band which is defined with minimum value of operating scale And maximum value of operating scale

0004 Output indicates that Ramp/Soak function has finished

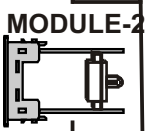
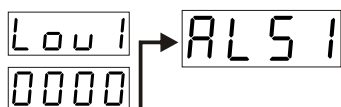
MODULE-2



EMI-410
EMI-430
EMI-440
EMI-450

0005 Sensor break alarm output for analogue input module in Module-2 socket. (It is visible if one of analogue input modules is plugged in Module-2 socket)

0006 If process value is less than minimum value of operating scale for analogue input module in Module-2 socket or greater than maximum value of operating scale for analogue input module in Module-2 socket, process output becomes active. (This parameter is visible if one of the analogue input modules is plugged in Module-2 socket)

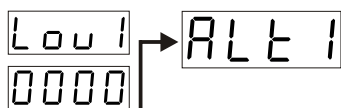


EMI-410
EMI-430
EMI-440
EMI-450

Measurement input selection for Module-1 alarm output. This parameter is visible if Logic output function of Module-1 is Alarm output and one of the analogue input modules is plugged in Module-2 socket

0000 Alarm output runs according to the process input.

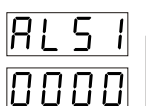
0001 Alarm output runs according to the analogue input module (2nd sensor input) in Module-2 socket.



It determines alarm type. It is active if logic output function of Module-1 is an alarm output.

0000 Process high alarm

0001 Process low alarm



If there is no analogue input module in Module-2 socket

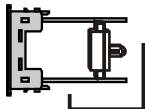
0002 Deviation high alarm. It is active when alarm output runs according to the process input.

0003 Deviation low alarm. It is active when alarm output runs according to the process input.

0004 Deviation band alarm. It is active when alarm output runs according to the process input.

0005 Deviation range alarm. It is active when alarm output runs according to the process input.

MODULE-2

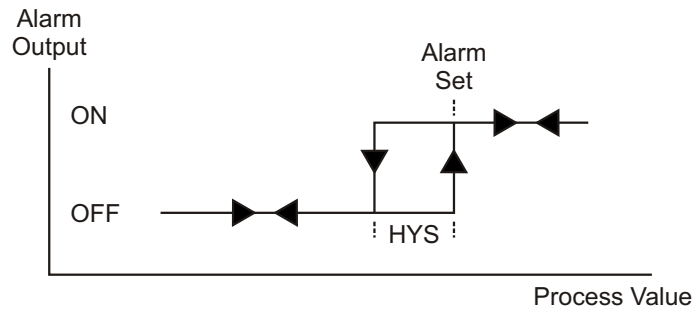


EMI-420

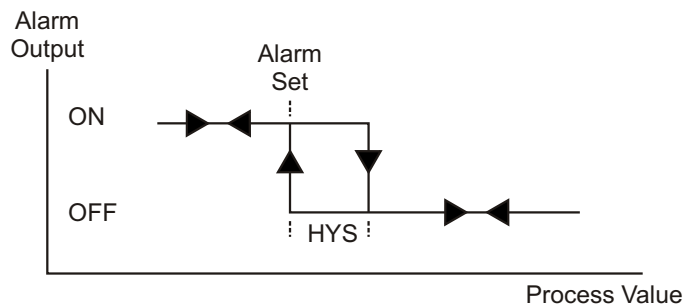
0006

Heater failure alarm. It is active if \sim CT input module is plugged in Module-2 socket.

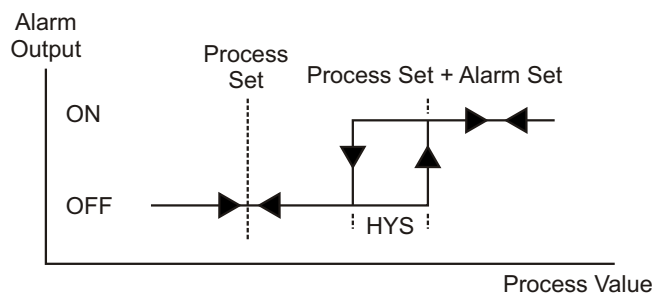
Process high alarm



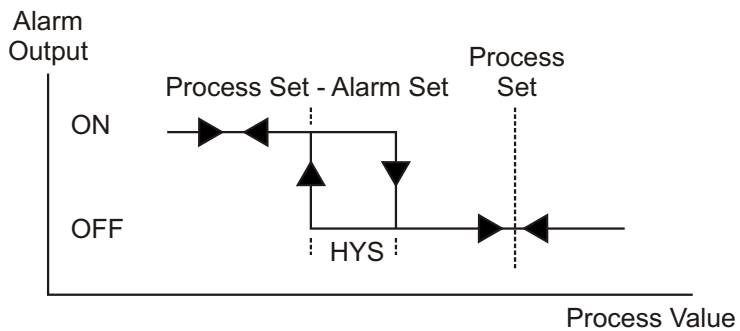
Process low alarm



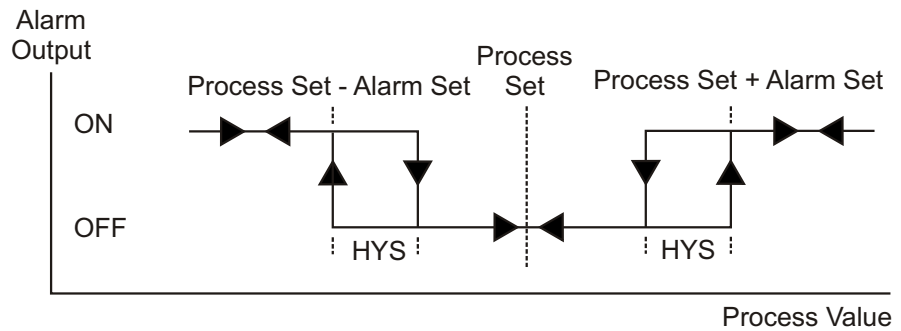
Deviation High Alarm



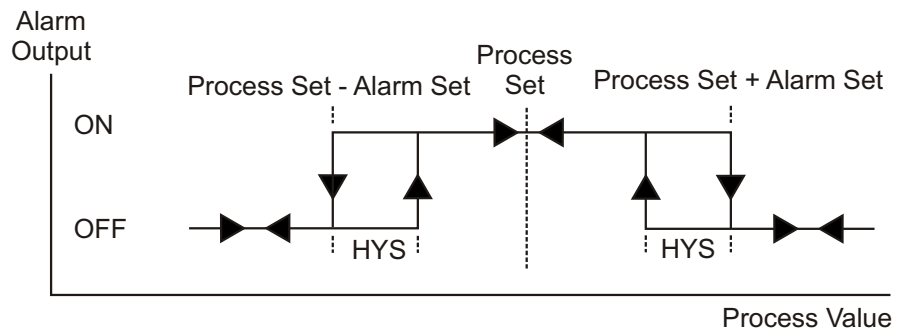
Deviation Low Alarm



Deviation Band Alarm



Deviation Range Alarm



Low 1
0000

ALH 1

Alarm- 1 hysteresis value. It is active if logic output function of Module-1 is selected alarm output.

If **ALS 1** is **0000** or there is no analogue input module (2nd sensor input) in Module-2 socket, then it can be adjusted from 0% to 50% of process input scale (**UPL** - **LOL**)

If **ALS 1** is **0001** and there is one of an analogue input module (2nd sensor input) in Module-2 socket, then it can be adjusted from 0% to 50% of analogue input module scale (**UPL2** - **LOL2**)

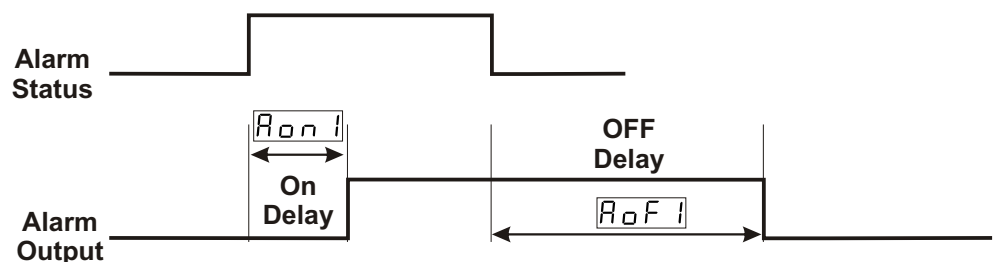
If there is \sim CT input module (EMI-420) in Module-2 socket and alarm type parameter **ALT 1** is **0006** , then it can be adjusted from 0.0 to 20.0A \sim

Ron 1

Alarm on delay time. It can be adjusted from 0000 to 9999 seconds. It is active if logic output function of Module-1 is alarm output.

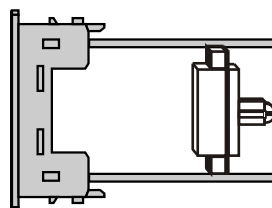
RoF 1

Alarm off delay time. It can be adjusted from 0000 to 9998 seconds. When the value is greater than 9998, **LECH** is seen on the display. It means alarm latching output is selected. It is active if logic output function of Module-1 is alarm output.





These parameters are active if EMO-430 (0/4...20 mA—Current Output) module is plugged in Module-1 socket.



EMO-430

10P1
Conf

0At1

Configuration of analogue output module in Module-1 socket.

0000

0...20mA output or 0...10V— according to Section 5.2.5 is selected.

0001

4...20mA output or 2...10V— according to Section 5.2.5 is selected.

0uA1

Function selection of analogue output module in Module-1 socket.

HEAT

Analogue output module in Module-1 socket is used for heating

COOL

Analogue output module in Module-1 socket is used for cooling.

RETr

Analogue output module in Module-1 socket is used for retransmission.

0uA1
RETr

RETr1

Defines “Re-transmission” function. (It is active if “re-transmission” function is selected for analogue output module in Module-1 socket.

rt.Pr

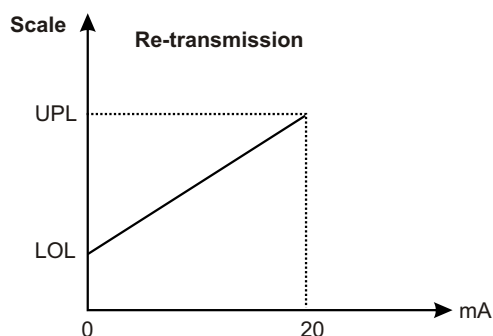
It retransmits Process value to analogue output.

rt.Er

It retransmits difference between Process and Set value to analogue output.

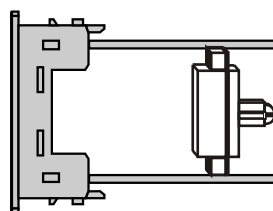
rt.PU

It retransmits Set value to analogue output.





These parameters are active if EMI-400 (Digital Input) module is plugged in Module-1 socket.



EMI-400

10P1
Conf

L in 1

Configuration of digital input in Module-1 socket.

0000

Manual / Automatic selection input

When the logic input is triggered ;

In PID Tune and selection of operation form menu (run List), if selection of operation form parameter (Auto) is run, then Auto is selected, if Auto parameter is Auto, then run is selected.

0001

Auto Tune (Limit Cycle Tuning) Start/Stop input.

When the logic input is triggered ;

It is used to start or stop the Auto Tune operation.

If input is being active while Atun operation does not perform, automatic tune selection parameter Atun is selected YES and then Auto Tune operation starts to run. If input is being active while Atun operation performs, Auto Tune operation is stopped.

0002

Ramp&Soak, Start / Stop input.

When the logic input is triggered ;

If Ramp / Soak control parameter rssl is run or Hold then off is selected
If it is off then run is selected.

0003

Ramp&Soak, Start / Hold input.

When the logic input is triggered ;

If Ramp / Soak control parameter rssl is run then Hold is selected
Hold then run is selected

0004

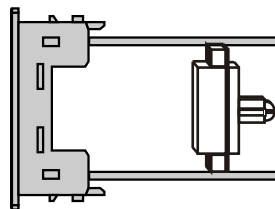
Alarm Latch Canceling.

When the logic input is triggered ;

If there is a latching alarm output and alarm condition is not active, latching is canceled.



These parameters are active if EMI-410 (0/4...20mA $\overline{\text{---}}$ Current Input) , EMI-430 (TC or 0...50mV $\overline{\text{---}}$ input), EMI-440 (PT-100 Input) or EMI-450 (0...10V $\overline{\text{---}}$ Input) module is plugged in Module-1 socket.



EMI - 410
EMI - 430
EMI - 440
EMI - 450

10P1
Conf

15L1

Configuration of analogue input module in Module-1 socket

0000

TC input type selection. This must be selected if analogue input module in Module-1 socket is EMI-430.

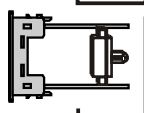
0001

PT-100 input type selection. This must be selected, if analogue input module in Module-1 socket is EMI-440.

0002

$\overline{\text{---}}$ Voltage / Current input type selection. This must be selected if analogue input module in Module-1 socket is EMI-410 , EMI-430 or EMI - 450.

15L1
0000



EMI-430

15L1

Selection of sensor type and scale for TC input module in Module-1 socket. It is active if input type of Module-1 is selected TC.

0000

L (-100°C;850°C) or (-148°F;1562°F)

0001

L (-100.0°C;850.0°C) or (-148.0°F;999.9°F)

0002

J (-200°C;900°C) or (-328°F;1652°F)

0003

J (-199.9°C;900.0°C) or (-199.9°F;999.9°F)

0004

K (-200°C;1300°C) or (-328°F;2372°F)

0005

K (-199.9°C;999.9°C) or (-199.9°F;999.9°F)

0006

R (0°C;1700°C) or (32°F;3092°F)

0007

R (0.0°C;999.9°C) or (32.0°F;999.9°F)

0008

S (0°C;1700°C) or (32°F;3092°F)

0009

S (0.0°C;999.9°C) or (32.0°F;999.9°F)

0010

T (-200°C;400°C) or (-328°F;752°F)

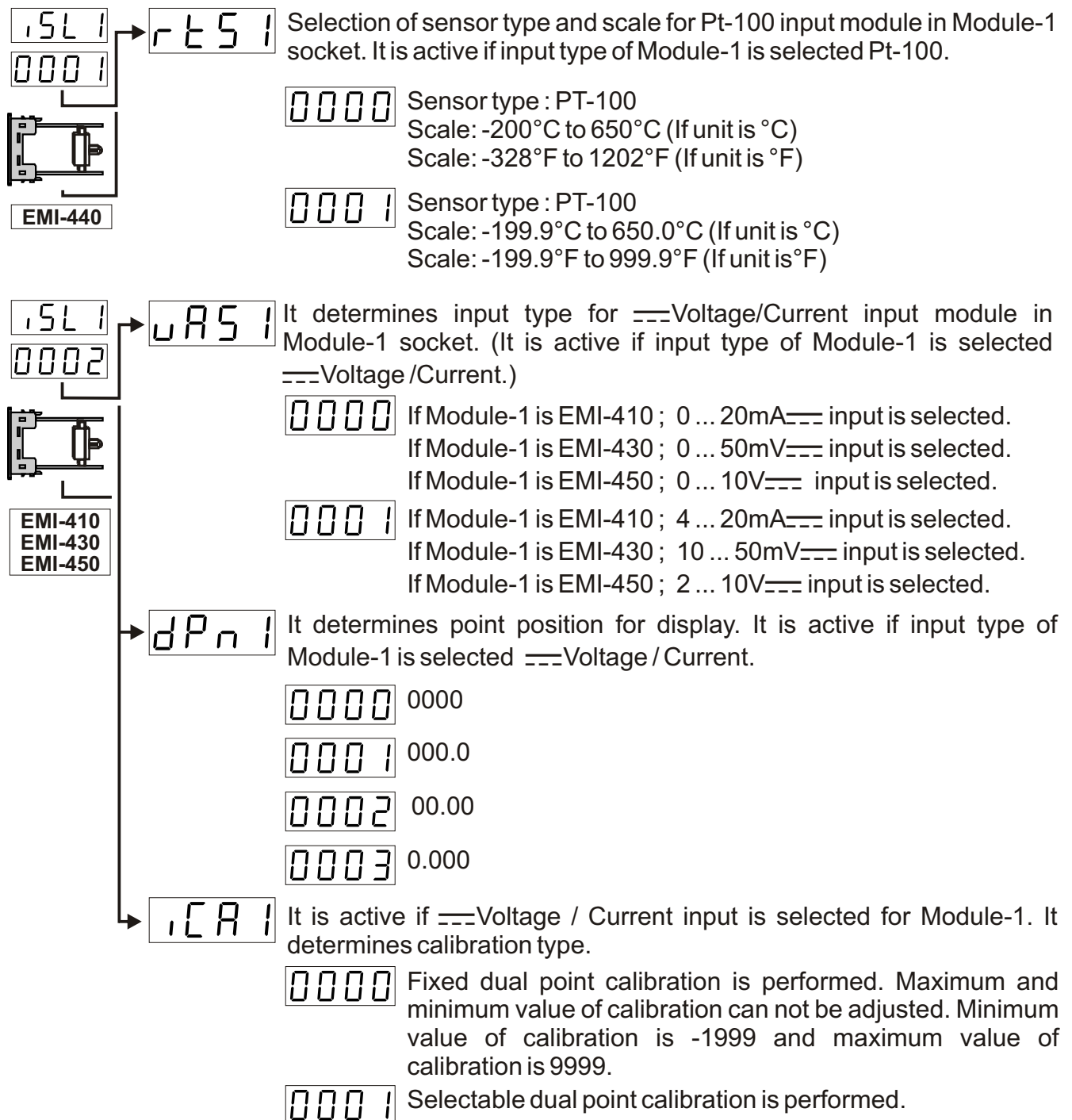
0011

T (-199.9°C;400.0°C) or (-199.9°F;752.0°F)

0012

B (44°C;1800°C) or (111°F;3272°F)

0013	B (44.0°C;999.9°C) or (111.0°F ; 999.9°F)
0014	E (-150°C;700°C) or (-238°F;1292°F)
0015	E (-150.0°C;700.0°C) or (-199.9°F;999.9°F)
0016	N (-200°C;1300°C) or (-328°F;2372°F)
0017	N (-199.9°C;999.9°C) or (-199.9°F;999.9°F)
0018	C (0°C;2300°C) or (32°F;3261°F)
0019	C (0.0°C;999.9°C) or (32.0°F;999.9°F)



Defines minimum value for selectable dual point calibration. It is active if $\frac{V}{I}$ is selected. It can be adjusted from -1999 to 9999.

Defines maximum value for selectable dual point calibration. It is active if $\frac{V}{I}$ is selected. It can be adjusted from -1999 to 9999.

Unit selection

Unit is °C.

Unit is °F.

Unit is U. It is active if input type of Module-1 is selected $\frac{V}{I}$.

No unit. It is active if input type of Module-1 is selected $\frac{V}{I}$.

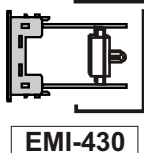
Minimum value of operating scale (Low Limit). It can be changed according to analogue input type and scale.

Maximum value of operating scale (High Limit). It can be changed according to analogue input type and scale.

Display offset for value in analogue input module. It can be adjusted from -10% to +10% of scale. This value is added to the process value.

It is filter time for input signal. It can be adjusted 0.0 to 900.0 seconds.

It decides if cold junction compensation is active or not for TC input module in Module-1 socket. It is active if process input of Module-1 is TC input.



Cold junction compensation is active

Cold junction compensation is not active

It determines if the measured value from analogue input module in Module-1 socket is used as Remote Set or not. This parameter is visible if point position and unit parameters are same for process input and analogue input module.

Measured value from analogue input module in Module-1 socket is used as process set value. User defined process set value is not considered.

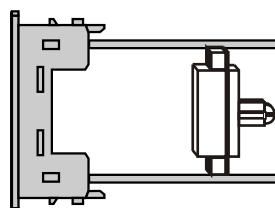
Measured value from analogue input module in Module-1 socket is not used as process set value. User defined process set value is considered.

ioP1 Conf



These parameters are active if EMI-420 (∼CT) Input Module is plugged in Module-1 socket.

ioP1
Conf



EMI-420

Ctrl

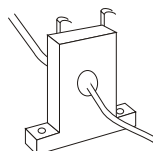
Current transfer ratio for Module-1. It can be adjusted from 0 to 100

Example : For 100:5A type current transformer ;

This parameter must be $\text{Ctrl} = 100/5 = 0020$

Current Transformer

Calculating set value for heating failure



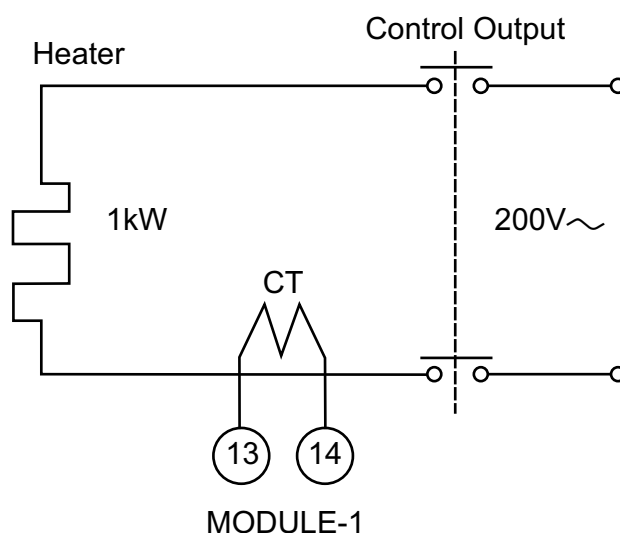
$$\text{Set} = [(\text{Current value without failure} + \text{Current value with heater failure})] / 2$$

For example ; If that there is a system with one heater (200V∼ and 1kW) ;

In normal conditions current in heater = $1000 / 200 = 5\text{A}$

If there is a heater failure no current will be on the heater (0A).

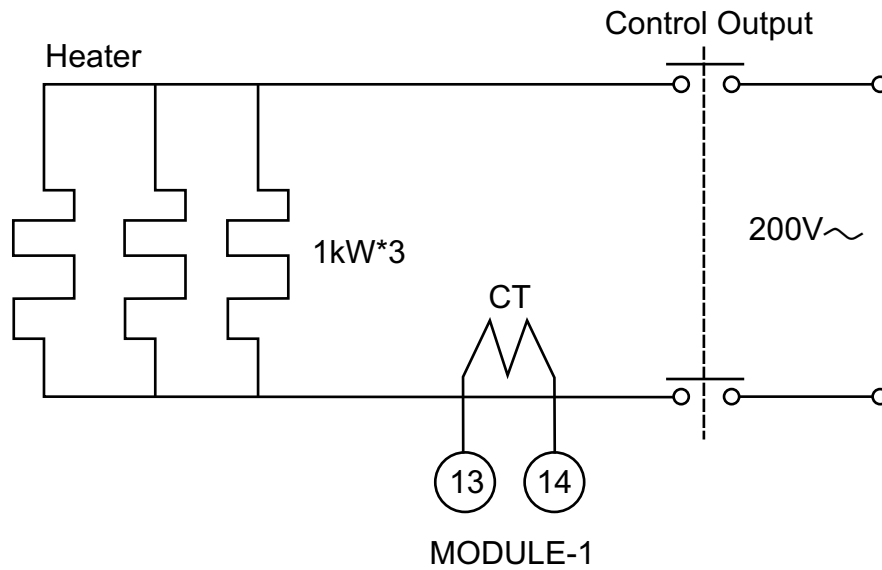
Then Set value must be adjusted = $(5+0)/2 = 2.5\text{A}$



For correct measurements with EMI-420 (∼CT) Input Module in Module-1 socket, heating output must be active minimum for 0.2 sec (200 msec).

If a system operates with PID control form, heating minimum output time OLTH must be minimum 0.2 sec.

For example ;If there is a system with three heater (200V \sim and 1kW) ;
 In normal conditions current in heater ; $[1000 / 200] * 3 = 5A * 3 = 15A$
 If one of the heater is out of order, there is $5 * 2 = 10A$ current on two heaters. Current
 in heater failure is 10A. Then Set value must be adjusted $(15+10) / 2 = 12.5A$



For correct measurements with EMI-420 (\sim CT) Input Module in Module-1 socket, heating output must be active minimum for 0.2 sec (200 msec).

If a system operates with PID control form, heating minimum control time 0.2 Must be minimum 0.2 second.

8.2.4 MODULE-2 Configuration Parameters

Module-2 configuration parameters are arranged automatically by the device according to the module type in Module-2 socket. These parameters are not accessible if there is no module in Module-2 socket.

EMO-400, EMO-410, EMO-420	out2	Defines output function
	Con2	Defines control algorithm of output module
	HYS2	Hysteresis value of output module
	HYn2	Defines operation form of hysteresis
	Enr2	In ON/OFF operation, this time must be passed for the output to be energised again.
	LoU2	Defines logic output function
	AL52	Selection of measurement input for alarm output. (There must be one of analogue input modules in Module-1 socket.)
	ALt2	Defines alarm type
	ALH2	Alarm hysteresis value
	Aon2	Alarm on delay time
	Aof2	Alarm off delay time
EMO-430	oAt2	Configuration of analogue output module
	ouA2	Function selection of analogue output
	rEt2	It determines "re-transmission" function for analogue output module
EMI-400	L in2	Configuration of logic input
EMI-410, EMI-430, EMI-440, EMI-450	isl2	Configuration of analogue input module
	tSL2	Selection of sensor type and scale for TC input module
	rtS2	Selection of sensor type and scale for PT-100 input module
	uA52	It determines input type for --- Voltage/Current input module
	dPn2	It determines point position for display.
	icA2	It determines calibration type.
	icL2	It defines minimum value for selectable dual point calibration.

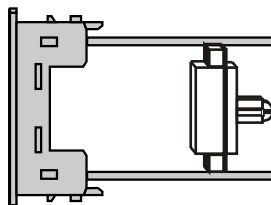
EMI-410, EMI-430, EMI-440, EMI-450	ICH2	It defines maximum value for selectable dual point calibration. It is active if $\overline{\text{---}}$ Voltage/Current input is selected.
	unt2	Unit selection
	LoL2	Minimum value of operating scale
	uPL2	Maximum value of operating scale
	IPU2	Display offset for measured value from analogue input module.
	IFL2	Filter time for input signal
	[Jn2	It determines if cold junction compensation is active or not. It is active if input module is TC.
EMI-420	RE52	Remote Set function
	[tr2	Current transfer ratio parameter for \sim CT input module

Module-2 configuration parameters are defined according to which input / output modules are plugged in Module-2 socket.

ioP2 Conf



These parameters are active if EMO-400 (Relay Output) , EMO-410 (SSR Driver) or EMO-420 (Digital Output) module is plugged in Module-2 socket.



EMO - 400
EMO - 410
EMO - 420

ioP2
Conf

out2 Determines output function for Module-2

HEAT Heating

COOL Cooling

LOUT Logic output

out2
HEAT
OR
COOL

Con2 It defines control algorithm of output module in Module-2 socket. It is active if output function of Module-1 is heating or cooling.

onof ON/OFF control algorithm

Pid PID control algorithm

Con2
onof

HYS2 Hysteresis value for OUT-2. It can be adjusted from 0% to 50% of defined scale. (It is active if ON/OFF control is selected)

HYN2 It determines operation form of hysteresis. (It is active if ON/OFF control is selected)

0000 SV + HYS/2 and SV - HYS/2

0001 SV and SV+HYS or SV and SV-HYS

EN2 In ON/OFF operation, this time must be passed for the output to be energised again. It can be adjusted from 0.0 to 100.0. (It is active if ON/OFF control is selected)

out2 → Lout2 It determines logic output function of output module in Module-2 socket. It is active if output function of Module-2 is Lout (Logic Output)

0000 Alarm output

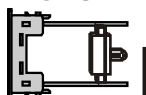
0001 Manual / Automatic data output

0002 Sensor break alarm output

0003 Output is active when the process value is out of the band which is defined with minimum value of operating scale L o L And maximum value of operating scale u P L

0004 Output indicates that Ramp/Soak function has finished

MODULE-1



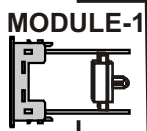
EMI-410
EMI-430
EMI-440
EMI-450

0005 Sensor break alarm output for analogue input module in Module-1 socket. (It is visible if one of analogue input modules is plugged in Module-1 socket)

0006 If process value is less than minimum value of operating scale L o L for analogue input module in Module-1 socket or greater than maximum value of operating scale u P L for analogue input module in Module-1 socket, process output becomes active. (This parameter is visible if one of the analogue input modules is plugged in Module-1 socket)

Lout2 → AL52

Measurement input selection for Module-2 alarm output. This parameter is visible if Logic output function of Module-2 is Alarm output and one of the analogue input modules is plugged in Module-1 socket



EMI-410
EMI-430
EMI-440
EMI-450

0000 Alarm output runs according to the process input.

0001 Alarm output runs according to the analogue input module (2nd sensor input) in Module-1 socket.

Lout2 → ALt2

It determines alarm type. It is active if logic output function of Module-2 is adjusted alarm output.

0000 Process high alarm

0001 Process low alarm

AL52
0000

If there is no analogue input module in Module-1 socket

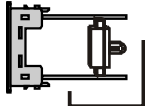
0002 Deviation high alarm. It is active when alarm output runs according to the process input.

0003 Deviation low alarm. It is active when alarm output runs according to the process input.

0004 Deviation band alarm. It is active when alarm output runs according to the process input.

0005 Deviation range alarm. It is active when alarm output runs according to the process input.

MODULE-1

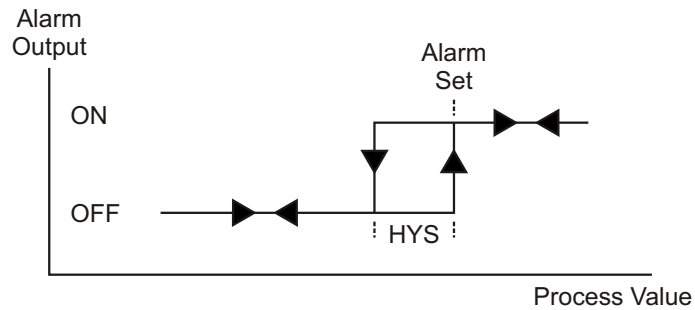


EMI-420

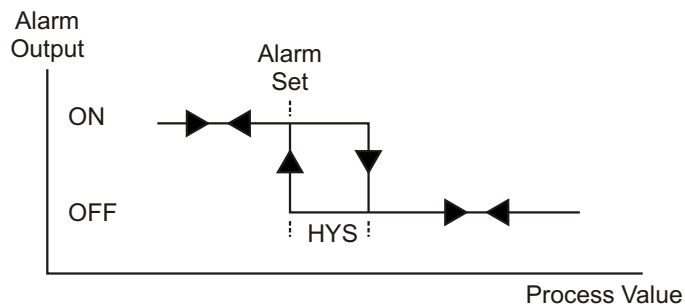
0006

Heater failure alarm. It is active if \sim CT input module is plugged in Module-1 socket.

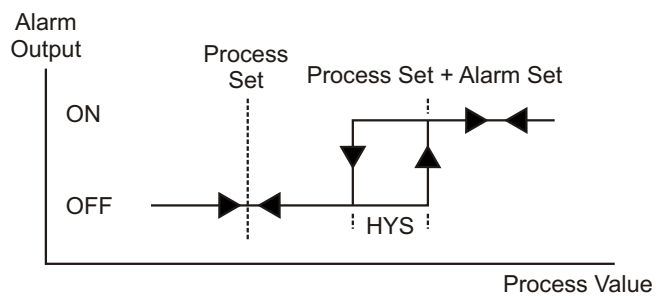
Process High Alarm



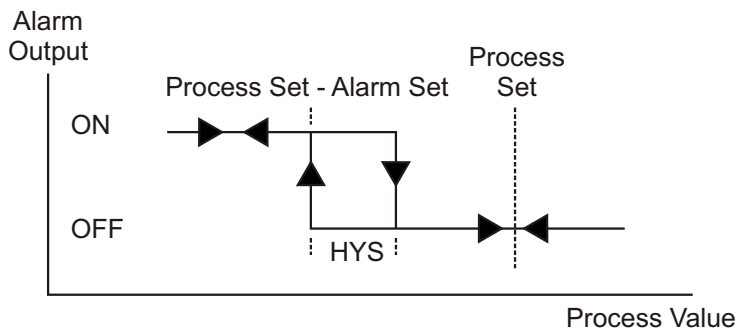
Process Low Alarm



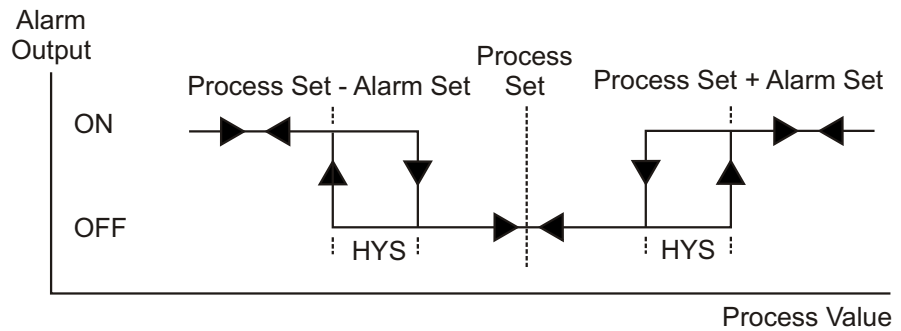
Deviation High Alarm



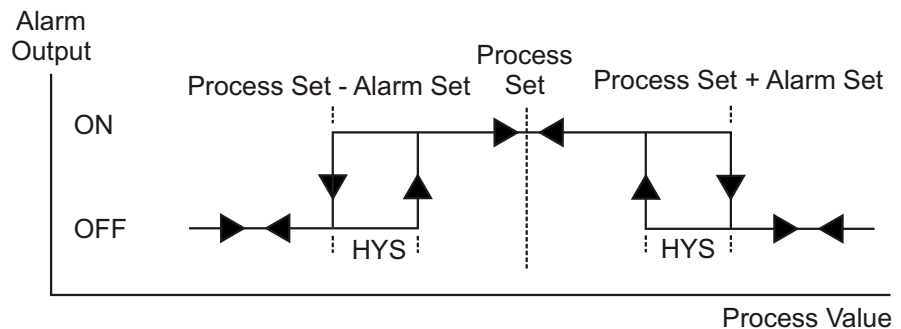
Deviation Low Alarm



Deviation Band Alarm



Deviation Range Alarm



Low2
0000

ALH2

Alarm- 2 hysteresis value. It is active if logic output function of Module-2 is alarm output.

If **ALS2** is **0000** or there is no analogue input module (2nd sensor input) in Module-1 socket, then it can be adjusted from 0% to 50% of process input scale (**uPL** - **LoL**)

If **ALS2** is **0001** and there is one of an analogue input module (2nd sensor input) in Module-1 socket, then it can be adjusted from 0% to 50% of analogue input module scale (**uPL1** - **LoL1**)

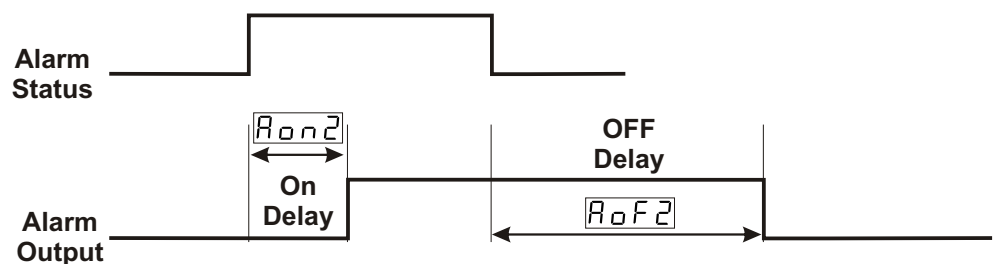
If there is \sim CT input module (EMI-420) in Module-1 socket and alarm type parameter **ALT2** is **0006** , then it can be adjusted from 0.0 to 20.0A \sim

Ron2

Alarm on delay time. It can be adjusted from 0000 to 9999 seconds. It is active if logic output function of Module-2 is alarm output.

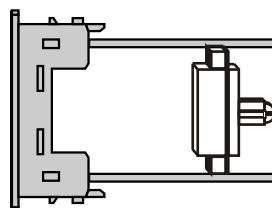
RoF2

Alarm off delay time. It can be adjusted from 0000 to 9998 seconds. When the value is greater than 9998, **LECH** is seen on the display. It means alarm latching output is selected. It is active if logic output function of Module-2 is alarm output.





These parameters are active if EMO-430 (0/4...20 mA \rightarrow Current Output) module is plugged in Module-2 socket.



EMO-430

10P2
Conf

0AR2 Configuration of analogue output module in Module-2 socket.

0000 0...20mA output or 0...10V \rightarrow according to Section 5.2.5 is selected.

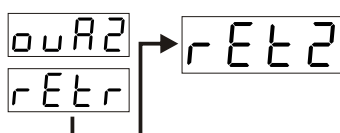
0001 4...20mA output or 2...10V \rightarrow according to Section 5.2.5 is selected.

0UAR2 Function selection of analogue output module in Module-2 socket.

HEAT Analogue output module in Module-2 socket is used for heating

COOL Analogue output module in Module-2 socket is used for cooling

RETR Analogue output module in Module-2 socket is used for “re-transmission”

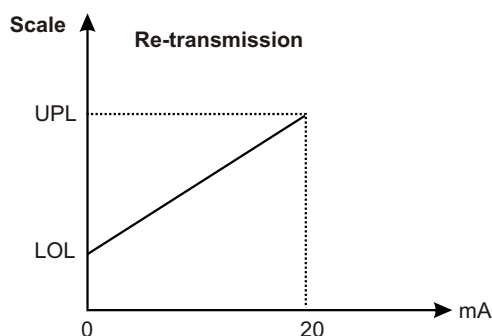


Defines “Re-transmission” function. (It is active if “re-transmission” function is selected for analogue output module in Module-2 socket)

RETR.PR It retransmits Process value to analogue output.

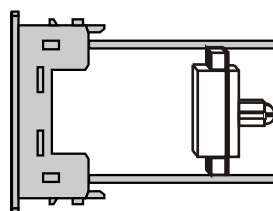
RETR.ER It retransmits difference between Process and Set value to analogue output.

RETR.PU It retransmits Set value to analogue output.





These parameters are active if EMI-400 (Digital Input) is plugged in Module-2 socket.



EMI-400

10P2
Conf

L in2

Configuration of digital input in Module-2 socket.

0000

Manual / Automatic selection input

When the logic input is triggered ;

In PID Tune and selection of operation form menu (run List) , if selection of operation form parameter (Auto) is MAN , then AUTO is selected, if Auto parameter is AUTO , then MAN is selected.

0001

Auto Tune (Limit Cycle Tuning) Start/Stop input

When the logic input is triggered ;

It is used to start or stop the Auto Tune operation.

If input is being active while Atun operation does not perform, automatic tune selection parameter Atun is selected YES and then Auto Tune operation starts to run. If input is being active while Atun operation performs, Auto Tune operation is stopped.

0002

Ramp&Soak, Start / Stop input

When the logic input is triggered ;

If Ramp / Soak control parameter RSSL is run or Hold then OFF is selected
If it is OFF then run is selected.

0003

Ramp&Soak, Start / Hold input

When the logic input is triggered ;

If Ramp / Soak control parameter RSSL is run then Hold is selected
Hold then run is selected

0004

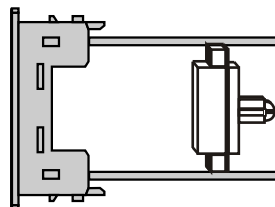
Alarm Latch Canceling.

When the logic input is triggered ;

If there is a latching alarm output and alarm condition is not active, latching is canceled.



These parameters are active if EMI-410 (0/4...20mA--- Current Input) , EMI-430 (TC or 0...50mV--- Input), EMI-440 (PT-100 Input) or EMI-450 (0...10V---Input) module is plugged in Module-2 socket.



EMI - 410
EMI - 430
EMI - 440
EMI - 450

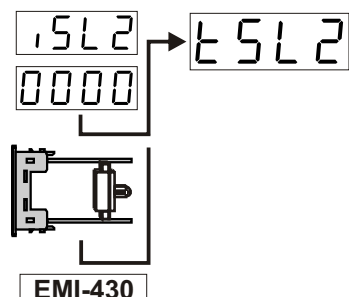
10P2
Conf

15L2 Configuration of analogue input module in Module-2.

0000 TC input type selection. This must be selected if analogue input module in Module-2 socket is EMI-430.

0001 PT-100 input type selection. This must be selected, if analogue input module in Module-2 socket is EMI-440.

0002 ---voltage / Current input type selection. This must be selected if analogue input module in Module-2 socket is EMI-410 , EMI-430 or EMI - 450.



t5L2 Selection of sensor type and scale for TC input module in Module-2 socket. It is active if input type of Module-2 is selected TC.

0000 L (-100°C;850°C) or (-148°F;1562°F)

0001 L (-100.0°C;850.0°C) or (-148.0°F;999.9°F)

0002 J (-200°C;900°C) or (-328°F;1652°F)

0003 J (-199.9°C;900.0°C) or (-199.9°F;999.9°F)

0004 K (-200°C;1300°C) or (-328°F;2372°F)

0005 K (-199.9°C;999.9°C) or (-199.9°F;999.9°F)

0006 R (0°C;1700°C) or (32°F;3092°F)

0007 R (0.0°C;999.9°C) or (32.0°F;999.9°F)

0008 S (0°C;1700°C) or (32°F;3092°F)

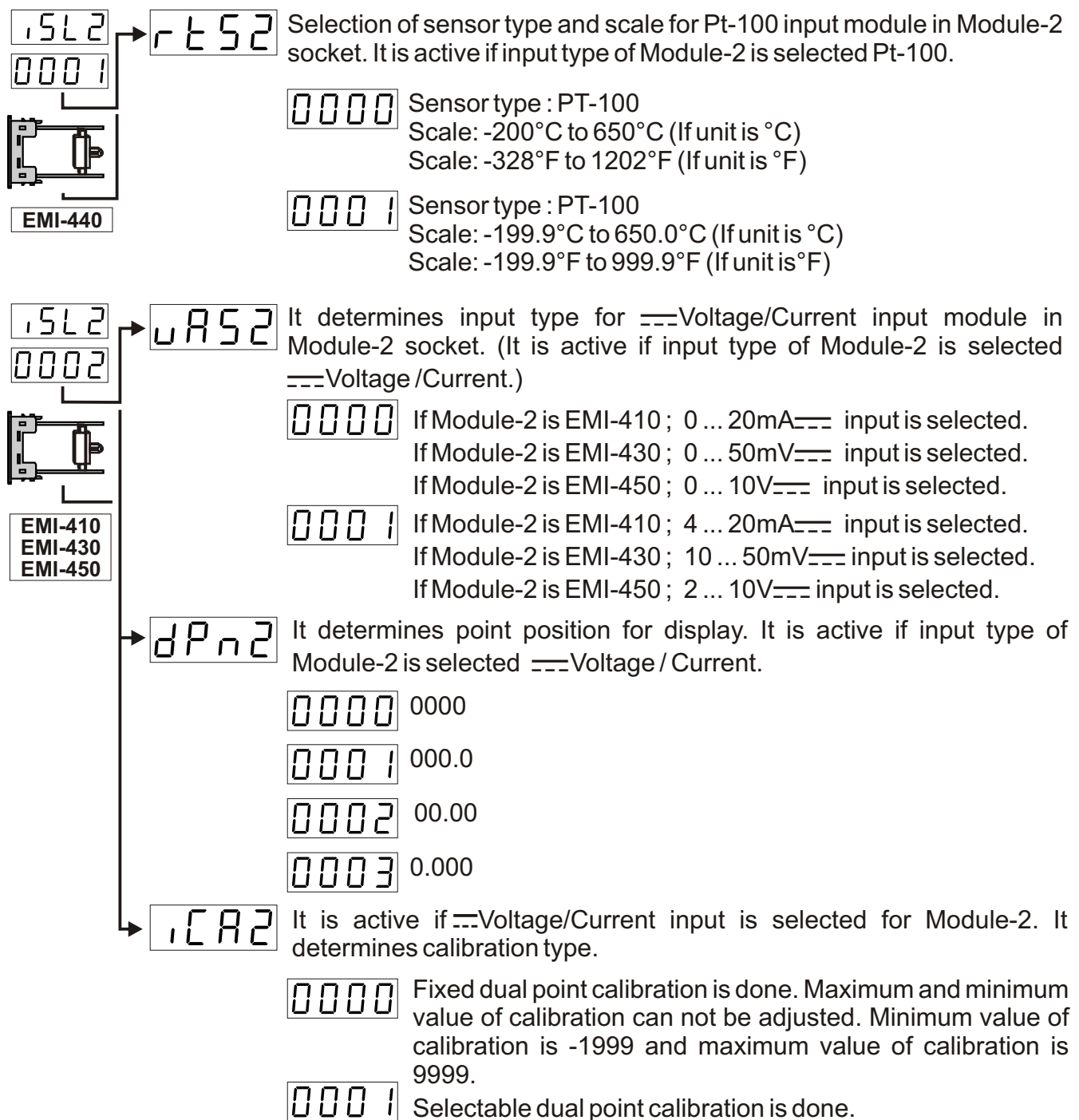
0009 S (0.0°C;999.9°C) or (32.0°F;999.9°F)

0010 T (-200°C;400°C) or (-328°F;752°F)

0011 T (-199.9°C;400.0°C) or (-199.9°F;752.0°F)

0012 B (44°C;1800°C) or (111°F;3272°F)

00 13	B (44.0°C;999.9°C) or (111.0°F ; 999.9°F)
00 14	E (-150°C;700°C) or (-238°F;1292°F)
00 15	E (-150.0°C;700.0°C) or (-199.9°F;999.9°F)
00 16	N (-200°C;1300°C) or (-328°F;2372°F)
00 17	N (-199.9°C;999.9°C) or (-199.9°F;999.9°F)
00 18	C (0°C;2300°C) or (32°F;3261°F)
00 19	C (0.0°C;999.9°C) or (32.0°F;999.9°F)



1CAL
0001

1CL2

Defines minimum value for selectable dual point calibration. It is active if ---Voltage / Current input is selected. It can be adjusted from -1999 to 9999.

1CH2

Defines maximum value for selectable dual point calibration. It is active if ---Voltage / Current input is selected. It can be adjusted from -1999 to 9999.

unit2

Unit selection

0C

Unit is °C.

0F

Unit is °F.

1SL2
0002

U

Unit is U. It is active if input type of Module-2 is selected ---Voltage / Current.

-

No unit. It is active if input type of Module-2 is selected ---Voltage / Current.

L0L2

Minimum value of operating scale (Low Limit). It can be changed according to analogue input type and scale.

uPL2

Maximum value of operating scale (High Limit). It can be changed according to analogue input type and scale.

1PU2

Display offset for value in analogue input module. It can be adjusted from -10% to +10% of scale. This value is added to the process value.

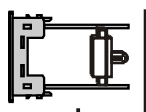
1FL2

It is filter time for input signal. It can be adjusted from 0.0 to 900.0 seconds.

1SL2
0000

CJn2

It determines if cold junction compensation is active or not for TC input module in Module-2 socket. It is active if process input of Module-2 is TC input.



EMI-430

YES

Cold junction compensation is active

no

Cold junction compensation is not active

rESS2

It determines if the measured value from analogue input module in Module-2 socket is used as Remote Set or not. This parameter is visible if point position and unit parameters are same for process input and analogue input module.

YES

Measured value from analogue input module in Module-2 socket is used as process set value. User defined process set value is not considered.

no

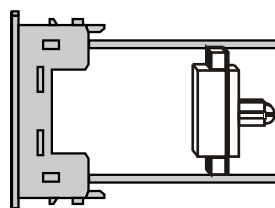
Measured value from analogue input module in Module-2 socket is not used as process set value. User defined process set value is considered.

10P2 Conf



These parameters are active if EMI-420 (~CT) Input Module is plugged in Module-2 socket.

10P2
Conf



EMI-420

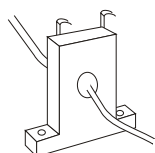
Clr2

Current transfer ratio for Module-2.
(It can be adjusted from 0 to 100.)

Example : For 100:5A type current transformer ;

This parameter must be $\text{Clr2} = 100/5 = 0020$

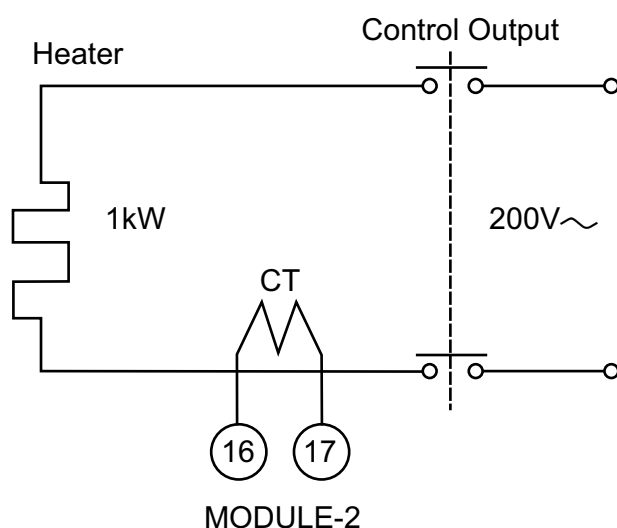
Current Transformer



Calculating set value for heating failure

$$\text{Set} = [(\text{Current value without failure} + \text{Current value with heater failure})] / 2$$

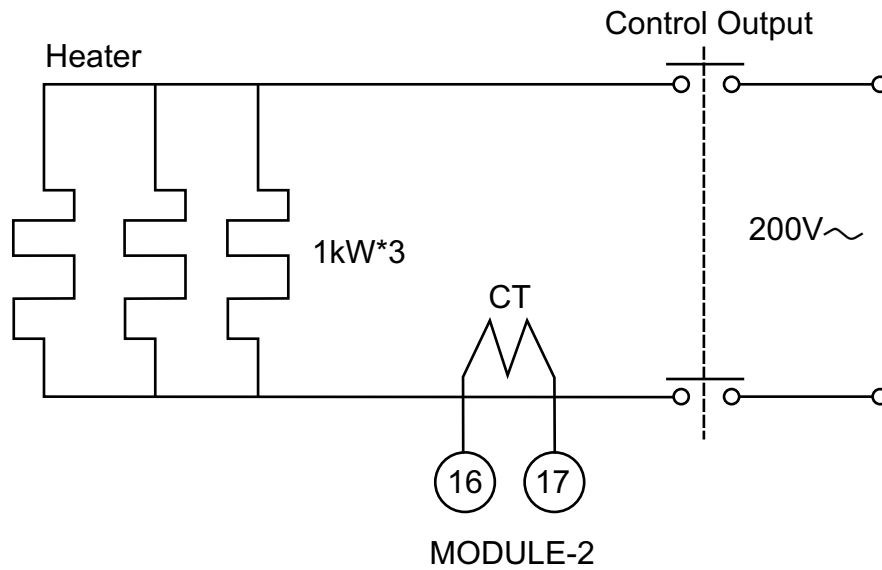
For example ; if there is a system with one heater (200V ~ and 1kW) ;
In normal conditions current in heater = $1000 / 200 = 5\text{A}$
If there is a heater failure no current will be on the heater (0A).
Then Set value must be adjusted = $(5+0)/2 = 2.5\text{A}$



For correct measurements with EMI-420 (~CT) Input Module in Module-2 socket, heating output must be active minimum for 0.2 sec (200 msec).

If a system operates with PID control form, heating minimum output time OLtH must be minimum 0.2 sec.

For example ;ift there is a system with three heater (200V \sim and 1kW);
 In normal conditions current in heater ; $[1000 / 200] * 3 = 5A * 3 = 15A$
 If one of the heater is out of order, there is $5 * 2 = 10A$ current on two heaters. Current
 in heater failure is 10A. Then Set value must be adjusted $(15+10) / 2 = 12.5A$



For correct measurements with EMI-420 (\sim CT) Input Module in Module-2 socket, heating output must be active minimum for 0.2 sec (200 msec).

If a system operates with PID control form, heating minimum control time OLTH Must be minimum 0.2 second.

out3
Conf

8.2.5 OUTPUT-3 Configuration Parameters

out3 Defines output function for Output-3

HEAT Heating

COOL Cooling

Lout Logic output

out3
HEAT
OR
COOL

Con Defines control algorithm of Output-3. It is active if output function of Output-3 is heating or cooling.

onof ON/OFF control algorithm

PID PID control algorithm

Con
onof

HYS Hysteresis value for OUT-3. It can be adjusted from 0% to 50% of defined scale. (It is active if ON/OFF control is selected)

Hyn It determines operation form of hysteresis. (It is active if ON/OFF control is selected)

0000 SV + HYS/2 and SV - HYS/2

0001 SV and SV+HYS or SV and SV-HYS

tn In ON/OFF operation, this time must be passed for the output to be energised again. It can be adjusted from 0.0 to 100.0 seconds. (It is active if ON/OFF control is selected)

out3
Lout

Lout It determines logic output function of Output-3. It is active if output function of Output-3 is Lout (Logic Output)

0000 Alarm output

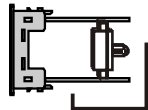
0001 Manual / Automatic data output

0002 Sensor break alarm output

0003 Output is active when the process value is out of the band which is defined with minimum value of operating scale LoL And maximum value of operating scale uPL

0004 Output indicates that Ramp/Soak function has finished

MODULE-1
or
MODULE-2



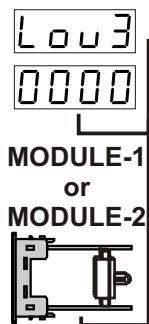
0005

Sensor break alarm output for analogue input module in Module-1 or Module-2 socket. (It is visible if one of analogue input modules is plugged in Module-1 or Module-2 socket)

EMI-410
EMI-430
EMI-440
EMI-450

0006

If process value is less than minimum value of operating scale $\underline{L o L 1}$ or $\underline{L o L 2}$ for analogue input module in Module-1 or Module-2 socket or greater than maximum value of operating scale $\underline{U P L 1}$ or $\underline{U P L 2}$ for analogue input module in Module-1 or Module-2 socket, process output becomes active. (This parameter is visible if one of the analogue input modules is plugged in Module-1 or Module-2 socket)



MODULE-1
or
MODULE-2

EMI-410
EMI-430
EMI-440
EMI-450

AL53

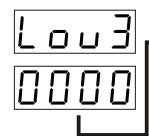
Measurement input selection for Output-3 alarm output. This parameter is visible if Logic output function of Output-3 is Alarm output and one of the analogue input modules is plugged in Module-1 or Module-2 socket

0000

Alarm output runs according to the process input.

0001

Alarm output runs according to the analogue input module (2nd sensor input) in Module-1 or Module-2 socket.



ALt3

It determines alarm type. It is active if logic output function of Output-3 is alarm output.

0000

Process high alarm

0001

Process low alarm

AL53
0000

0002

Deviation high alarm. It is active when alarm output runs according to the process input.

0003

Deviation low alarm. It is active when alarm output runs according to the process input.

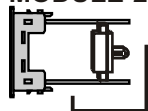
0004

Deviation band alarm. It is active when alarm output runs according to the process input.

0005

Deviation range alarm. It is active when alarm output runs according to the process input.

MODULE-1
or
MODULE-2

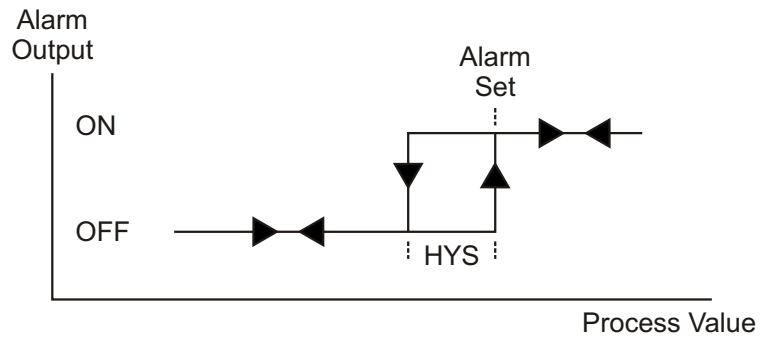


EMI-420

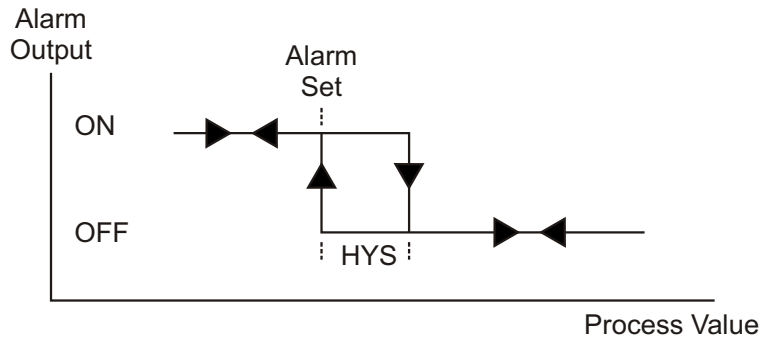
0006

Heater failure alarm. It is active if \sim CT input module is plugged in Module-1 or Module-2 socket.

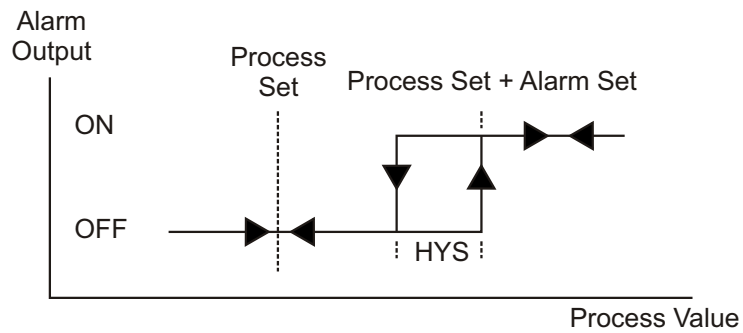
Process High Alarm



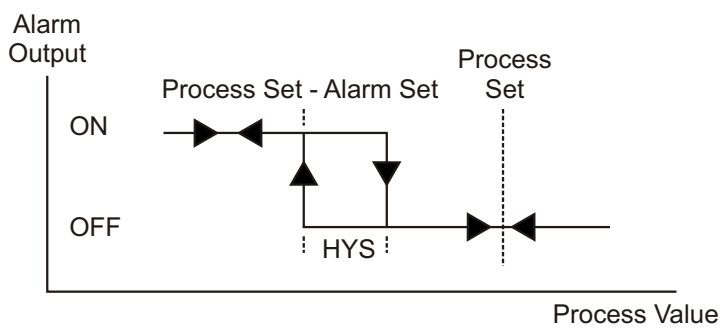
Process Low Alarm



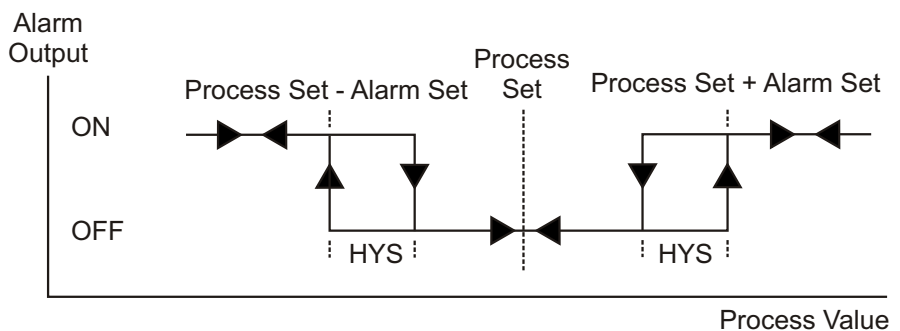
Deviation High Alarm



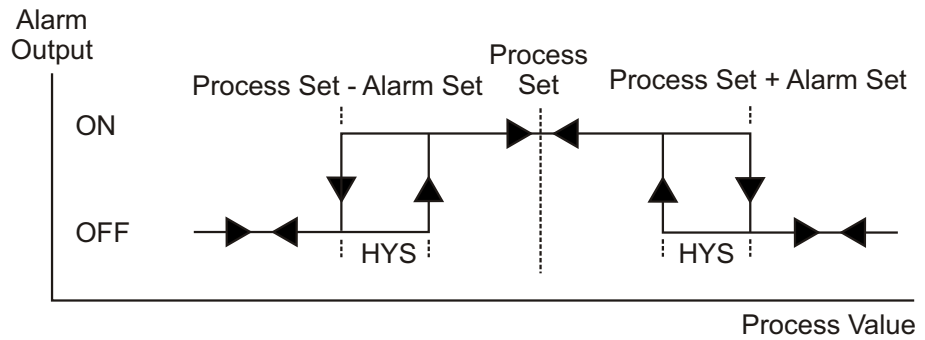
Deviation Low Alarm



Deviation Band Alarm



Deviation Range Alarm



ALH3
0000

Alarm-3 hysteresis value. It is active if logic output function of Output-3 is alarm output.

If **ALS3** is **0000** or there is no analogue input module (2nd sensor input) in Module-1 or Module-2 socket, then it can be adjusted 0% to 50% of process input scale (**uPL** - **LoL**)

If **ALS3** is **0001** and there is one of an analogue input module (2nd sensor input) in Module-1 or Module-2 socket, then it can be adjusted from 0% to 50% of analogue input module scale (**uPL2** - **LoL2**) or (**uPL1** - **LoL1**)

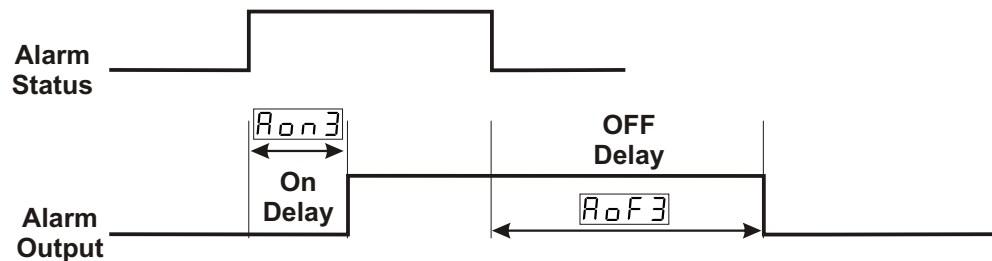
If there is \sim CT input module (EMI-420) in Module-1 or Module-2 socket and alarm type parameter **ALT3** is **0006** , then it can be adjusted from 0.0 to 20.0A \sim

Aon3

Alarm on delay time. It can be adjusted from 0000 to 9999 seconds. It is active if logic output function of Module-1 is alarm output.

Aof3

Alarm off delay time. It can be adjusted from 0000 to 9998 seconds. When the value is greater than 9998, **LECH** is seen on the display. It means alarm latching output is selected. It is active if logic output function of Output-3 is alarm output.



SU-L Minimum value for process set and alarm set values. It is named as low limit of set scale.

It can be adjusted from low limit of input selected with **,55L** parameter to **SU-U** parameter.

Please refer to Section 8.2.1 Process Input Type and Relevant Parameters with Process Input for **,55L** parameter

SU-U Maximum value for process set and alarm set values. It is named as high limit of set scale.

It can be adjusted from **SU-L** to high limit of input selected with **,55L** Parameter.

Please refer to Section 8.2.1 Process Input Type and Relevant Parameters with Process Input for **,55L** parameter

SUL2 Minimum value for set value of second sensor (analogue input module) in Module-1 or Module-2 socket. It is named as low limit of set scale for second sensor.

It can be adjusted from low limit of analogue input selected with **,5L1**

Or **,5L2** Parameter to **SUU2** parameter.

Please refer to Section 8.2.3 (Module-1 Configuration Parameters) and Section 8.2.4 (Module-2 Configuration Parameter) for **,5L1** and **,5L2** Parameters.

(This parameter is visible if one of the analogue input modules is plugged in Module-1 or Module-2 socket)

SUU2 Maximum value for set value of second sensor (analogue input module) in Module-1 or Module-2 socket. It is named as high limit of set scale for second sensor.

It can be adjusted from **SUL2** to high limit of analogue input selected with **,5L1** Parameter to **,5L2** parameter.

Please refer to Section 8.2.3 (Module-1 Configuration Parameters) and Section 8.2.4 (Module-2 Configuration Parameter) for **,5L1** and **,5L2** Parameters.

(This parameter is visible if one of the analogue input modules is plugged in Module-1 or Module-2 socket)

ULTE Motor travel time. It can be adjusted from **5 to 600** seconds.

(It is active if motorized valve control is selected)

ULHY Minimum time of motorized valve output activation. It can be adjusted from **0.1% to 5.0%**.

If **ULTE** = 100 sec and **ULHY** = 1.0% then minimum time of motorized valve output activation is $100 * 1.0\% = 1$ sec

(It is active if motorized valve control is selected)

SAdr Communication Accessing Address

Communication accessing address of device. It can be adjusted from 1 to 247.

bAud Communication Baud Rate

0000 1200 Baud Rate.

0001 2400 Baud Rate.

0002 4800 Baud Rate.

0003 9600 Baud Rate.

0004 19200 Baud Rate.

Prty Parity Selection for Communication

0000 No parity.

0001 Odd parity.

0002 Even parity.

StPb Stop Bit Selection for Communication

0000 1 stop bit

0001 2 stop bits

PASS
Conf

8.2.8 Operator and Technician Passwords

OPPS

It is used for accessing to the operator parameters.
It can be adjusted from 0 to 9999.

If it is 0000; no password protection while entering to the operator parameters.

If it is different from “0” and user wants to access to the operator parameters;

1- If user does not enter OPPS password correctly:
It turns to operation screen without accessing to parameters.

2- When OPPS in top display and 0000 in bottom display are seen, if user presses SET button without entering OPPS password (For observing the parameters):

Operator can see operator menus and parameters but operator can not change the parameters

(Please refer to Section 9. Failure Messages in ESM-4950 Process Controllers)

TEPS

It is used for accessing to the technician parameters.
It can be adjusted from 0 to 9999.

If it is 0000 ; no password protection while entering to the technician parameters.

If it is different from “0” and user wants to access to the technician parameters;

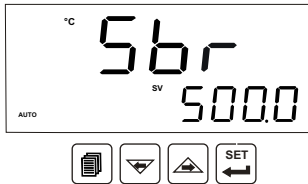
1- If user does not enter TEPS password correctly:
It turns to operation screen without accessing to parameters.

2- When TEPS in top display and 0000 in bottom display are seen, if user presses SET button without entering TEPS password (For observing the parameters):

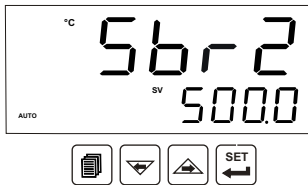
Technician can see all menus and parameters except Operator and Technician Password menu (“Pass Conf”) but technician can not change the parameters

(Please refer to Section 9. Failure Messages in ESM-4950 Process Controllers)

9. Failure Messages in ESM-4950 Process Controllers



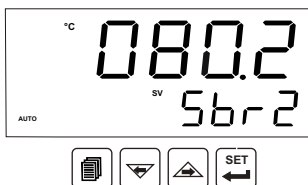
1 - Sensor failure in analogue inputs. Sensor connection is wrong or there is no sensor connection.



2 - If `EdSP` parameter in “Disp List” menu is `0002` and analogue input module is plugged in Module-1 or Module-2 socket, this is sensor failure of analogue input module. Sensor connection is wrong or there is no sensor connection.



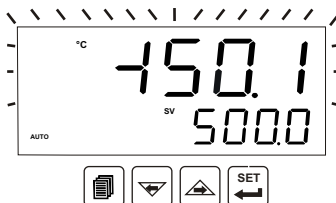
Please refer to Section 8.1.3 for detailed information about this parameter.



3 - If `EdSP` parameter is `0000` and `bdSP` parameter is `0003` and analogue input module is plugged in Module-1 or Module-2 socket, this is sensor failure of analogue input module. Sensor connection is wrong or there is no sensor connection.



Please refer to Section 8.1.3 for detailed information about this parameter.



4 - If top display blinks : If analogue input value is less than minimum value of operating scale `LoL` top display starts to blink.

In “PinP Conf” Menu if;

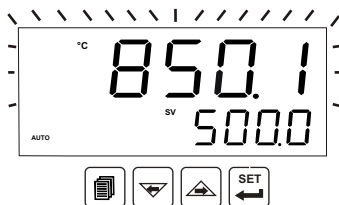
`LSL` = `0000`; `ECSL` = `0003`; `unit` = `°C` ;
`LoL` = `4999`; `uPL` = `9000` are defined.

Adjust `LoL` `4500`

If analogue input value is less than minimum value of operating scale `LoL` top display starts to blink.



Please refer to Section 8.2.1 for detailed information about this parameter.



5 - If top display blinks : If analogue input value is greater than maximum value of operating scale \boxed{uPL} , top display starts to blink.

In "PinP Conf" Menu ;

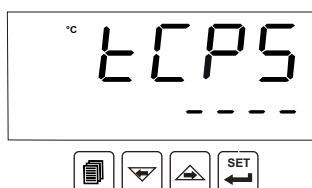
$\boxed{L5L} = \boxed{0000}$; $\boxed{EC5L} = \boxed{0003}$; $\boxed{unit} = \boxed{C}$;
 $\boxed{LoL} = \boxed{1999}$; $\boxed{uPL} = \boxed{9000}$

Adjust $\boxed{uPL} \square \boxed{8500}$

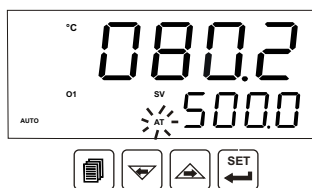
If analogue input value is greater than maximum value of operating scale \boxed{uPL} , top display starts to blink.



Please refer to Section 8.2.1 for detailed information about this parameter.



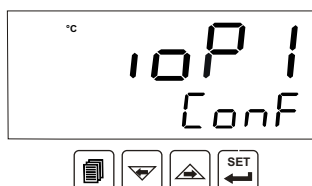
6 - If operator or technician password is different from "0" and user accesses to the parameter by Set button without entering the operator or technician password and wants to change a parameter, the warning message is shown on the bottom display as shown on the left. Device does not allow to do any changes without entering the password correctly.



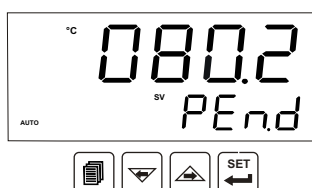
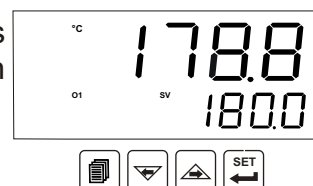
7 - If tuning operation can not be completed in 8 hours, AT led starts to blink. Blinking can be canceled by pressing Enter button.



Please refer to Section 8.1.2 for detailed information about this parameter.

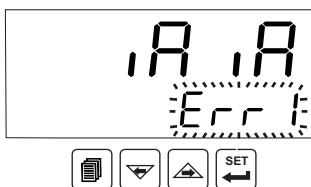


8 - If user does not do anything for 120 seconds while device is on Operator or Technician menus, device turns to operation screen.



9 - When Ramp / Soak operation finishes ;

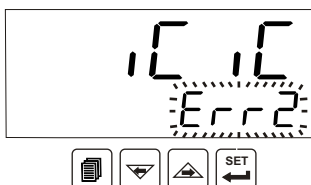
If \boxed{bdSP} parameter is $\boxed{0002}$, screen on the left is shown (Please refer to Section 8.1.3 for bdsp parameter)



10 - When power is on ; not starting the normal operation and blinking the bottom display as shown on the left;

It appears when two analogue input modules (EMI-410, EMI-430, EMI-440, EMI-450) are plugged in Module-1 and Module-2 socket at the same time.

For starting normal operation power off and pull out one of the analogue input modules.



11 - When power is on ; not starting the normal operation and blinking the bottom display as shown on the left;

It appears when two EMI-420 \sim CT input modules are plugged in Module-1 and Module-2 socket

For starting normal operation power off and pull out one of the EMI-420 \sim CT input modules.

10. Specifications

Device Type	: Process Controller
Housing&Mounting	: 96mm x 48mm x 86.5mm 1/8 DIN 43700 plastic housing for Panel mounting. Panel cut-out is 92x46mm.
Protection Class	: NEMA 4X (IP65 at front, IP20 at rear).
Weight	: Approximately 0.21 Kg.
Environmental Ratings	: Standard, indoor at an altitude of less than 2000 meters with none condensing humidity.
Storage/Operating Temperature	: -40 °C to +85 °C / 0 °C to +50 °C
Storage/Operating Humidity	: 90 % max. (None condensing)
Installation	: Fixed installation
Overvoltage Category	: II
Pollution Degree	: II, office or workplace, none conductive pollution
Operating Conditions	: Continuous
Supply Voltage and Power	: 100 - 240 V \sim (-15% / +10%) 50/60 Hz 6VA 24 V \sim (-15% / +10%) 50/60 Hz 6VA 24 V \equiv (-15% / +10%) 6W 12 V \equiv (-15% / +10%) 6W
Process Inputs	: Universal input TC, RTD, \equiv Voltage/Current
Thermocouple Input Types	: Selectable by parameters L (DIN43710) , J ,K ,R ,S ,T ,B ,E ,N (IEC584.1)(ITS90) , C (ITS90)
Thermoresistance Input Types	: PT 100 (IEC751) (ITS90)
\equivVoltage Input Types	: Selectable by parameters 0...50mV \equiv , 0...5V \equiv , 0...10V \equiv
\equivCurrent Input Types	: Selectable by parameters 0...20mA \equiv , 4...20mA \equiv
Accuracy	: \pm 0,25% of full scale for thermocouple, thermoresistance and voltage, \pm 0,70%of full scale for current.
Cold Junction Compensation	: Automatically \pm 0.1°C/1°C.
Line Compensation	: Maximum 10 Ω .
Sensor Break Protection	: Upscale
Sampling Cycle	: 3 samples per second
Input Filter	: 0.0 to 900.0 seconds
Control Forms	: Programmable ON / OFF, P, PI, PD or PID.
Standard Relay Output	: 5A@250V \sim (Programmable control or alarm output) (Electrical Life : 100.000 Operation (Full Load))
Output Modules	: -EMO-400 Relay Output Module (3A@250V \sim) -EMO-410 SSR Driver Output Module (Max20mA@18V \equiv) -EMO-420 Digital (Transistor) Output Module (Max 40mA@18V \equiv) -EMO-430 0/4...20mA \equiv Current Output Module
Input Modules	: -EMI-400 Digital Input Module -EMI-410 0/4...20mA \equiv Current Input Module -EMI-420 0...5A \sim CT Input Module -EMI-430 TC or 0...50mV Input Module -EMI-440 PT-100 Input Module -EMI-450 0...10V \equiv Input Module
Standard Communication Module	: EMC-400 RS-232 Communication Module
Optional Communication Module	: EMC-410 RS-485 Communication Module
Communication Protocol	: MODBUS-RTU
Process Display	: 13 mm Red 4 digit LED display
Set Display	: 8 mm Green 4 digit LED display
Led Indicators	: AT (Auto Tune), SV (Set value), Man (Manual Mode), Auto (Automatic Mode), O1 / 2 / 3 (Outputs) Leds, °C / °F / V unit, Ramp, Remote Leds